

# Double-spike solutions for a critical inhomogeneous elliptic problem in domains with small holes

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In this paper we construct solutions which develop two negative spikes as  $\varepsilon \rightarrow 0^+$  for the problem  $-\Delta u = |u|^{4/(N-2)}u + \varepsilon f(x)$  in  $\Omega$ ,  $u = 0$  on  $\partial\Omega$ , where  $\Omega \subset \mathbb{R}^N$  is a bounded smooth domain exhibiting a small hole, with  $f \geq 0$ ,  $f \not\equiv 0$ . This result extends a recent work of Clapp *et al.* in the sense that no symmetry assumptions on the domain are required.

## 1. Introduction

This paper deals with the construction of solutions of the problem

$$\left. \begin{aligned} -\Delta u &= |u|^{p-1}u + \varepsilon f(x) && \text{in } \Omega, \\ u &= 0 && \text{on } \partial\Omega, \end{aligned} \right\} \quad (1.1)$$

where  $\Omega$  is a bounded smooth domain in  $\mathbb{R}^N$ ,  $N \geq 3$ , which has a small hole,  $p = (N+2)/(N-2)$  is the critical Sobolev exponent,  $f(x)$  is an inhomogeneous perturbation,  $f \geq 0$ ,  $f \not\equiv 0$  and  $\varepsilon > 0$  is a small parameter.

In the case when  $1 < p < (N+2)/(N-2)$ , it is well known that if  $f = 0$ , the associated energy functional to problem (1.1) is even and satisfies the Palais–Smale (PS) condition in  $H_0^1(\Omega)$ , which implies the existence of infinitely many non-trivial solutions by standard Lyusternik–Schnirelman theory. Also known are many results on existence and multiplicity of sign-changing solutions for small and large inhomogeneous perturbations (see [2, 5, 18, 19, 23, 25]), whereas in [16] it was proved that (1.1) does not admit any positive solution if  $\varepsilon > 0$  is too large.

In the critical case,  $p = (N+2)/(N-2)$ , the embedding  $H_0^1(\Omega) \subset L^{p+1}(\Omega)$  is continuous but not compact, so that the (PS) condition does not hold, and serious difficulties in facing the existence question arise. In fact, Pohozaev [17] proved that (1.1) has no solution if  $f = 0$  and  $\Omega$  is strictly star-shaped. In contrast, Brezis and Nirenberg [7] showed that this situation can be reverted by introducing suitable additive perturbations. Rey [20] pointed out that the result in [6] implies that if  $f \geq 0$ ,  $f \not\equiv 0$  and  $f \in H^{-1}(\Omega)$ , then at least two positive solutions exist provided that  $\varepsilon > 0$  is sufficiently small. Moreover, in [20] it was proven that if  $f \geq 0$ ,  $f \not\equiv 0$ , is sufficiently regular, then at least  $\text{cat}(\Omega) + 1$  positive solutions exist for  $\varepsilon > 0$  sufficiently small, one of them converging uniformly to 0 while the others

concentrate at some special points in  $\Omega$ , depending on  $f$  and the regular part of Green's function of the Laplacian on  $\Omega$ , as  $\varepsilon \rightarrow 0$ . In parallel to Rey's result in [20], but with a different approach, Tarantello [26] proved that (1.1) admits at least two solutions for  $f \not\equiv 0$  satisfying  $\|\varepsilon f\|_{H^{-1}(\Omega)} < C_N$ , where  $C_N$  is an explicit constant; such solutions are positive if  $f \geq 0$ . The effect of the symmetries in further multiplicity of solutions has been considered in some works. Ali and Castro [1] proved that the existence result in [7] is optimal for positive solutions in a ball: if  $\Omega$  is a ball and  $f \equiv 1$ , problem (1.1) has exactly two positive solutions for all sufficiently small  $\varepsilon > 0$ . More recently, Clapp *et al.* [9] proved that if  $\Omega$  is symmetric with respect to 0,  $0 \notin \Omega$ , and  $f$  is even, then at least  $\text{cat}(\Omega) + 2$  positive solutions exist provided that  $\|\varepsilon f\|_{H^{-1}}$  is sufficiently small. The results in [1, 7, 9, 20, 26] deal with the existence of positive solutions to problem (1.1), provided that  $f \geq 0$  and  $f \neq 0$ , where  $\varepsilon > 0$  is a small parameter.

Concerning solutions which are not necessarily positive, Clapp *et al.* [10] showed the existence of solutions of (1.1) under certain symmetry assumptions in the domain  $\Omega$  and the function  $f$ . Such solutions develop  $k$  negative spikes, for any  $k \geq k_0(\Omega)$ , where  $k_0(\Omega)$  is a sufficiently large number depending on  $\Omega$ .

In this paper we leave aside any symmetry assumptions on the domain  $\Omega$  and the perturbation  $f$ , and we find solutions to problem (1.1) developing a negative double-spike shape. Additionally, we give precise information about the asymptotic profile of the blow-up of these solutions as  $\varepsilon \rightarrow 0$  and we indicate a clearly delimited region where the spikes are formed.

More precisely, our setting in problem (1.1) is as follows: let us consider the domain

$$\Omega = \mathcal{D} \setminus \overline{B(P, \mu)}, \quad (1.2)$$

where  $\mathcal{D}$  is a bounded smooth domain in  $\mathbb{R}^N$ ,  $N \geq 3$ ,  $P \in \mathcal{D}$  and  $\mu > 0$  is a small number. Let us consider  $f \in C^{0,\gamma}(\overline{\Omega})$ , for some  $0 < \gamma < 1$ , such that  $\inf_{x \in \Omega} f(x) > 0$  and, by simplicity, we fix  $P = 0$ . Then our main result is as follows.

**THEOREM 1.1.** *There exists a constant  $\mu_0 = \mu_0(f, \mathcal{D}) > 0$ , such that for each  $0 < \mu < \mu_0$  fixed, there exists a number  $\varepsilon_0 > 0$  and a family of solutions  $u_\varepsilon$  of (1.1), for  $0 < \varepsilon = \varepsilon_n < \varepsilon_0$ , with the following property:  $u_\varepsilon$  has exactly a pair of local minimum points  $(\xi_1^\varepsilon, \xi_2^\varepsilon) \in \Omega^2$  with  $k_*\mu < |\xi_i^\varepsilon| < k^*\mu$ ,  $i = 1, 2$ , for certain constants  $k_*$ ,  $k^*$  independent of  $\mu$  and such that, for each small  $\delta > 0$ ,*

$$\inf_{\{|x - \xi_i^\varepsilon| > \delta, i=1,2\}} u_\varepsilon(x) \rightarrow 0 \quad \text{and} \quad \inf_{\{|x - \xi_i^\varepsilon| < \delta\}} u_\varepsilon(x) \rightarrow -\infty, \quad i = 1, 2,$$

as  $\varepsilon \rightarrow 0$ .

Indeed, we will find that  $u_\varepsilon$  is a non-trivial solution of (1.1) of the form

$$u_\varepsilon(x) = -\alpha_N \sum_{i=1}^2 \left\{ \frac{\varepsilon^{2/(N-2)} \lambda_{i\varepsilon}}{\varepsilon^{4/(N-2)} \lambda_{i\varepsilon}^2 + |x - \xi_i^\varepsilon|^2} \right\}^{(N-2)/2} + \varepsilon^{-1} \hat{\phi}(x) + \theta_\varepsilon(x),$$

where  $\theta_\varepsilon(x) \rightarrow 0$  uniformly as  $\varepsilon \rightarrow 0$ ,  $\hat{\phi}$  is the unique solution of the problem

$$\begin{aligned} -\Delta \hat{\phi}(x) &= \varepsilon^2 f(x) & \text{in } \Omega, \\ \hat{\phi} &= 0 & \text{on } \partial\Omega, \end{aligned}$$

$\alpha_N = (N(N-2))^{(N-2)/4}$  and the points  $\xi_i^\varepsilon \rightarrow \xi_i$ , up to subsequences, where  $(\xi_1, \xi_2)$  is a critical point of the functional

$$\Phi(x, y) = \frac{1}{2} \left\{ \frac{H(x, x)w^2(y) + 2G(x, y)w(x)w(y) + H(y, y)w^2(x)}{G^2(x, y) - H(x, x)H(y, y)} \right\}$$

defined in the region  $\{(x, y) \in \Omega^2 : G(x, y) - H^{1/2}(x, x)H^{1/2}(y, y) > 0, x \neq y\}$ . Here  $G$  and  $H$  are, respectively, Green's function of the Laplacian on  $\Omega$  and its regular part, and  $w$  is the unique solution of the problem

$$\begin{aligned} -\Delta w &= f & \text{in } \Omega, \\ w &= 0 & \text{on } \partial\Omega. \end{aligned}$$

Additionally, one can identify the limits  $\lambda_i$  of  $\lambda_{i\varepsilon}$  as

$$\lambda_i = \left( a_N^{-1} \frac{H(\xi_j, \xi_j)w(\xi_i) + G(\xi_i, \xi_j)w(\xi_j)}{G^2(\xi_i, \xi_j) - H(\xi_i, \xi_i)H(\xi_j, \xi_j)} \right)^{2/(N-2)}, \quad i \neq j, \quad i, j = 1, 2,$$

where  $a_N$  is an explicit constant, and consider the constants  $k_*$ ,  $k^*$  as follows:  $k_*$  is the unique solution in  $]1, +\infty[$  of the equation

$$\frac{2^{2-N}}{s^{N-2}} = \frac{(s^2 + 1)^{N-2} + (s^2 - 1)^{N-2}}{(s^4 - 1)^{N-2}}$$

and  $K \leq k^* = k_*(\Omega, f) < \infty$ , where  $K$  is the unique solution in  $]1, +\infty[$  of the equation

$$\frac{2^{1-N}}{s^N} = \frac{(s^2 - 1)^{N-1} + (s^2 + 1)^{N-1}}{(s^4 - 1)^{N-1}}.$$

In particular, if  $f$  is a constant and  $\Omega$  is an annulus, then  $k^* = K$ .

On the other hand, it will be clear from the proof that the small excised domain does not need to be exactly a ball, and we consider this case just for notational simplicity.

The proof of theorem 1.1 follows a Lyapunov-Schmidt reduction procedure, related with this problem. This method has been used for solving problem (1.1) in the critical case (see [10, 20]) and in the slightly supercritical case with  $f = 0$  (see [12, 13], and also [21, 22] for related results).

In the next section we derive some basic estimates for the *reduced energy* associated with this problem. Sections 3 and 4 will be devoted to discussion of the finite-dimensional reduction scheme which we use for the construction of solutions of (1.1). In §5 we introduce an auxiliary function which will be the key in our min-max scheme, which we develop in §6 to finally establish theorem 1.1.

## 2. Basic estimates in the reduced energy

Let  $\Omega$  be a bounded smooth domain in  $\mathbb{R}^N$ ,  $N \geq 3$ , and let us consider the expanded domain

$$\Omega_\varepsilon = \varepsilon^{-2/(N-2)}\Omega, \quad \varepsilon > 0.$$

Using the change of variable

$$v_\varepsilon(x') = -\varepsilon u(\varepsilon^{2/(N-2)}x'), \quad x' \in \Omega_\varepsilon,$$

we note that  $u$  solves (1.1) if and only if  $v_\varepsilon$  solves

$$\left. \begin{aligned} \Delta v + |v|^{p-1}v &= \varepsilon^{p+1}\tilde{f}(x') && \text{in } \Omega_\varepsilon, \\ v &= 0 && \text{on } \partial\Omega_\varepsilon, \end{aligned} \right\} \quad (2.1)$$

where  $p = (N+2)/(N-2)$  and  $\tilde{f}(x') = f(\varepsilon^{2/(N-2)}x')$ . It is well known that all positive solutions of equation  $\Delta\vartheta + \vartheta^p = 0$  in  $\mathbb{R}^N$  are given by the functions

$$\bar{U}_{\lambda,\xi}(x) = \alpha_N \left( \frac{\lambda}{\lambda^2 + |x - \xi|^2} \right)^{(N-2)/2},$$

with  $\lambda > 0$ ,  $\xi \in \mathbb{R}^N$  and  $\alpha_N = (N(N-2))^{(N-2)/4}$  [3, 7, 8, 24]. Since  $\Omega_\varepsilon$  is expanding to the whole  $\mathbb{R}^N$  as  $\varepsilon \rightarrow 0$ , and  $\varepsilon^{p+1}\tilde{f}(x') \rightarrow 0$  uniformly as  $\varepsilon \rightarrow 0$ , it is reasonable to assume that, for certain numbers  $\lambda_1, \lambda_2 > 0$  and points  $\xi_1, \xi_2 \in \Omega$ , some solution  $v_\varepsilon$  of (2.1) becomes

$$v_\varepsilon \sim \bar{U}_{\lambda_1, \xi'_1} + \bar{U}_{\lambda_2, \xi'_2},$$

where  $\xi'_i = \varepsilon^{-2/(N-2)}\xi_i \in \Omega_\varepsilon$ , and where from now on  $\xi$  denotes a point in  $\Omega$  and  $\xi'$  denotes a point in  $\Omega_\varepsilon$ .

From [11], we know that a better approximation to  $v_\varepsilon$  should be obtained by using the orthogonal projections onto  $H_0^1(\Omega_\varepsilon)$  of the functions  $\bar{U}_{\lambda, \xi'}$ , denoted by  $U_{\lambda, \xi'}$ , namely the unique solution of the problem

$$\begin{aligned} -\Delta U_{\lambda, \xi'} &= \bar{U}_{\lambda, \xi'}^p && \text{in } \Omega_\varepsilon, \\ U_{\lambda, \xi'} &= 0 && \text{on } \partial\Omega_\varepsilon. \end{aligned}$$

In other words,  $U_{\lambda, \xi'} = \bar{U}_{\lambda, \xi'} - \bar{v}_{\lambda, \xi'}$ , where  $\bar{v}_{\lambda, \xi'}$  solves

$$\begin{aligned} -\Delta \bar{v}_{\lambda, \xi'} &= 0 && \text{in } \Omega_\varepsilon, \\ \bar{v}_{\lambda, \xi'} &= \bar{U}_{\lambda, \xi'} && \text{on } \partial\Omega_\varepsilon. \end{aligned}$$

Hence, if we consider  $\bar{U} = \bar{U}_{1,0}$ , we obtain

$$\bar{v}_{\lambda, \xi'}(x') = \varepsilon^2 \lambda^{(N-2)/2} H(\varepsilon^{2/(N-2)}x', \xi) \int_{\mathbb{R}^N} \bar{U}^p + o(\varepsilon^2) \quad (2.2)$$

and, away from  $x' = \xi'$ ,

$$U_{\lambda, \xi'}(x') = \varepsilon^2 \lambda^{(N-2)/2} G(\varepsilon^{2/(N-2)}x', \xi) \int_{\mathbb{R}^N} \bar{U}^p + o(\varepsilon^2) \quad (2.3)$$

uniformly for  $x'$  on each compact subset of  $\Omega_\varepsilon$ , where  $G$  and  $H$  are, respectively, Green's function of the Laplacian with the Dirichlet boundary condition on  $\Omega$  and its regular part. Now, to simplify notation, we consider the function

$$V(x') = U_1(x') + U_2(x'), \quad x' \in \Omega_\varepsilon,$$

where  $U_i = U_{\lambda_i, \xi'_i}$ ,  $i = 1, 2$ , and we set  $\boldsymbol{\xi} = (\xi_1, \xi_2) \in \Omega^2$  and  $\boldsymbol{\lambda} = (\lambda_1, \lambda_2) \in \mathbb{R}_+^2$ . Then, we look for solutions of problem (2.1) of the form

$$v(x') = V(x') + \tilde{\eta}(x'), \quad x' \in \Omega_\varepsilon, \quad (2.4)$$

which for suitable points  $\xi$  and scalars  $\lambda$  will have the remainder term  $\tilde{\eta}$  of small order all over  $\Omega_\varepsilon$ . Since solutions of (2.1) correspond to stationary points of its associated energy functional  $J_\varepsilon$  defined by

$$J_\varepsilon(v) = \frac{1}{2} \int_{\Omega_\varepsilon} |\nabla v|^2 - \frac{1}{p+1} \int_{\Omega_\varepsilon} |v|^{p+1} + \varepsilon^{p+1} \int_{\Omega_\varepsilon} \tilde{f}v, \quad (2.5)$$

we have that if a solution of the form (2.4) exists, then we should have  $J_\varepsilon(v) \sim J_\varepsilon(V)$  and the corresponding points  $(\boldsymbol{\xi}, \boldsymbol{\lambda})$  in the definition of  $V$  also should be ‘approximately stationary’ for the finite-dimensional functional  $(\boldsymbol{\xi}, \boldsymbol{\lambda}) \mapsto J_\varepsilon(V)$ . Thus, our first goal is to estimate  $J_\varepsilon(V)$ . In order to establish the expansion, we consider the function  $w$ , which corresponds to the unique solution in  $C^{0,\gamma}(\Omega)$  of the problem

$$\left. \begin{aligned} -\Delta w &= f && \text{in } \Omega, \\ w &= 0 && \text{on } \partial\Omega, \end{aligned} \right\} \quad (2.6)$$

and we make the following choice of the points and parameters: we fix  $\delta > 0$  and we define the parameters  $\lambda_i$  as

$$\lambda_i = (a_N^{-1} A_i)^{2/(N-2)}, \quad i = 1, 2,$$

where  $a_N = \int_{\mathbb{R}^N} \bar{U}^p$  and  $A_i \in ]\delta, \delta^{-1}[$ , for  $i = 1, 2$ . We also define the set

$$\mathcal{M}_\delta = \{(\boldsymbol{\xi}, \mathbf{A}) : |\xi_1 - \xi_2| > \delta, \text{ dist}(\xi_i, \partial\Omega) > \delta; i = 1, 2\}, \quad (2.7)$$

where  $\boldsymbol{\xi} = (\xi_1, \xi_2) \in \Omega^2$  and  $\mathbf{A} = (A_1, A_2) \in ]\delta, \delta^{-1}[$ .

LEMMA 2.1. *Let  $\delta > 0$  given. The expansion*

$$J_\varepsilon(V) = 2C_N + \varepsilon^2 \Phi(\boldsymbol{\xi}, \mathbf{A}) + o(\varepsilon^2)$$

*holds uniformly in the  $C^1$ -sense, with respect to  $(\boldsymbol{\xi}, \mathbf{A})$  in  $\mathcal{M}_\delta$ . Here*

$$C_N = \frac{1}{2} \int_{\mathbb{R}^N} |\nabla \bar{U}|^2 - \frac{1}{p+1} \int_{\mathbb{R}^N} \bar{U}^{p+1} \quad (2.8)$$

*and the function  $\Phi$  is defined by*

$$\Phi(\boldsymbol{\xi}, \mathbf{A}) = \frac{1}{2} \left\{ \sum_{i=1}^2 A_i^2 H(\xi_i, \xi_i) - 2A_1 A_2 G(\xi_1, \xi_2) \right\} + \sum_{i=1}^2 A_i w(\xi_i). \quad (2.9)$$

The proof of the previous lemma is based on (2.2), (2.3) and some estimates established in [4], and follows a similar procedure to that used to prove [13, lemma 3.2] and [10, proposition 1]; it is therefore omitted here.

### 3. The finite-dimensional reduction

We first introduce some notation to be used in what follows. For functions  $u, v$  defined in  $\Omega_\varepsilon$  we set

$$\langle u, v \rangle = \int_{\Omega_\varepsilon} uv.$$

Let us fix a small number  $\delta > 0$  and consider points  $(\xi', \mathbf{A})$  in

$$\mathcal{M}_\delta^\varepsilon = \{(\xi', \mathbf{A}) \in \Omega_\varepsilon^2 \times ]\delta, \delta^{-1}[^2: |\xi'_1 - \xi'_2| > \delta_\varepsilon, \text{dist}(\xi'_i, \partial\Omega_\varepsilon) > \delta_\varepsilon; i = 1, 2\}, \quad (3.1)$$

where  $\delta_\varepsilon = \delta\varepsilon^{-2/(N-2)}$ ,  $\xi' = (\xi'_1, \xi'_2)$  and  $\mathbf{A} = (A_1, A_2)$ . Since all solutions  $\vartheta$  of the problem  $\Delta\vartheta + p\bar{U}_{\Lambda,0}^{p-1}\vartheta = 0$  in  $\mathbb{R}^N$  which satisfy  $|\vartheta(x)| < C|x|^{2-N}$  belong to

$$\text{span} \left\{ \frac{\partial\bar{U}_{\Lambda,0}}{\partial x_j}, \frac{\partial\bar{U}_{\Lambda,0}}{\partial\Lambda} \right\}_{j=1,\dots,N+1}$$

(see [8]), it is convenient to consider, for  $i = 1, 2$ , the functions

$$\bar{Z}_{ij}(x') = \frac{\partial\bar{U}_i}{\partial\xi'_{ij}}(x'), \quad j = 1, \dots, N, \quad \bar{Z}_{i(N+1)}(x') = \frac{\partial\bar{U}_i}{\partial\Lambda_i}(x'),$$

and their respective  $H_0^1(\Omega_\varepsilon)$ -projections  $Z_{ij}$ , namely, the unique solutions of

$$\begin{aligned} \Delta Z_{ij} &= \Delta\bar{Z}_{ij} && \text{in } \Omega_\varepsilon, \\ Z_{ij} &= 0 && \text{on } \partial\Omega_\varepsilon. \end{aligned}$$

In order to simplify notation, we will define

$$V = U_1 + U_2 \quad \text{and} \quad \bar{V} = \bar{U}_1 + \bar{U}_2.$$

We start by studying a linear problem which is the basis for the reduction of (2.1): given  $h \in L^\infty(\bar{\Omega}_\varepsilon)$ , find a function  $\eta$  and constants  $c_{ij}$  such that

$$\left. \begin{aligned} \Delta\eta + p|V|^{p-1}\eta &= h + \sum_{i,j} c_{ij} U_i^{p-1} Z_{ij} && \text{in } \Omega_\varepsilon, \\ \eta &= 0 && \text{on } \partial\Omega_\varepsilon, \\ \langle \eta, U_i^{p-1} Z_{ij} \rangle &= 0 && \text{for all } i, j. \end{aligned} \right\} \quad (3.2)$$

We want to prove that this problem is uniquely solvable with uniform bounds in certain appropriate norms. In other words, we want study the linear operator  $L_\varepsilon$  associated with (3.2), namely

$$L_\varepsilon(\eta) = \Delta\eta + p|V|^{p-1}\eta, \quad (3.3)$$

under the previous orthogonality conditions. In order to achieve this goal, we introduce the following  $L^\infty$ -norms with weight. Let  $\omega_i = (1 + |x' - \xi'_i|^2)^{-(N-2)/2}$ ,  $i = 1, 2$ ; for a function  $\theta$  defined in  $\Omega_\varepsilon$ , we consider the norms

$$\|\theta\|_* = \|(\omega_1 + \omega_2)^{-\sigma}\theta(x')\|_\infty + \|(\omega_1 + \omega_2)^{-\sigma-1}\nabla\theta(x')\|_\infty,$$

where  $\sigma = \frac{1}{2}$  if  $3 \leq N \leq 6$ ,  $\sigma = 2/(N-2)$  if  $N \geq 7$  and

$$\|\theta\|_{**} = \|(\omega_1 + \omega_2)^{-\varsigma}\theta(x')\|_\infty,$$

where  $\varsigma = \frac{1}{2}p$  if  $3 \leq N \leq 6$  and  $\varsigma = 4/(N-2)$  if  $N \geq 7$ . These norms are similar to those defined in [10] for  $N \geq 7$  but, for  $3 \leq N \leq 6$ , we have modified them, something apparently necessary in this case, since  $p \geq 2$ . Now, we study the invertibility of the linear operator  $L_\varepsilon$  defined in (3.3). Hence, it is also important to understand the differentiability of  $L_\varepsilon$  in the variables  $(\xi', \mathbf{A}) \in \mathcal{M}_\delta^\varepsilon$ .

PROPOSITION 3.1. *Assume that  $(\xi', \mathbf{A}) \in \mathcal{M}_\delta^\varepsilon$ . There then exist  $\varepsilon_0 > 0$  and  $C > 0$  such that, for all  $0 < \varepsilon < \varepsilon_0$  and for all  $h \in C^\alpha(\bar{\Omega}_\varepsilon)$ , the problem (3.2) admits a unique solution  $\eta \equiv M_\varepsilon(h)$ . Moreover, the map  $(\xi', \mathbf{A}, h) \mapsto \eta \equiv M_\varepsilon(h)$  is of class  $C^1$  and satisfies*

$$\|\eta\|_* \leq C\|h\|_{**} \quad \text{and} \quad \|\nabla_{(\xi', \mathbf{A})}\eta\|_* \leq C\|h\|_{**}.$$

The proof of this proposition follows from a slight variation of the arguments in the proof of [13, propositions 4.1 and 4.2] with the necessary modifications in [14], so we omit it here. In what follows,  $C$  represents a generic positive constant that is independent of  $\varepsilon$  and of the particular points  $(\xi', \mathbf{A}) \in \mathcal{M}_\delta^\varepsilon$ .

Now, we are ready to begin the finite-dimensional reduction. We want to solve the following nonlinear problem: find a function  $\tilde{\eta}$  such that, for certain constants  $c_{ij}$ ,  $i = 1, 2$ ,  $j = 1, \dots, N + 1$ , one has

$$\left. \begin{aligned} \Delta(V + \tilde{\eta}) + |V + \tilde{\eta}|^{p-1}(V + \tilde{\eta}) - \varepsilon^{p+1}\tilde{f} &= \sum_{i,j} c_{ij}U_i^{p-1}Z_{ij} && \text{in } \Omega_\varepsilon, \\ \tilde{\eta} &= 0 && \text{on } \partial\Omega_\varepsilon, \\ \langle \tilde{\eta}, U_i^{p-1}Z_{ij} \rangle &= -\langle \phi, U_i^{p-1}Z_{ij} \rangle && \text{for all } i, j, \end{aligned} \right\} \quad (3.4)$$

where  $\phi$  solves the problem

$$\left. \begin{aligned} -\Delta\phi &= \varepsilon^{p+1}\tilde{f} && \text{in } \Omega_\varepsilon, \\ \phi &= 0 && \text{on } \partial\Omega_\varepsilon. \end{aligned} \right\} \quad (3.5)$$

Note that  $V + \tilde{\eta}$  is a solution of (2.1) if the scalars  $c_{ij}$  in (3.4) are all zero. Also, we note that the partial differential equation in (3.4) is equivalent in  $\Omega_\varepsilon$  to

$$\Delta\eta + p|V|^{p-1}\eta = -N_\varepsilon(\eta) - R_\varepsilon + \sum_{i,j} c_{ij}U_i^{p-1},$$

where  $\eta = \tilde{\eta} - \phi$ ,

$$N_\varepsilon(\eta) = |V + \eta - \phi|^{p-1}(V + \eta - \phi)_+ - |V|^{p-1}V - p|V|^{p-1}(\eta - \phi) \quad (3.6)$$

and

$$R_\varepsilon = |V|^{p-1}V - \bar{U}_1^p - \bar{U}_2^p - p|V|^{p-1}\phi. \quad (3.7)$$

A first step to solve (3.4) consists of dealing with the following nonlinear problem: find a function  $\varphi$  that, for certain constants  $c_{ij}$ ,  $i = 1, 2$ ,  $j = 1, \dots, N + 1$ , solves

$$\left. \begin{aligned} \Delta(V + \tilde{\eta}) + |V + \tilde{\eta}|^{p-1}(V + \tilde{\eta})_+ - \varepsilon^{p+1}\tilde{f} &= \sum_{i,j} c_{ij}U_i^{p-1}Z_{ij} && \text{in } \Omega_\varepsilon, \\ \varphi &= 0 && \text{on } \partial\Omega_\varepsilon, \\ \langle \varphi, U_i^{p-1}Z_{ij} \rangle &= 0 && \text{for all } i, j, \end{aligned} \right\} \quad (3.8)$$

where  $\tilde{\eta} = \psi + \varphi - \phi$ , with  $\phi$  satisfying (3.5), and the function  $\psi$  is chosen as

$$\psi = -M_\varepsilon(R_\varepsilon), \quad (3.9)$$

where  $M_\varepsilon$  is defined as in proposition 3.1 and  $R_\varepsilon$  is given by (3.7). Actually, it is easy to check that, for points  $(\boldsymbol{\xi}', \mathbf{A}) \in \mathcal{M}_\delta^\varepsilon$ , one has

$$\|\psi\|_* \leq C\varepsilon^2.$$

Now, in (3.8) we rewrite the equation of interest as

$$\Delta\varphi + p|V|^{p-1}\varphi = -N_\varepsilon(\eta) - (\Delta\psi + p|V|^{p-1}\psi + R_\varepsilon) + \sum_{i,j} c_{ij}U_i^{p-1}Z_{ij},$$

where  $\eta = \psi + \varphi$ .

LEMMA 3.2. *Assume that  $(\boldsymbol{\xi}', \mathbf{A}) \in \mathcal{M}_\delta^\varepsilon$ . There then exists  $C > 0$  such that, for all  $\varepsilon > 0$  small enough and  $\|\varphi\|_* \leq \frac{1}{4}$ , one has*

$$\|N_\varepsilon(\psi + \varphi)\|_{**} \leq \begin{cases} C(\|\varphi\|_*^2 + \varepsilon\|\varphi\|_* + \varepsilon^{p+1}) & \text{if } 3 \leq N \leq 6, \\ C(\varepsilon^{2(p-2)}\|\varphi\|_*^2 + \varepsilon^{p^2-3p+2}\|\varphi\|_*^p + \varepsilon^{p^2-p+2}) & \text{if } N \geq 7. \end{cases}$$

*Proof.* Note that  $\|\phi\|_* \leq C\varepsilon^p$  if  $3 \leq N \leq 6$ ,  $\|\phi\|_* \leq C\varepsilon^2$  if  $N \geq 7$  and  $\|\psi\|_* \leq C\varepsilon^2$ . Since  $\|\psi + \varphi\|_* \leq \|\psi\|_* + \|\varphi\|_*$ , for  $\eta = \psi + \varphi$  we have that  $\|\eta\|_* < 1$ . Also we note that

$$N_\varepsilon(\eta) = C|V + \bar{t}(\eta - \phi)|^{p-2}(\eta - \phi)^2, \quad (3.10)$$

with  $\bar{t} \in ]0, 1[$ . Hence, if  $3 \leq N \leq 6$ , then

$$|(\omega_1 + \omega_2)^{-p/2}N_\varepsilon(\eta)| \leq C(\omega_1 + \omega_2)^{(p-1)/2}\|\eta - \phi\|_*^2 \leq C\|\eta - \phi\|_*^2.$$

On the other hand, for  $N \geq 7$ , if  $|\eta| \leq \frac{1}{2}(\omega_1 + \omega_2)$ , we again use (3.10) to obtain

$$\begin{aligned} |(\omega_1 + \omega_2)^{-4/(N-2)}N_\varepsilon(\eta)| &\leq C(\omega_1 + \omega_2)^{(6-N)/(N-2)}\|\eta - \phi\|_*^2 \\ &\leq C\varepsilon^{(6-N)/(N-2)}\|\eta - \phi\|_*^2. \end{aligned}$$

In another case we obtain directly from (3.6) that

$$\begin{aligned} |(\omega_1 + \omega_2)^{-4/(N-2)}N_\varepsilon(\eta)| &\leq C|(\omega_1 + \omega_2)^{-4/(N-2)}(\eta - \phi)^p| \\ &\leq C\varepsilon^{(6-N)/(N-2)(2/(N-2))}\|\eta - \phi\|_*^p. \end{aligned}$$

The result follows on combining previous estimates.

We now deal with the following problem:

$$\left. \begin{aligned} \Delta\varphi + pV^{p-1}\varphi &= -N_\varepsilon(\eta) + \sum_{i,j} c_{ij}U_i^{p-1}Z_{ij} && \text{in } \Omega_\varepsilon, \\ \varphi &= 0 && \text{on } \partial\Omega_\varepsilon, \\ \langle \varphi, U_i^{p-1}Z_{ij} \rangle &= 0 && \text{for all } i, j, \end{aligned} \right\} \quad (3.11)$$

where  $\eta = \psi + \varphi$  and  $\psi$  is the function defined in (3.9).

PROPOSITION 3.3. *Assume that  $(\boldsymbol{\xi}', \mathbf{A}) \in \mathcal{M}_\delta^\varepsilon$ . There then exists  $C > 0$  such that, for all  $\varepsilon > 0$  small enough, there exists a unique solution  $\varphi = \varphi(\boldsymbol{\xi}', \mathbf{A})$  to problem (3.11). Moreover, the map  $(\boldsymbol{\xi}', \mathbf{A}) \mapsto \varphi(\boldsymbol{\xi}', \mathbf{A})$  is of class  $C^1$  for the  $\|\cdot\|_*$ -norm and it satisfies*

$$\|\varphi\|_* \leq C\varepsilon^2 \quad \text{and} \quad \|\nabla_{(\boldsymbol{\xi}', \mathbf{A})}\varphi\|_* \leq C\varepsilon^2.$$



*Proof.* Let us set

$$\mathcal{F}_r = \{\varphi \in H_0^1(\Omega_\varepsilon) : \|\varphi\|_* \leq r\varepsilon^2\},$$

with  $r > 0$  a constant to be fixed later. We define the map  $A_\varepsilon : \mathcal{F}_r \rightarrow H_0^1(\Omega_\varepsilon)$  as

$$A_\varepsilon(\varphi) = -M_\varepsilon(N_\varepsilon(\psi + \varphi)),$$

where  $M_\varepsilon$  is the operator defined in proposition 3.1. Since  $\psi = -M_\varepsilon(R_\varepsilon)$ , solving (3.11) is equivalent to finding a fixed point  $\varphi$  for  $A_\varepsilon$ . From proposition 3.1 and lemma 3.2, we deduce that if  $\varphi \in \mathcal{F}_r$  and  $\varepsilon > 0$  is small enough, then

$$\|A_\varepsilon(\varphi)\|_* \leq r\varepsilon^2$$

for a suitable choice of  $r = r(N)$  which we consider fixed from now on. Note that, for  $\varphi_1, \varphi_2 \in \mathcal{F}_r$ , from lemma 3.2 we have

$$\|A_\varepsilon(\varphi_1) - A_\varepsilon(\varphi_2)\|_* \leq C\|N_\varepsilon(\psi + \varphi_1) - N_\varepsilon(\psi + \varphi_2)\|_{**} \leq C\varepsilon^p\|\varphi_1 - \varphi_2\|_*,$$

for all  $N \geq 3$ . It follows that, for  $\varepsilon > 0$  small enough, the map  $A_\varepsilon$  is a contraction  $\|\cdot\|_*$  in  $\mathcal{F}_r$ . Therefore,  $A_\varepsilon$  has a fixed point in  $\mathcal{F}_r$ .

Concerning differentiability properties, let us recall that  $\eta = \psi + \varphi$  is defined by the relation

$$B(\boldsymbol{\xi}', \mathbf{A}, \eta) \equiv \eta + M_\varepsilon(N_\varepsilon(\psi + \varphi)) = 0.$$

We see that

$$D_\eta B(\boldsymbol{\xi}', \mathbf{A}, \eta)[\theta] = \theta + M_\varepsilon(\theta D_\eta N_\varepsilon(\psi + \varphi)) \equiv \theta + \tilde{M}(\theta)$$

and check that

$$\|\tilde{M}(\theta)\|_* \leq C\varepsilon\|\theta\|_*.$$

This implies that, for  $\varepsilon$  small, the linear operator  $D_\eta B(\boldsymbol{\xi}', \mathbf{A}, \eta)$  is invertible in the space of the continuous functions in  $\Omega_\varepsilon$  with bounded  $\|\cdot\|_*$ -norm, with a uniformly bounded inverse depending continuously on its parameters.

Now, let us consider the differentiability with respect to the  $\boldsymbol{\xi}'$  variable; for simplicity we write

$$\frac{\partial}{\partial \xi'_{ij}} = \partial_{\xi'_{ij}}.$$

Then

$$\begin{aligned} \partial_{\xi'_{ij}} B(\boldsymbol{\xi}', \mathbf{A}, \eta) &= \partial_{\xi'_{ij}} M_\varepsilon(N_\varepsilon(\psi + \varphi)) + M_\varepsilon(\partial_{\xi'_{ij}} N_\varepsilon(\psi + \varphi)) \\ &\quad + M_\varepsilon(D_\eta N_\varepsilon(\psi + \varphi) \partial_{\xi'_{ij}} \psi). \end{aligned}$$

It is clear that all expressions which define to  $\partial_{\xi'_{ij}} B(\boldsymbol{\xi}', \mathbf{A}, \eta)$  depend continuously on their parameters. Applying the implicit function theorem, we find that  $\varphi(\boldsymbol{\xi}', \mathbf{A})$  is a  $C^1$ -function in  $L_*^\infty$ . Additionally, we obtain

$$\partial_{\xi'_{ij}} \varphi = -(D_\eta B(\boldsymbol{\xi}', \mathbf{A}, \eta))^{-1}(\partial_{\xi'_{ij}} B(\boldsymbol{\xi}', \mathbf{A}, \eta))$$

and, using the first part of this proposition, the estimates in the previous lemmas, proposition 3.1 and the fact that  $(\boldsymbol{\xi}, \mathbf{A}) \in \mathcal{M}_\delta^\varepsilon$ , we conclude that

$$\|\partial_{\xi'_{ij}} \varphi\|_* \leq C(\|N_\varepsilon(\psi + \varphi)\|_{**} + \|\partial_{\xi'_{ij}} N_\varepsilon(\psi + \varphi)\|_{**} + \|D_\eta N_\varepsilon(\psi + \varphi) \partial_{\xi'_{ij}} \psi\|_{**}) \leq C\varepsilon^2.$$

Similarly, we can analyse the differentiability of  $B$  with respect to  $\mathbf{A}$ . This finishes the proof.

#### 4. The reduced functional

Now we are ready to solve the full problem. Let us consider  $(\boldsymbol{\xi}', \mathbf{A}) \in \mathcal{M}_\delta^\varepsilon$  with  $\mathcal{M}_\delta^\varepsilon$  defined by (3.1). All the estimates obtained below will be uniform on these points. Let  $\varphi = \varphi(\boldsymbol{\xi}', \mathbf{A})$  be the unique solution, given by proposition 3.3, of problem (3.8) with  $\tilde{\eta} = \psi + \varphi - \phi$ , where  $\varphi$  solves (3.9) and  $\phi$  solves (3.5). Note that if  $\boldsymbol{\xi} = \varepsilon^{2/(N-2)}\boldsymbol{\xi}' \in \Omega^2$  and  $\boldsymbol{\lambda} = (\lambda_1, \lambda_2) \in \mathbb{R}_+^2$  so that  $c_{ij} = 0$  for all  $i, j$ , then a solution of (1.1) is

$$u(x) = -\varepsilon^{-1}v(\varepsilon^{-2/(N-2)}x), \quad x \in \Omega,$$

where  $v = V + \psi + \varphi(\boldsymbol{\xi}', \mathbf{A}) - \phi$ . Hence,  $u$  will be a critical point of

$$I_\varepsilon(u) = \frac{1}{2} \int_\Omega |\nabla u|^2 - \frac{1}{p+1} \int_\Omega |u|^{p+1} - \varepsilon \int_\Omega f u,$$

while  $v$  will be one of  $J_\varepsilon$  given by (2.5). Then it is convenient to consider the following functions defined in  $\Omega$ :

$$\begin{aligned} \hat{U}_i(x) &= \varepsilon^{-1}U_i(\varepsilon^{-2/(N-2)}x) = U_{\lambda_i, \xi_i}(x), & \hat{\psi}(x) &= \varepsilon^{-1}\psi(\varepsilon^{-2/(N-2)}x), \\ \hat{\varphi}(\boldsymbol{\xi}, \mathbf{A})(x) &= \varepsilon^{-1}\varphi(\boldsymbol{\xi}', \mathbf{A})(\varepsilon^{-2/(N-2)}x) & \hat{\phi}(x) &= \varepsilon^{-1}\phi(\varepsilon^{-2/(N-2)}x). \end{aligned}$$

Note that  $\hat{U}_i = U_{\lambda_{i\varepsilon}, \xi_i}$ , where  $\lambda_{i\varepsilon} = (c_N \Lambda_i^2 \varepsilon)^{2/(N-2)} \in \mathbb{R}_+$  and  $\boldsymbol{\xi} = \varepsilon^{2/(N-2)}\boldsymbol{\xi}'$ , with  $(\boldsymbol{\xi}, \mathbf{A}) \in \mathcal{M}_\delta$  defined by (2.7). Now, let us set  $\hat{U} = \hat{U}_1 + \hat{U}_2$ . Consider now the functional

$$\mathcal{I}(\boldsymbol{\xi}, \mathbf{A}) \equiv I_\varepsilon(\hat{U} + \hat{\psi} + \hat{\varphi}(\boldsymbol{\xi}, \mathbf{A}) - \hat{\phi}). \quad (4.1)$$

It is easy to check that

$$\mathcal{I}(\boldsymbol{\xi}, \boldsymbol{\lambda}) = J_\varepsilon(V + \psi + \varphi(\boldsymbol{\xi}', \mathbf{A}) - \phi).$$

Then, setting  $\tilde{\eta} = \psi + \varphi(\boldsymbol{\xi}', \mathbf{A}) - \phi$ , one shows that  $DJ_\varepsilon(V + \tilde{\eta})[\vartheta] = 0$  for all  $\vartheta \in H_\varepsilon$ , where  $H_\varepsilon = \{\vartheta \in H_0^1(\Omega_\varepsilon) : \langle \vartheta, V_i^{p-1} Z_{ij} \rangle = 0 \text{ for all } i, j\}$ . Also one has

$$\frac{\partial V}{\partial \xi'_{lk}} = Z_{lk} + o(1) \quad \text{for all } l, k, \quad \frac{\partial V}{\partial \Lambda_{l(N+1)}} = Z_{l(N+1)} + o(1) \quad \text{for all } l,$$

with  $o(1) \rightarrow 0$  in the  $\|\cdot\|_*$ -norm as  $\varepsilon \rightarrow 0$ . Then from proposition 3.3 we obtain the following basic result.

**LEMMA 4.1.** *The function  $u = \hat{U} + \hat{\psi} + \hat{\varphi}(\boldsymbol{\xi}, \mathbf{A}) - \hat{\phi}$  is a solution of problem (1.1) if only if  $(\boldsymbol{\xi}, \mathbf{A})$  is a critical point of  $\mathcal{I}$ .*

Next step is then to give an asymptotic estimate for  $\mathcal{I}(\boldsymbol{\xi}, \mathbf{A})$ . Set

$$\sigma_f = \int_\Omega f(x)w(x) dx, \quad (4.2)$$

where  $w$  is the solution of (2.6). We then have the following proposition.

PROPOSITION 4.2. *The following expansion holds:*

$$\mathcal{I}(\boldsymbol{\xi}, \mathbf{A}) = 2C_N + \varepsilon^2\{\Phi(\boldsymbol{\xi}, \mathbf{A}) + \sigma_f\} + o(\varepsilon^2)\theta(\boldsymbol{\xi}, \mathbf{A}) \quad (4.3)$$

uniformly in the  $C^1$ -sense with respect to  $(\boldsymbol{\xi}, \mathbf{A}) \in \mathcal{M}_\delta$ , where  $\theta$  is a bounded uniformly function independently of  $\varepsilon > 0$ . Here  $C_N$  is the constant given by (2.8) and  $\Phi$  is the function given by (2.9).

*Proof.* The first step to achieve our goal is to prove that

$$\mathcal{I}(\boldsymbol{\xi}, \mathbf{A}) - I_\varepsilon(\hat{V} + \hat{\psi} - \hat{\phi}) = o(\varepsilon^2) \quad (4.4)$$

and

$$\nabla_{(\boldsymbol{\xi}, \mathbf{A})}(\mathcal{I}(\boldsymbol{\xi}, \mathbf{A}) - I_\varepsilon(\hat{V} + \hat{\psi} - \hat{\phi})) = o(\varepsilon^2). \quad (4.5)$$

Let us set  $\vartheta = V + \psi - \phi$  and note that

$$\begin{aligned} \mathcal{I}(\boldsymbol{\xi}, \mathbf{A}) - I_\varepsilon(\hat{V} + \hat{\psi} - \hat{\phi}) &= - \int_0^1 t \left( \int_{\Omega_\varepsilon} N_\varepsilon(\psi + \varphi)\varphi \right) dt \\ &\quad + \int_0^1 t \left( \int_{\Omega_\varepsilon} p(|V|^{p-1} - |\vartheta + t\varphi|^{p-1})\varphi^2 \right) dt. \end{aligned}$$

Now, differentiating with respect to the  $\boldsymbol{\xi}$  variable, we obtain

$$\begin{aligned} D_{\boldsymbol{\xi}}(\mathcal{I}(\boldsymbol{\xi}, \mathbf{A}) - I_\varepsilon(\hat{\vartheta})) &= -\varepsilon^{-2/(N-2)} \int_0^1 t \int_{\Omega_\varepsilon} p \nabla_{\boldsymbol{\xi}'}[|\vartheta + t\varphi|^{p-1}\varphi^2 - |V|^{p-1}\varphi^2] dt \\ &\quad - \varepsilon^{-2/(N-2)} \int_{\Omega_\varepsilon} \nabla_{\boldsymbol{\xi}'}(N_\varepsilon(\psi + \varphi)\varphi). \end{aligned}$$

Bearing in mind that  $\|N_\varepsilon(\psi + \varphi)\|_* + \|\varphi\|_* + \|\psi\|_* + \|\nabla_{\boldsymbol{\xi}'}\varphi\|_* + \|\nabla_{\boldsymbol{\xi}'_1}\psi\|_* \leq O(\varepsilon^2)$ , we see that (4.4) and (4.5) hold.

A second step is to prove that

$$I_\varepsilon(\hat{V} + \hat{\psi} - \hat{\phi}) - I_\varepsilon(\hat{V} - \hat{\phi}) = o(\varepsilon^2) \quad (4.6)$$

and

$$\nabla_{(\boldsymbol{\xi}, \mathbf{A})}(I_\varepsilon(\hat{V} + \hat{\psi} - \hat{\phi}) - I_\varepsilon(\hat{V} - \hat{\phi})) = o(\varepsilon^2). \quad (4.7)$$

Put  $\eta = V - \phi$  and, by the fundamental calculus theorem, note that

$$\begin{aligned} I_\varepsilon(\hat{\eta} + \hat{\psi}) - I_\varepsilon(\hat{\eta}) &= \int_0^1 (1-t) \left( \int_{\Omega_\varepsilon} p|\eta + t\psi|^{p-1}\psi^2 - \int_{\Omega_\varepsilon} |\nabla\psi|^2 \right) dt \\ &\quad + \int_{\Omega_\varepsilon} (|V|^p - |\eta|^p - p|V|^{p-1}\phi)\psi + \int_{\Omega_\varepsilon} R_\varepsilon\psi. \end{aligned} \quad (4.8)$$

Now, differentiating with respect to  $\xi$  variables, we obtain

$$\begin{aligned}
D_{\xi}(I_{\varepsilon}(\hat{\eta} + \hat{\psi}) - I_{\varepsilon}(\hat{\eta})) &= \varepsilon^{-2/(N-2)} \int_0^1 (1-t) \int_{\Omega_{\varepsilon}} \nabla_{\xi'}(p|\eta + t\psi|^{p-1}\psi^2 - |\nabla\psi|^2) dt \\
&\quad + \varepsilon^{-2/(N-2)} \int_{\Omega_{\varepsilon}} \nabla_{\xi'}(|V|^p - |\eta|^p - p|V|^{p-1}\phi)\psi \\
&\quad + \varepsilon^{-2/(N-2)} \int_{\Omega_{\varepsilon}} (|V|^p - |\eta|^p - p|V|^{p-1}\phi)\nabla_{\xi'}\psi \\
&\quad + \varepsilon^{-2/(N-2)} \int_{\Omega_{\varepsilon}} \nabla_{\xi'}R_{\varepsilon}\psi + \varepsilon^{-2/(N-2)} \int_{\Omega_{\varepsilon}} R_{\varepsilon}\nabla_{\xi'}\psi.
\end{aligned}$$

Since  $\|R_{\varepsilon}\|_{**} + \|\nabla_{\xi'}R_{\varepsilon}\|_{**} + \|\phi\|_{\infty} + \|\psi\|_* + \|\nabla_{\xi'}\psi\|_* \leq O(\varepsilon^2)$  and  $\|\phi\|_* \leq O(\varepsilon^p)$  if  $3 \leq N \leq 6$ ,  $\|\phi\|_* \leq O(\varepsilon^2)$  if  $N \geq 7$ , we obtain the result that (4.6) and (4.7) hold.

Finally, we need only the following two estimates to hold:

$$I_{\varepsilon}(\hat{V} - \hat{\phi}) - I_{\varepsilon}(\hat{V}) = \varepsilon^2\sigma_f + o(\varepsilon^2), \quad (4.9)$$

where  $\sigma_f$  is given by (4.2), and

$$D_{(\xi, \Lambda)}(I_{\varepsilon}(\hat{V} - \hat{\phi}) - I_{\varepsilon}(\hat{V})) = o(\varepsilon^2). \quad (4.10)$$

Now, we have

$$\begin{aligned}
I_{\varepsilon}(\hat{V} - \hat{\phi}) - I_{\varepsilon}(\hat{V}) &= \int_0^1 \left( \int_{\Omega_{\varepsilon}} |\nabla\phi|^2 - \int_{\Omega_{\varepsilon}} p|V - t\phi|^{p-1}\phi^2 \right) dt \\
&\quad + \int_{\Omega_{\varepsilon}} (\bar{U}_1^p + \bar{U}_2^p - |V - t\phi|^p)\phi. \quad (4.11)
\end{aligned}$$

Note that

$$\int_0^1 t \int_{\Omega_{\varepsilon}} |\nabla\phi|^2 dt = \int_{\Omega_{\varepsilon}} |\nabla\phi|^2 = \varepsilon^{p+1} \int_{\Omega_{\varepsilon}} \tilde{f}\phi = \varepsilon^2 \int_{\Omega} fw = \varepsilon^2\sigma_f,$$

and since  $\|\phi\|_{\infty} \leq O(\varepsilon^{p+1})$ , we have that

$$\left| \int_{\Omega_{\varepsilon}} p|V - t\phi|^{p-1}\phi^2 \right| \leq C\varepsilon^4 \int_{\Omega_{\varepsilon}} (\omega_1 + \omega_2)^{p-1} \leq o(\varepsilon^2).$$

On the other hand, it is not difficult to check that

$$\begin{aligned}
\left| \int_{\Omega_{\varepsilon}} \left( \sum_{i=1}^2 \bar{U}_i^p - |V - t\phi|^p \right) \phi \right| &= \left| \int_{\Omega_{\varepsilon}} R_{\varepsilon}\phi + \int_{\Omega_{\varepsilon}} (|V|^p - |V - t\phi|^p - p|V|^{p-1}\phi)\phi \right| \\
&\leq o(\varepsilon^2).
\end{aligned}$$

The above estimates yield (4.9). Now, from (4.11) we obtain

$$\begin{aligned}
D_{\xi}(I_{\varepsilon}(\hat{V} - \hat{\phi}) - I_{\varepsilon}(\hat{V})) &= \varepsilon^{-2/(N-2)} \int_0^1 t \int_{\Omega_{\varepsilon}} p|V - t\phi|^{p-2}\nabla_{\xi'}V\phi^2 dt \\
&\quad + \varepsilon^{-2/(N-2)} \int_{\Omega_{\varepsilon}} \nabla_{\xi'}(\bar{U}_1^p + \bar{U}_2^p - |V - t\phi|^p)\phi, \quad (4.12)
\end{aligned}$$

but since  $\|\phi\|_\infty \leq O(\varepsilon^{p+1})$ , it is easy to check that (4.10) holds. Similarly, our results hold for differentiability with respect to  $\mathbf{A}$ .

REMARK 4.3. Lemma 2.1 and the previous proposition yield

$$\nabla_{(\xi, \mathbf{A})} \mathcal{I}(\xi, \mathbf{A}) = \varepsilon^2 \nabla_{(\xi, \mathbf{A})} \Phi(\xi, \mathbf{A}) + o(\varepsilon^2) \nabla_{(\xi, \mathbf{A})} \theta(\xi, \mathbf{A}), \quad (4.13)$$

uniformly with respect to  $(\xi, \mathbf{A}) \in \mathcal{M}_\delta$ , where  $\theta$  and  $\nabla_{(\xi, \mathbf{A})} \theta$  are bounded uniformly functions, independently of all  $\varepsilon > 0$  small.

## 5. An auxiliary function on the exterior domain

In this section we consider the domain  $\Omega$  defined in (1.2) with  $P = 0$ ,  $\mu > 0$  small and fixed and we assume that  $f \in C^{0,\gamma}(\bar{\Omega})$ , for some  $0 < \gamma < 1$ , with  $\min_{x \in \Omega} f(x) = \alpha > 0$ . Let  $w$  be the unique solution in  $C^{2,\gamma}(\bar{\Omega})$  of problem (2.6). It is then easy to check that  $w_\mu(x) = \mu^{-2} w(\mu x)$  is the unique  $C^{2,\gamma}(\overline{\mu^{-1}\Omega})$  solution of the problem

$$\begin{aligned} -\Delta w_\mu &= \hat{f} \quad \text{in } \mu^{-1}\Omega, \\ w_\mu &= 0 \quad \text{on } \partial(\mu^{-1}\Omega), \end{aligned}$$

where  $\hat{f}(x) = f(\mu x)$  for  $x \in (\mu^{-1}\Omega)$ .

Now, we consider the exterior domain

$$E = \mathbb{R}^N \setminus \overline{B(0,1)}$$

and we denote by  $G_E$  and  $H_E$ , respectively, Green's function on  $E$  and its regular part. By convenience, in the set

$$\mathbf{V} = \{(x, y) \in \mathbb{R}^N \times \mathbb{R}^N : G_E(x, y) - H_E^{1/2}(x, x) H_E^{1/2}(y, y) > 0\} \cap (\mu^{-1}\Omega)$$

we define the function

$$\Phi_E(x, y) = \frac{1}{2} \left\{ \frac{H_E(x, x) w_\mu^2(y) + 2G_E(x, y) w_\mu(x) w_\mu(y) + H_E(y, y) w_\mu^2(x)}{G_E^2(x, y) - H_E(x, x) H_E(y, y)} \right\}.$$

Then, if  $x$  and  $y$  are variable vectors whose magnitudes remain constant and we differentiate  $\Phi_E$  with respect to the angle  $\theta$  formed between them, we obtain

$$\frac{\partial}{\partial \theta} \Phi_E(x, y) = F(x, y, \theta) \sin \theta$$

for  $0 < \theta < \pi$ . Since  $F(x, y, \theta) > 0$  for all  $\theta \in ]0, \pi[$ ,  $(x, y) \in \mathbf{V}$ , we have that for given magnitudes  $|x|$  and  $|y|$ ,  $\Phi_E$  maximizes its value when  $\theta = \pi$ , is to say when  $x$  and  $y$  have opposite directions. In the rest of this section we assume that this is the situation.

### 5.1. A first step to the auxiliary function: a radial case

In this subsection we consider a fixed constant  $T > 0$  and the domain

$$\Omega := \mathcal{A}_\mu = \{x \in \mathbb{R}^N : 1 < |x| < \mu^{-1}\} \quad \text{and} \quad f \equiv 1.$$

We write  $R := R(\mu, T) = \mu^{-1}T$  so that  $w_\mu \in C^{2,\gamma}(\bar{\mathcal{A}}_\mu)$  is defined by

$$w_\mu(x) := W_R(x) = \frac{1}{2N} \left\{ \frac{R^2 - 1}{R^{2-N} - 1} |x|^{2-N} - |x|^2 + R^{2-N} \frac{1 - R^N}{R^{2-N} - 1} \right\}.$$

From the maximum principle we have that  $W_R$  is strictly positive in  $\mathcal{A}_\mu$ . Additionally, it achieves its maximum value in

$$x_\mu^* \in \mathbb{R}^N \quad \text{such that } |x_\mu^*| = R_\mu^* = \left( \frac{(N-2)R^{N-2}(R^2-1)}{2(R^{N-2}-1)} \right)^{1/N}. \quad (5.1)$$

Note that  $R_\mu^* \rightarrow +\infty$  as  $\mu \rightarrow 0$ . Now we consider an unitary vector  $\mathbf{e}$  and we set  $x = s\mathbf{e}$ ,  $y = -t\mathbf{e}$  with  $s, t > 1$ . Then

$$\begin{aligned} & 2\beta_N \Phi_E(x, y) \\ &:= 2\beta_N \Phi_R(x, y) \\ &= 2\beta_N \tilde{\Phi}_R(s, t) \\ &= \left( \frac{\tilde{W}_R^2(t)}{(s^2-1)^{N-2}} + 2 \left\{ \frac{1}{(s+t)^{N-2}} - \frac{1}{(st+1)^{N-2}} \right\} \tilde{W}_R^2(s) \tilde{W}_R^2(t) + \frac{\tilde{W}_R^2(s)}{(t^2-1)^{N-2}} \right) \\ &\quad \times \left( \left( \frac{1}{(s+t)^{N-2}} - \frac{1}{(st+1)^{N-2}} \right)^2 - \frac{1}{[(s^2-1)(t^2-1)]^{N-2}} \right)^{-1}, \end{aligned}$$

where  $\tilde{W}_R(r) = W_R(r\mathbf{e})$ , for  $1 < r < R$ .

REMARK 5.1. We define in  $]1, +\infty[ \times ]1, +\infty[$  the following function:

$$\tilde{\Psi}(s, t) = \frac{1}{(s+t)^{N-2}} - \frac{1}{(st+1)^{N-2}} - \frac{1}{[(s^2-1)(t^2-1)]^{(N-2)/2}}. \quad (5.2)$$

From (5.1), it is easy to check that we can choose  $\mu_0$  small enough such that for all  $0 < \mu < \mu_0$  there exist  $1 < k_* < K < R_{\mu_0}^*$  independent of  $\mu$ , verifying  $\tilde{\Psi}(k_*, k_*) = 0$ ,  $\tilde{\Psi}(K, K) = \max_{(x,y) \in E} \tilde{\Psi}(|x|, |y|)$ . Moreover,  $k_*$  is the unique solution in  $]1, +\infty[$  of the equation

$$\frac{2^{2-N}}{s^{N-2}} = \frac{(s^2+1)^{N-2} + (s^2-1)^{N-2}}{(s^4-1)^{N-2}}$$

and  $K$  is the unique solution in  $]1, +\infty[$  of

$$\frac{2^{1-N}}{s^N} = \frac{(s^2+1)^{N-1} + (s^2-1)^{N-1}}{(s^4-1)^{N-1}}.$$

Now, it is not difficult to prove the following lemma.

LEMMA 5.2. *The function  $\tilde{\Phi}_R$  achieves only one minimum value at a critical point of the form  $(\rho_R, \rho_R) \in ]k_*, K[$ .*

## 5.2. General case

Let  $\Omega$  be the domain defined in (1.2), with  $P = 0$ . In this subsection we consider the values  $m, M$  as follows:  $m$  is the radius of the biggest ball centred at the origin contained in  $\mathcal{D}$  and  $M$  is the radius of the smallest ball centred at the origin

containing to  $\mathcal{D}$ . Let  $w$  be the unique solution  $C^{2,\gamma}(\bar{\Omega})$  of problem (2.6). By the maximum principle, we check that

$$z_m(x) \leq w(x) \leq z_M(x) \quad \text{for all } \mu < |x| < m,$$

where  $z_m(x) = \alpha\mu^2 W_{R_1}(\mu^{-1}x)$  and  $z_M(x) = \beta\mu^2 W_{R_2}(\mu^{-1}x)$ , with  $R_1 = \mu^{-1}m$  and  $R_2 = \mu^{-1}M$ . Hence,

$$\Phi_{R_1}(\mu^{-1}x, \mu^{-1}y) \leq \Phi_E(\mu^{-1}x, \mu^{-1}y) \leq \Phi_{R_2}(\mu^{-1}x, \mu^{-1}y) \quad \text{for all } \mu < |x|, |y| < m.$$

Since the function  $\tilde{\Psi}(s, s)$  defined in (5.2) is decreasing in its diagonal for values of  $s$  greater than  $K$  and goes to 0, then is not difficult to show that the system

$$\frac{\tilde{\Phi}_{R_1}(s, s)}{\tilde{\Phi}_{R_2}(K, K)} \geq 1, \quad s \geq K,$$

possesses a solution, we say  $k^*$ , when we have chosen  $\mu > 0$  sufficiently small but fixed. Indeed, if we set  $\beta = \max_{x \in \Omega} f(x)$  and  $(\alpha m^2 - \beta M^2)K^{N-2} + \beta M^2 \neq 0$ , then, in the limit for  $\mu$ , we can choose

$$k^* = \max \left\{ K, \left\{ \left( \frac{\alpha m^2 K^{N-2}}{(\alpha m^2 - \beta M^2)K^{N-2} + \beta M^2} \right)_+ \right\}^{1/(N-2)} \right\}.$$

If  $(\alpha m^2 - \beta M^2)K^{N-2} + \beta M^2 = 0$ , we change  $K$  by a value a few greater than  $K$  in the definition of  $k^*$ . Then the following lemma is obtained.

LEMMA 5.3. *The function  $\Phi_E(x, y)$  achieves a relative minimum value in a critical point  $(x_\mu, y_\mu)$  with  $x_\mu$  and  $y_\mu$  having opposite directions, and  $(|x_\mu|, |y_\mu|) \in ]k_*, k^*[$ . Moreover,  $|x_\mu|$  and  $|y_\mu|$  belong to a compact region fully contained in  $]k_*, k^*[$ , which is independent of all sufficiently small  $\mu > 0$ .*

Let

$$\mathbb{Q} = \{(x, y) \in \mathbf{V} \times \mathbf{V} : k_* < |x|, |y| < k^*\}.$$

We then define the following value:

$$c_\mu = \Phi_E(x_\mu, y_\mu) = \min_{(x,y) \in \mathbb{Q}} \Phi_E(x, y). \quad (5.3)$$

Let  $\delta_\mu > 0$  be a suitable small value such that the level set

$$\{(x, y) \in \mathbb{Q} : \Phi_E(x, y) = \delta_\mu\}$$

is a closed curve and that  $\nabla \Phi_E(x, y)$  does not vanish on it. Let us set

$$\Upsilon_\mu = \{(x, y) \in \mathbb{Q} : \Phi_E(x, y) < \delta_\mu\}. \quad (5.4)$$

Thus, on this region we have that  $\Phi_E(x, y) < \delta_\mu$  and if  $(x, y) \in \partial \Upsilon_\mu$ , then one of the following situations happens: either there is a tangential direction  $\tau$  to  $\partial \Upsilon_\mu$  such that  $\nabla \Phi_E(x, y) \cdot \tau \neq 0$ , or  $x$  and  $y$  lie in opposite directions, where  $\Phi_E(x, y) = \delta_\mu$  and  $\nabla \Phi_E(x, y) \neq 0$  points orthogonally outwards to  $\Upsilon_\mu$ . Moreover, for fixed sufficiently small  $\mu_0 > 0$ ,

$$\Upsilon_{\hat{\mu}} \subset \subset \Upsilon_\mu \subset \subset \mathbb{Q} \quad \text{for all } 0 < \hat{\mu} < \mu < \mu_0. \quad (5.5)$$

Let us now consider the exterior domain

$$E_\mu = \mathbb{R}^N \setminus \overline{B(0, \mu)},$$

and we denote by  $G_\mu$  and  $H_\mu$ , respectively, Green's function on  $E_\mu$  and its regular part. Then

$$G_\mu(x, y) = \mu^{2-N} G_E(\mu^{-1}x, \mu^{-1}y) \quad \text{and} \quad H_\mu(x, y) = \mu^{2-N} H_E(\mu^{-1}x, \mu^{-1}y).$$

In particular, if we set

$$\Sigma_\Omega^\mu = \mu\Upsilon_\mu, \tag{5.6}$$

with  $\Upsilon_\mu$  defined by (5.4), then  $\Sigma_\Omega^\mu$  corresponds precisely to the set where

$$\Phi_E(\mu^{-1}x, \mu^{-1}y) < \delta_\mu,$$

with  $\delta_\mu$  defined by (5.4). Moreover, since

$$G(x, y) = G_\mu(x, y) + O(1) \quad \text{for all } (x, y) \in \mu\mathbb{Q},$$

where the quantity  $O(1)$  is bounded independently of all small  $\mu$ , in the  $C^1$ -sense, and the same is true for the function  $H$ , we have that, in the region  $\mu\mathbb{Q}$ , the function

$$\Phi_\Omega(x, y) = \frac{1}{2} \left\{ \frac{H(x, x)w^2(y) + 2G(x, y)w(x)w(y) + H(y, y)w^2(x)}{G^2(x, y) - H(x, x)H(y, y)} \right\} \tag{5.7}$$

satisfies the following relation:

$$\Phi_\Omega(x, y) = \mu^{N+2}\Phi_E(\mu^{-1}x, \mu^{-1}y) + o(1), \tag{5.8}$$

where the quantity  $o(1)$  is bounded independently of all small numbers  $\mu > 0$  in the  $C^1$ -sense. Additionally,  $o(1) \rightarrow 0$  as  $\mu \rightarrow 0$ .

## 6. The min–max scheme and proof of the main result

In this section  $\mu > 0$  is a fixed sufficiently small number and  $\Omega$  is the domain given in (1.2) with  $P = 0$ . According to the results (4.1) and (4.13), obtained above, our problem reduces to that of finding a critical point for

$$\Phi(\boldsymbol{\xi}, \mathbf{A}) = \frac{1}{2} \left\{ \sum_{i=1}^2 A_i^2 H(\xi_i, \xi_i) - 2A_1 A_2 G(\xi_1, \xi_2) \right\} + \sum_{i=1}^2 A_i w(\xi_i), \tag{6.1}$$

where  $\boldsymbol{\xi} = (\xi_1, \xi_2) \in \Omega^2$  and  $\mathbf{A} = (A_1, A_2) \in \mathbb{R}_+^2$ . Here we consider the function  $\Phi$  defined over the class  $\Sigma_\Omega^\mu \times \mathbb{R}_+^2$ , where  $\Sigma_\Omega^\mu$  is defined by (5.6). Indeed  $\Phi$  has some singularities on this class which we can avoid by replacing the term  $G(\xi_1, \xi_2)$  in (6.1) by

$$G|_M(\xi_1, \xi_2) = \begin{cases} G(\xi_1, \xi_2) & \text{if } G(\xi_1, \xi_2) \leq M, \\ M & \text{if } G(\xi_1, \xi_2) > M, \end{cases} \tag{6.2}$$

where  $M$  is a big number. Hence, we can work with the modified functional, which, for simplicity, we still denote by  $\Phi$ .



For every  $\boldsymbol{\xi} \in \Sigma_\Omega^\mu$  we choose  $d(\boldsymbol{\xi}) = (d_1(\boldsymbol{\xi}), d_2(\boldsymbol{\xi})) \in \mathbb{R}^2$ , which is a vector defining the negative direction of the associated quadratic form with  $\Phi$ . Such a direction exists since  $G^2(x, y) - H(x, x)H(y, y) > 0$  over  $\Sigma_\Omega^\mu$ . More precisely, for fixed  $\boldsymbol{\xi}_0 \in \Sigma_\Omega^\mu$ , the function

$$\Phi(\boldsymbol{\xi}_0, \mathbf{d}) = \frac{1}{2} \left\{ \sum_{i=1}^2 d_i^2 H(\xi_{0,i}, \xi_{0,i}) - 2d_1 d_2 G(\xi_{0,1}, \xi_{0,2}) \right\} + \sum_{i=1}^2 d_i w(\xi_{0,i}),$$

regarded as a function of  $\mathbf{d} = (d_1, d_2)$  only, with  $d_1, d_2 > 0$ , has a unique critical point  $\bar{\mathbf{d}}(\boldsymbol{\xi}_0) = (\bar{d}_1(\boldsymbol{\xi}_0), \bar{d}_2(\boldsymbol{\xi}_0))$  given by

$$\bar{d}_i(\boldsymbol{\xi}_0) = \frac{H(\xi_{0,j}, \xi_{0,j})w(\xi_{0,i}) + G(\xi_{0,i}, \xi_{0,j})w(\xi_{0,j})}{G^2(\xi_{0,i}, \xi_{0,j}) - H(\xi_{0,i}, \xi_{0,i})H(\xi_{0,j}, \xi_{0,j})}, \quad i, j = 1, 2, \quad i \neq j.$$

In particular,

$$\Phi(\boldsymbol{\xi}_0, \bar{\mathbf{d}}(\boldsymbol{\xi}_0)) = \Phi_\Omega(\boldsymbol{\xi}_0), \quad (6.3)$$

where  $\Phi_\Omega$  is the function given by (5.7). Then we simply choose  $d(\boldsymbol{\xi}) = \bar{\mathbf{d}}(\boldsymbol{\xi})$ . Let  $x_\mu$  and  $y_\mu$  the points given by (5.3). From now on we consider  $\hat{\rho}_\mu = |x_\mu|$  and  $\bar{\rho}_\mu = |y_\mu|$ . Set

$$\mathbb{S} = \{(x, y) \in \mathbb{Q}^2 : (|x|, |y|) = (\mu\hat{\rho}_\mu, \mu\bar{\rho}_\mu)\}.$$

Let  $\mathcal{K}$  be the class of all continuous functions

$$\kappa : \mathbb{S} \times I_0 \times [0, 1] \rightarrow \Sigma_\Omega^\mu \times \mathbb{R}_+^2$$

such that

- (i)  $\kappa(\boldsymbol{\xi}, \sigma_0, t) = (\boldsymbol{\xi}, \sigma_0 d(\boldsymbol{\xi}))$  and  $\kappa(\boldsymbol{\xi}, \sigma_0^{-1}, t) = (\boldsymbol{\xi}, \sigma_0^{-1} d(\boldsymbol{\xi}))$  for all  $\boldsymbol{\xi} \in \mathbb{S}, t \in [0, 1]$ .
- (ii)  $\kappa(\boldsymbol{\xi}, \sigma, 0) = (\boldsymbol{\xi}, \sigma d(\boldsymbol{\xi}))$  for all  $(\boldsymbol{\xi}, \sigma) \in \mathbb{S} \times I_0$ , where  $I_0 = [\sigma_0, \sigma_0^{-1}]$  and  $\sigma_0$  is a small number to be chosen later.

Then we define the min-max value as

$$c(\Omega) = \inf_{\kappa \in \mathcal{K}} \sup_{(\boldsymbol{\xi}, \sigma) \in \mathbb{S} \times I_0} \Phi(\kappa(\boldsymbol{\xi}, \sigma, 1)). \quad (6.4)$$

In what follows we prove that  $c(\Omega)$  is a critical value of  $\Phi$ .

LEMMA 6.1. *For all sufficiently small  $\mu > 0$ , the following estimate holds:*

$$c(\Omega) \leq \mu^{N+2} c_\mu + o(1),$$

where  $o(1) \rightarrow 0$  as  $\mu \rightarrow 0$ , and  $c_\mu$  is the value defined in (5.3).

*Proof.* For all  $t \in [0, 1]$ , we consider the test path defined as  $\kappa(\boldsymbol{\xi}, \sigma, t) = (\boldsymbol{\xi}, \sigma d(\boldsymbol{\xi}))$ . Maximizing  $\Phi(\boldsymbol{\xi}, \sigma d(\boldsymbol{\xi}))$  in the variable  $\sigma$ , we note that this maximum value is attained at  $\sigma = 1$ , because of our choice of the vector  $d(\boldsymbol{\xi})$ . Hence, from (6.3), we have

$$\max_{\sigma \in I_0} \Phi(\boldsymbol{\xi}, \sigma d(\boldsymbol{\xi})) = \Phi(\boldsymbol{\xi}, d(\boldsymbol{\xi})).$$

On the other hand, by the definition of  $\mathbb{S}$ , we see that

$$\Phi_E(\mu^{-1}\xi_1, \mu^{-1}\xi_2) = c_\mu.$$

Then the conclusion is immediate from (5.8) and the definition of  $c(\Omega)$ .

In order to prove that  $c(\Omega)$  is indeed a critical point of  $\Phi$  we need an intersection lemma. The idea behind this result is the topological continuation of the set of solutions of an equation (see [15]). For every  $(\boldsymbol{\xi}, \sigma, t) \in \mathbb{S} \times I_0 \times [0, 1]$  we define

$$\kappa(\boldsymbol{\xi}, \sigma, t) = (\tilde{\xi}(\boldsymbol{\xi}, \sigma, t), \tilde{\Lambda}(\boldsymbol{\xi}, \sigma, t)) \in \Sigma_{\Omega}^{\mu} \times \mathbb{R}_+^2,$$

with  $\tilde{\xi} = (\tilde{\xi}_1, \tilde{\xi}_2)$ ,  $\tilde{\Lambda} = (\tilde{\Lambda}_1, \tilde{\Lambda}_2)$ , and we define the set

$$\mathbb{M} = \{(\boldsymbol{\xi}, \sigma) \in \mathbb{S} \times I_0 : \tilde{\Lambda}_1(\boldsymbol{\xi}, \sigma, 1) \cdot \tilde{\Lambda}_2(\boldsymbol{\xi}, \sigma, 1) = 1\}.$$

The following lemma has been proved by Del Pino *et al.* in [12, lemma 6.2]. Therefore, we omit the proof here.

LEMMA 6.2. *For every open neighbourhood  $W$  of  $\mathbb{M}$  in  $\mathbb{S} \times I_0$ , the projection  $g : W \rightarrow \mathbb{S}$  induces a monomorphism in cohomology, that is*

$$g^* : H^*(\mathbb{S}) \rightarrow H^*(W)$$

*is injective.*

PROPOSITION 6.3. *There exists a constant  $A > 0$  such that*

$$\sup_{(\boldsymbol{\xi}, \sigma) \in \mathbb{S} \times I_0} \Phi(\kappa(\boldsymbol{\xi}, \sigma, 1)) \geq -A \quad \text{for all } \kappa \in \mathcal{K}.$$

*Proof.* Note that  $\boldsymbol{\xi} \in \Sigma_{\Omega}^{\mu}$  implies that  $\xi_i \in B(0, \mu k^*) \setminus B(0, \mu k_*)$ , for  $i = 1, 2$ , with  $\hat{\rho}_{\mu}, \bar{\rho}_{\mu} \in ]k_*, k^*[$  for any  $\mu$  sufficiently small. Thus, we can find a number  $\delta_0 > 0$  such that if  $|\xi_1 - \xi_2| < \delta_0$ , then  $\xi_1 \cdot \xi_2 > 0$ . Let  $A_0 > 0$  be such that  $G(x, y) \geq A_0$  implies  $|x - y| < \delta_0$ .

We argue by contradiction. Let us assume that, for certain  $\kappa \in \mathcal{K}$ , we have

$$\Phi(\kappa(\boldsymbol{\xi}, \sigma, 1)) \leq -A_0 \quad \text{for all } (\boldsymbol{\xi}, \sigma) \in \mathbb{S} \times I_0.$$

This implies that, for all  $(\boldsymbol{\xi}, \sigma) \in \mathbb{M}$ ,  $(\tilde{\xi}, \tilde{\sigma}) = (\tilde{\xi}(\boldsymbol{\xi}, \sigma, 1), \tilde{\Lambda}(\boldsymbol{\xi}, \sigma, 1))$ , we have

$$2G(\tilde{\xi}_1, \tilde{\xi}_2) - (\tilde{\Lambda}_1^2 H(\tilde{\xi}_1, \tilde{\xi}_1) + 2\tilde{\Lambda}_1 w(\tilde{\xi}_1) + \tilde{\Lambda}_2^2 H(\tilde{\xi}_2, \tilde{\xi}_2) + 2\tilde{\Lambda}_2 w(\tilde{\xi}_2)) \geq 2A_0$$

and since  $H(\tilde{\xi}_i, \tilde{\xi}_i) > 0$  and  $w(\tilde{\xi}_i) > 0$ , we conclude that if we take a small neighbourhood  $W$  of  $\mathbb{M}$  in  $\mathbb{S} \times I_0$ , then for every  $(\boldsymbol{\xi}, \sigma) \in W$  we have

$$G(\tilde{\xi}(\boldsymbol{\xi}, \sigma, 1)) \geq A_0.$$

Hence,  $|\tilde{\xi}_1 - \tilde{\xi}_2| < \delta_0$ . Let us fix points  $\zeta_i \in \mathbb{R}^N$ ,  $i = 1, 2$ , such that  $|\zeta_1| = \hat{\rho}_{\mu}$  and  $|\zeta_2| = \bar{\rho}_{\mu}$ . Then  $\boldsymbol{\zeta} = (\zeta_1, \zeta_2) \in \mathbb{S}$ . Setting  $\kappa_1 = \kappa(\cdot, 1)$ , we see that, because of the above conclusion,  $\kappa_1(W) \subset (\Sigma_{\Omega}^{\mu} \setminus T(\boldsymbol{\zeta})) \times \mathbb{R}_+^2$ , where  $T(\boldsymbol{\zeta}) = \{(t_1 \zeta_1, t_2 \zeta_2) : t_1, t_2 \in ]k, K[ \}$ .

Consider the map  $s : \Sigma_{\Omega}^{\mu} \times \mathbb{R}_+^2 \rightarrow \mathbb{S}$  defined componentwise as

$$s(\boldsymbol{\xi}, \mathbf{A}) = \mu \left( \frac{\hat{\rho}_{\mu} \xi_1}{|\xi_1|}, \frac{\bar{\rho}_{\mu} \xi_2}{|\xi_2|} \right).$$

Then  $\kappa_0^* \circ s^* : H^*(\mathbb{S}) \rightarrow H^*(\mathbb{S} \times I_0)$ , where  $\kappa_0 = \kappa(\cdot, 0)$  is an isomorphism. By the homotopy axiom we then deduce that  $\kappa_1^* \circ s^*$  is also an isomorphism. We consider

the following commutative diagram:

$$\begin{array}{ccccc}
H^*(\mathbb{S} \times I_0) & \xleftarrow{\kappa_1^*} & H^*(\Sigma_\Omega^\mu \times \mathbb{R}_+^2) & \xleftarrow{\kappa^*} & H^*(\mathbb{S}) \\
i_1^* \downarrow & & i_2^* \downarrow & & i_3^* \downarrow \\
H^*(W) & \xleftarrow{\tilde{\kappa}_1^*} & H^*(\kappa_1(W)) & \xleftarrow{\tilde{s}^*} & H^*(\mathbb{S} \setminus \{\zeta\}),
\end{array}$$

where  $i_1, i_2$  and  $i_3$  are inclusion maps,  $\tilde{\kappa}_1 = \kappa_1|_W$  and  $\tilde{s} = s|_{\kappa_1(W)}$ . From lemma 6.2 we have that  $i_1^*$  is a monomorphism, which is a contradiction of the fact that  $H^{2N}(\mathbb{S} \setminus \{\zeta\}) = 0$ . Thus, the result follows.

In order to prove that the min–max number (6.4) is a critical value of  $\Phi$ , we need to take into consideration the fact that the domain in which  $\Phi$  is defined is not necessarily closed for the gradient flow of  $\Phi$ . The following lemma is given towards this aim.

LEMMA 6.4. *Assume that  $\mu > 0$  is a sufficiently small number. Let  $(\xi^n, \mathbf{A}^n) \in \Sigma_\Omega^\mu \times \mathbb{R}_+^2$  be a sequence such that*

$$\nabla_{\mathbf{A}} \Phi(\xi_n, \mathbf{A}_n) \rightarrow 0. \quad (6.5)$$

*Then each component of  $\mathbf{A}_n$  is bounded above and below by positive constants.*

*Proof.* Note that  $\bar{\Sigma}_\Omega^\mu \subset \subset \Omega$ . Hence,  $w(\xi_i) > 0$ ,  $i = 1, 2$ , for all  $\xi \in \bar{\Sigma}_\Omega^\mu$ . We set  $\xi_n = (\xi_{1,n}, \xi_{2,n})$  and  $\mathbf{A}_n = (A_{1,n}, A_{2,n})$ . Then (6.5) is equivalent to

$$A_{i,n} H(\xi_{i,n}, \xi_{i,n}) - A_{j,n} G(\xi_{i,n}, \xi_{j,n}) + w(\xi_{i,n}) \rightarrow 0, \quad i, j = 1, 2, \quad i \neq j.$$

It is clear that  $|\mathbf{A}_n| \rightarrow 0$  or  $A_{i,n} \rightarrow 0$  and  $A_{j,n} \rightarrow C$ , with non-zero  $C$  and with  $i \neq j$ , cannot happen. Hence, we can suppose that  $|\mathbf{A}_n| \rightarrow +\infty$ . Since  $H$  and  $G$  remain uniformly controlled ( $\mu$  is fixed), we easily see that  $A_{1,n} \rightarrow +\infty$  and  $A_{2,n} \rightarrow +\infty$ . We set  $\tilde{A}_{i,n} = A_{i,n}/|\mathbf{A}_n|$ , for  $i = 1, 2$ , and passing to a subsequence, if necessary, we may assume that this sequence it approaches a non-zero vector  $(\hat{A}_1, \hat{A}_2)$  with  $\hat{A}_i \neq 0$  for  $i = 1, 2$ . It follows that

$$\tilde{A}_{i,n} H(\xi_{i,n}, \xi_{i,n}) - \tilde{A}_{j,n} G(\xi_{1,n}, \xi_{2,n}) + \frac{w(\xi_{i,n})}{|\mathbf{A}_n|} \rightarrow 0, \quad i, j = 1, 2, \quad i \neq j.$$

For a suitable subsequence, for some  $(\bar{\xi}_1, \bar{\xi}_2) \in \bar{\Sigma}_\Omega^\mu$ , we obtain the system

$$\frac{\hat{A}_1}{\hat{A}_2} = \frac{G(\bar{\xi}_1, \bar{\xi}_2)}{H(\bar{\xi}_1, \bar{\xi}_1)} \quad \text{and} \quad \frac{\hat{A}_2}{\hat{A}_1} = \frac{G(\bar{\xi}_1, \bar{\xi}_2)}{H(\bar{\xi}_2, \bar{\xi}_2)}.$$

Hence,

$$G^2(\bar{\xi}_1, \bar{\xi}_2) - H(\bar{\xi}_1, \bar{\xi}_1)H(\bar{\xi}_2, \bar{\xi}_2) = 0,$$

which is a contradiction, since the quantity on the left-hand side in the previous equality is strictly positive when  $\mu > 0$  is chosen sufficiently small. This finishes the proof.

PROPOSITION 6.5. *Let us assume that  $\mu > 0$  is a sufficiently small number. Then the functional  $\Phi$  satisfies the (PS) condition in the region  $\Sigma_\Omega^\mu \times \mathbb{R}_+^2$  at the level  $c(\Omega)$  given in (6.4).*

*Proof.* Let us consider a sequence  $(\boldsymbol{\xi}_n, \mathbf{A}_n) \in \Sigma_\Omega^\mu \times \mathbb{R}_+^2$  such that

$$\nabla_{\mathbf{A}}\Phi(\boldsymbol{\xi}_n, \mathbf{A}_n) \rightarrow 0 \quad \text{and} \quad \nabla_{\boldsymbol{\xi}}^T\Phi(\boldsymbol{\xi}_n, \mathbf{A}_n) \rightarrow 0,$$

where  $\nabla_{\boldsymbol{\xi}}^T\Phi$  corresponds to the tangential gradient of  $\Phi$  to  $\partial\Sigma_\Omega^\mu \times \mathbb{R}_+^2$  in the case when  $\boldsymbol{\xi}_n$  approaches  $\partial\Sigma_\Omega^\mu$  or the full gradient otherwise. From the previous lemma, the components of  $\mathbf{A}_n$  are bounded above and below by positive constants, so that we may assume, passing to a subsequence if necessary, that  $(\boldsymbol{\xi}_n, \mathbf{A}_n) \rightarrow (\boldsymbol{\xi}_0, \mathbf{A}_0) \in \Sigma_\Omega^\mu \times \mathbb{R}_+^2$  and  $\Phi(\boldsymbol{\xi}_n, \mathbf{A}_n) \rightarrow c(\Omega)$ . Then

$$\nabla_{\mathbf{A}}\Phi(\boldsymbol{\xi}_0, \mathbf{A}_0) = 0.$$

Observe that if  $\boldsymbol{\xi}_0 \in \text{Int}(\Sigma_\Omega^\mu)$ , then  $\boldsymbol{\xi}_0$  is a critical point of  $\Phi$ . We assume the opposite, i.e. that  $\boldsymbol{\xi}_0 \in \partial\Sigma_\Omega^\mu$ . Then

$$\Phi_E(\mu^{-1}\xi_{0,1}, \mu^{-1}\xi_{0,2}) = \delta_\mu.$$

Firstly, we note that  $\nabla_{\mathbf{A}}\Phi(\boldsymbol{\xi}_0, \mathbf{A}_0) = 0$ . Then  $\mathbf{A}_0$  satisfies

$$A_{0,i} = \frac{H(\xi_{0,j}, \xi_{0,j})w(\xi_{0,i}) + G(\xi_{0,i}, \xi_{0,j})w(\xi_{0,j})}{G^2(\xi_{0,i}, \xi_{0,j}) - H(\xi_{0,i}, \xi_{0,i})H(\xi_{0,j}, \xi_{0,j})}, \quad i, j = 1, 2, \quad i \neq j.$$

Substituting these values in  $\Phi$ , from (6.3) we obtain

$$c(\Omega) = \Phi(\boldsymbol{\xi}_0, \mathbf{A}_0) = \Phi_\Omega(\boldsymbol{\xi}_0)$$

and from (5.8) we deduce that

$$c(\Omega) = \mu^{N+2}\Phi_E(\mu^{-1}\xi_{0,1}, \mu^{-1}\xi_{0,2}) + \theta(\boldsymbol{\xi}_0),$$

where  $\theta(\boldsymbol{\xi}_0)$  is small in the  $C^1$  sense, as  $\mu > 0$  becomes smaller. Hence,  $\nabla_{\boldsymbol{\xi}}\Phi(\boldsymbol{\xi}_0, \mathbf{A}_0) \cdot \tau \sim 0$  for any direction  $\tau$  tangential to  $\partial\Sigma_\Omega^\mu$ . Thus, from the analysis in the previous section, we have that  $\xi_{0,1}$  and  $\xi_{0,2}$  are in opposite directions;  $\Phi(\boldsymbol{\xi}_0, \mathbf{A}_0) \sim \mu^{N+2}\delta_\mu$  and  $\nabla_{\boldsymbol{\xi}}\Phi(\boldsymbol{\xi}_0, \mathbf{A}_0)$  must be away from 0. Then choosing  $\tau$  parallel to  $\nabla_{\boldsymbol{\xi}}\Phi(\boldsymbol{\xi}_0, \mathbf{A}_0)$  we obtain that  $\nabla_{\boldsymbol{\xi}}\Phi(\boldsymbol{\xi}_0, \mathbf{A}_0) \cdot \tau$  must be away from 0, which is a contradiction. Then, the point  $\boldsymbol{\xi}_0 \in \text{Int}(\Sigma_\Omega^\mu)$ , which implies that the (PS) condition holds and the results follows.

Now we are ready to complete the proof of theorem 1.1.

*Proof of theorem 1.1.* Let us consider the domain  $\Sigma_a^b = \Sigma_\Omega^\mu \times [\mathbf{a}, \mathbf{b}]^2$  with  $\mathbf{a}, \mathbf{b}$  to be chosen later. Then the functional  $\mathcal{I}$  given by (4.1) is well defined on  $\Sigma_a^b$  except on the set

$$\Delta_\rho = \{(\boldsymbol{\xi}, \mathbf{A}) \in \Sigma_a^b : |\xi_1 - \xi_2| < \rho\}.$$

From (4.3) we can extend  $\mathcal{I}$  to all  $\Sigma_a^b$  by extending  $\Phi$  as in (6.2), and keep relations (4.3) and (4.13) over  $\Sigma_a^b$ .

From proposition 6.5,  $\Phi$  satisfies the (PS) condition. There then exist constants  $\mathbf{b} > 0$ ,  $c > 0$  and  $\varrho_0 > 0$ , such that if  $0 < \varrho < \varrho_0$ , and  $(\boldsymbol{\xi}, \mathbf{A}) \in \Sigma_\Omega^\mu$  satisfying  $|\mathbf{A}| \geq \mathbf{b}$  and  $c(\Omega) - 2\varrho \leq \Phi(\boldsymbol{\xi}, \mathbf{A}) \leq c(\Omega) + 2\varrho$ , then  $|\nabla\Phi(\boldsymbol{\xi}, \mathbf{A})| \geq c$ .

We now use the min–max characterization of  $c(\Omega)$  to choose  $\kappa \in \mathcal{K}$  so that

$$c(\Omega) \leq \sup_{(\xi, \sigma) \in \mathbb{S} \times I_0} \Phi(\kappa(\xi, \sigma, 1)) \leq c(\Omega) + \varrho.$$

By making  $\mathbf{a}$  small and  $\mathbf{b}$  large if necessary, we can assume that  $\kappa(\xi, \sigma, 1) \in \Sigma_{2\mathbf{a}}^{b/2} \subset \Sigma_{\mathbf{a}}^b$  for all  $(\xi, \sigma) \in \mathbb{S} \times I_0$ .

Consider now  $\eta : \Sigma_{\mathbf{a}}^b \times [0, +\infty] \rightarrow \Sigma_{\mathbf{a}}^b$ , the solution of the equation

$$\dot{\eta} = -h(\eta)\nabla\mathcal{I}(\eta)$$

with initial condition  $\eta(\xi, \mathbf{A}, 0) = (\xi, \mathbf{A})$ . Here the function  $h$  is defined in  $\Sigma_{\mathbf{a}}^b$  so that  $h(\xi, \mathbf{A}) = 0$  for all  $(\xi, \mathbf{A})$  with  $\Phi(\xi, \mathbf{A}) \leq c(\Omega) - 2\varrho$  and  $h(\xi, \mathbf{A}) = 1$  if  $\Phi(\xi, \mathbf{A}) \geq c(\Omega) - \varrho$ , satisfying  $0 \leq h \leq 1$ .

Hence, by the choice of  $\mathbf{a}$  and  $\mathbf{b}$ , and bearing in mind (4.3) and (4.13), we have that  $\eta(\xi, \mathbf{A}, t) \in \Sigma_{\mathbf{a}}^b$  for all  $t \geq 0$ . Then the min–max value

$$C(\Omega) = \inf_{t \geq 0} \sup_{(\xi, \sigma) \in \mathbb{S} \times I_0} \mathcal{I}(\eta(\kappa(\xi, \sigma, 1), t))$$

is a critical value for  $\mathcal{I}$ . We always assume that  $\varepsilon$  is sufficiently small, in order to make the errors in (4.1) sufficiently small. Theorem 1.1 is thus proven.

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