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## On distance-preserving elimination orderings in graphs: Complexity and algorithms\*

David Coudert<sup>a</sup>, Guillaume Ducoffe<sup>b,c,\*</sup>, Nicolas Nisse<sup>a</sup>, Mauricio Soto<sup>d</sup>

<sup>a</sup> Université Côte d'Azur, Inria, CNRS, I3S, France

<sup>b</sup> ICI – National Institute for Research and Development in Informatics, Romania

<sup>c</sup> The Research Institute of the University of Bucharest ICUB, Romania

<sup>d</sup> Departamento de Ingeniería Matemàtica, Universidad de Chile, Facultad de Ciencias Físicas y Matemàticas, Chile

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## ABSTRACT

For every connected graph *G*, a subgraph *H* of *G* is *isometric* if the distance between any two vertices in *H* is the same in *H* as in *G*. A *distance-preserving elimination ordering* of *G* is a total ordering of its vertex-set *V*(*G*), denoted  $(v_1, v_2, ..., v_n)$ , such that any subgraph  $G_i = G \setminus (v_1, v_2, ..., v_i)$  with  $1 \le i < n$  is isometric. This kind of ordering has been introduced by Chepoi in his study on weakly modular graphs (Chepoi, 1998). We prove that it is NP-complete to decide whether such ordering exists for a given graph — even if it has diameter at most 2. Then, we prove on the positive side that the problem of computing a distance-preserving ordering when there exists one is fixed-parameter-tractable in the treewidth. Lastly, we describe a heuristic in order to compute a distance-preserving ordering when there exists one that we compare to an exact exponential time algorithm and to an ILP formulation for the problem.

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## 1. Introduction

*Elimination orderings* of a graph are total orderings of its vertex-set. Many interesting graph problems can be specified in terms of the existence of an elimination ordering with some given properties. These range from some practical problems in molecular biology and chemistry [8] to the analysis of graph search algorithms [14], the characterization of some graph classes [10,29], and the study of network clustering methods in social networks [26]. On the computational point of view, vertex ordering characterizations of a given graph class often lead to efficient (polynomial-time) recognition algorithms for the graphs in this class [2,6,15,21,28]. In this work we will consider one specific kind of elimination ordering that is called *distance-preserving elimination ordering* [11]. Precisely, let us remind that a subgraph *H* of a graph *G* is *isometric* if the distance between any two vertices in *H* is the same in *H* as in *G*. An elimination ordering  $(v_1, v_2, ..., v_n)$  of *G* is distance-preserving if it satisfies that each suffix  $(v_i, v_{i+1}, ..., v_n)$  with i < n induces an isometric subgraph of *G*.

Distance-preserving elimination orderings encompass several other elimination orderings studied in the literature [6,7,19,24,25,28], all of which can be computed in polynomial time when they exist. In particular, known refinements of distance-preserving elimination orderings comprise the perfect elimination orderings [28], maximum neighbourhood orderings [6], h-extremal orderings [7], semisimplicial elimination orderings [24], dismantlable orderings [25] and more generally *domination elimination orderings* [19]. The latter orderings characterize chordal graphs, dually chordal graphs,

\* Corresponding author at: ICI – National Institute for Research and Development in Informatics, Romania. *E-mail address:* guillaume.ducoffe@ici.ro (G. Ducoffe).

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homogeneously orderable graphs, cop-win graphs and a subclass of tandem-win graphs [12], respectively, and as above stated they all can be computed in polynomial-time when they exist. However the complexity of deciding whether a distance-preserving elimination ordering exists in a given graph has been left open until this paper. We aim at completing the picture and characterizing the complexity of this problem.

*Related work.* In [17] it has been proved that every graph with a distance-preserving elimination ordering has a *minimum-size cycle basis* with only triangles and quadrangles, that can be easily computed if a distance-preserving elimination ordering is part of the input. This property has been useful in the study of some tree-likeness invariants of graphs (*e.g.*, in comparing treewidth with treelength). However, the complexity of recognizing graphs with a distance-preserving elimination ordering has been left open in [17]. Prior works [9,11] have focused on the existence of distance-preserving elimination orderings in some well-structured graph classes, *i.e.*, the *weakly modular graphs*. In particular, it has been proved recently in [9] that every breadth-first search ordering of a weakly modular graph is distance-preserving, that allows to compute one such ordering in linear time for a given graph in this class.

On the positive side, above stated refinements of distance-preserving elimination orderings [6,7,19,24,25,28] can all be computed with greedy algorithms when they exist. Indeed, for all these orderings it can be tested in polynomial-time whether a given vertex can be eliminated first. As an example, any dominated vertex can be the starting vertex of some domination elimination ordering (total ordering of the vertex-set where for every suffix, the closed neighbourhood of the first vertex is dominated in the subgraph induced by the suffix). The latter implies that any partial domination elimination ordering can be extended unless the graph does not admit such a total order. A first hint that computing a distance-preserving elimination ordering can be more difficult is that it is not that simple to choose a starting vertex. For instance, consider the wheel  $W_5$  obtained from a cycle  $C_5$  of length five by adding a universal vertex. Every elimination ordering of  $W_5$  where the universal vertex is the last vertex eliminated is distance-preserving. However, if the universal vertex is eliminated first then the cycle  $C_5$  is an isometric subgraph of  $W_5$  that does not admit a distance-preserving elimination ordering. The above problem occurring with  $C_5$  also occurs with hypercubes, that can be proved using tools from discrete geometry.<sup>1</sup>

*Our contributions.* We prove on the negative side that it is NP-complete to decide whether a given graph admits a distance-preserving elimination ordering (Section 3). The latter result may look surprising since as above stated, a broad range of distance-preserving orderings with additional properties can be computed in polynomial time when they exist. Then we show that the problem remains NP-complete even for general graphs with diameter at most two (Section 3.3). Note that in a sense our result is optimal w.r.t. the diameter because complete graphs trivially admit a distance-preserving ordering. Our reduction will show how to encode a 3-SAT formula in a graph whose distance-preserving orderings are in many-to-many correspondence with the satisfying assignments for the formula. This line of work resembles to the one in [31] in order to show that it is NP-complete to recognize collapsible complexes. Our work differs from theirs in that we study orderings with very distinct properties and the "simpler" structure of graphs – w.r.t. complexes – further constrains our gadgets to mimic variables and clauses of the formula.

On a more positive side, we prove in Section 4 that the problem of computing a distance-preserving ordering when there exists one is fixed-parameter-tractable in the treewidth.

Next, we show that a meta-theorem on vertex-orderings [3] can be applied to our problem, that results in an algorithm with  $\mathcal{O}^*(2^n)$ -time and space complexity, as well as in an algorithm with  $\mathcal{O}^*(4^n)$ -time and polynomial space complexity. We also propose an Integer Linear Programming formulation which may lead to a better running time in practice. These exact algorithms are described in Section 5 as well as simple heuristic algorithms.

*Notations.* Graphs in this study are finite, simple (hence without loop nor multiple edges) and unweighted. We refer to [5,20] for standard reference books on graphs (see also [1] for a survey about metric graph theory). Let  $(v_1, v_2, \ldots, v_n)$  be an elimination ordering of a graph *G*, we say that vertex  $v_i$ ,  $1 \le i \le n$ , is the *i*th vertex to be eliminated, and that vertex  $v_i$  is eliminated before vertex  $v_j$ , denoted  $v_i \prec v_j$ , if i < j.

#### 2. Local characterization

In what follows, we will avoid considering all the distances in the graph at each time a vertex is eliminated. That is, we replace the "global" condition that  $G \setminus v$  is isometric by a "local" one implying only the neighbours of v. The following characterization will explain how to do so.

**Lemma 1.** Let G = (V, E) and  $v \in V$ , the subgraph  $G \setminus v$  is isometric if and only if every two non-adjacent neighbours of vertex v have at least two common neighbours in G (including v).

**Proof.** If  $G \setminus v$  is isometric, then let  $x, y \in N_G(v)$  be non-adjacent. Since  $d_{G \setminus v}(x, y) = d_G(x, y) = 2$ , x and y have another common neighbour than vertex v. Conversely, suppose that every two non-adjacent neighbours of vertex v have at least

<sup>&</sup>lt;sup>1</sup> More precisely, for the special case of an *n*-dimensional hypercube, the distance-preserving orderings are equivalent to the so-called "shellable orderings" as defined in [32]. In particular, if every partial distance-preserving ordering of the *n*-dimensional hypercube could be extended, then it would imply that its dual, the *n*-dimensional octahedron, is extendably shellable, that is known to be false for  $n \ge 12$  [22].

two common neighbours in *G*. In particular, every of them have at least one common neighbour in  $G \setminus v$ . Then, for every two non-adjacent  $x, y \in N_G(v)$  the subpath (x, v, y) can be substituted in any shortest-path of *G* with the subpath (x, u, y) of  $G \setminus v$ , where *u* denotes a common neighbour of *x*, *y*. This proves that  $G \setminus v$  is an isometric subgraph.  $\Box$ 

By using Lemma 1, one obtains the following characterization of distance-preserving elimination orderings. It can be seen as a reformulation of the characterization given in [11, Lemma 3.2] in terms of pseudopeakless functions.

**Corollary 2.** An elimination ordering  $\prec$  of G = (V, E) is distance-preserving if and only if for every  $u, v \in V$  at distance  $d_G(u, v) = 2$ , there is  $w \in N_G(u) \cap N_G(v)$  such that  $u \prec w$  or  $v \prec w$ .

**Proof.** Let  $(v_1, v_2, ..., v_n)$  be the elimination ordering we consider. For every  $0 \le i < n$ , define  $G_i = G \setminus \{v_1, ..., v_{i-1}\}$  (in particular  $G_0 = G$ ). On the one direction, suppose that  $\prec$  is distance-preserving. Let  $v_i, v_j \in V$  satisfy  $d_G(v_i, v_j) = 2$  with i < j. Since  $\prec$  is distance-preserving,  $G_i$  is an isometric subgraph of G. Hence, since  $v_i, v_j \in V(G_i)$  and  $d_G(v_i, v_j) = 2$ , there exists  $w \in N_G(v_i) \cap N_G(v_j)$  such that  $w \in V(G_i)$ , *i.e.*,  $v_i \prec w$ . On the other direction, suppose that  $\prec$  is not distance-preserving. Let  $i \ge 0$  be the least index such that  $G_i$  is an isometric subgraph of G but  $G_{i+1} = G_i \setminus v_i$  is not. By Lemma 1, there exist  $x, y \in N_{G_i}(v_i)$  nonadjacent such that  $N_{G_i}(x) \cap N_{G_i}(y) \cap V(G_{i+1}) = \emptyset$ . In particular, there does not exist any  $w \in N_G(x) \cap N_G(y)$  such that  $x \prec w$  or  $y \prec w$  (else,  $w \in V(G_{i+1})$ ).  $\Box$ 

Finally, it may be easier sometimes to group vertices into subsets whose vertices can be eliminated in an arbitrary way. On such occasions, we will base on the following consequence of Lemma 1.

**Corollary 3.** Let *G* be a graph,  $S \subset V(G)$  satisfy that for every  $v \in S$ , every two non-adjacent neighbours of vertex v have a common neighbour in  $G \setminus S$ . Then, for any  $S' \subseteq S$ , the subgraph  $G \setminus S'$  is isometric.

**Proof.** By contradiction, let  $S' \subseteq S$  falsify the corollary with S' being of minimum size w.r.t. this property. Let  $v \in S'$ ,  $S'' := S' \setminus v$ . The subgraph  $G \setminus S''$  is isometric by the minimality of S'. Furthermore, by the hypothesis every two non-adjacent neighbours of v have a common neighbour in  $G \setminus S$ , hence in  $G \setminus S'$  so,  $G \setminus S'$  is isometric by Lemma 1. This contradicts the fact that S' falsifies the corollary.  $\Box$ 

## 3. Hardness results

The purpose of this section is to prove the following result.

**Theorem 4.** Deciding whether a given graph G admits a distance-preserving elimination ordering is NP-complete, already if G has diameter at most two.

Note that since the all-pairs-shortest-paths in a graph can be computed in polynomial-time then it easily follows that the problem is in NP and so, we will only prove the NP-hardness. We will first prove that deciding whether a given graph G admits a distance-preserving elimination ordering is NP-hard, already if G has diameter at most five. This first part of the proof is involved and it is based on a technical reduction from 3-SAT, the standard NP-complete problem [13]. Then, we will show how to lower the diameter to two (Section 3.3).

#### 3.1. Main reduction

Given a formula  $\Phi$  with *n* variables and *m* clauses of exactly three literals each, the 3-SAT problem aims at deciding whether there exists a boolean assignment of the variables which makes the formula true. In case it does, then the formula  $\Phi$  is said satisfiable. We will construct a graph  $G_{\Phi}$  from an arbitrary formula  $\Phi$  so that there is a distance-preserving elimination ordering of  $G_{\Phi}$  if and only if  $\Phi$  is satisfiable. This will prove the NP-hardness of our problem. To achieve the result, assume w.l.o.g. that no literal and its negation can be contained in the same clause of  $\Phi$  (else, any such clause could be removed from  $\Phi$ ), and every variable appears both positively and negatively in the clauses of  $\Phi$  (else, any clause containing either this variable or its negation could also be removed from  $\Phi$ ). Let us denote by  $x_1, x_2, \ldots, x_n$  the *n* variables, and by  $C_1, C_2, \ldots, C_m$  the *m* clauses of  $\Phi$ . The graph  $G_{\Phi}$  is defined as follows.

*Variable gadget.* For every variable  $x_i$ ,  $1 \le i \le n$ , let us add in  $G_{\Phi}$  an induced quadrangle  $(x_i, y_i, \bar{x}_i, \bar{y}_i)$  (*i.e.*, a cycle with four vertices). For every  $1 \le j \le m$ , if  $x_i$  is in the *j*th clause of the formula then four more vertices  $a_{ij}$ ,  $b_{ij}$ ,  $c_{ij}$ ,  $d_{ij}$  are added and made adjacent to vertex  $x_i$ . Similarly if  $\bar{x}_i$  is in the *j*th clause of the formula then four more vertices  $a_{ij}$ ,  $b_{ij}$ ,  $c_{ij}$ ,  $d_{ij}$  are added and made adjacent to vertex  $\bar{x}_i$  (this is clearly defined because no clause contains both literals  $x_i$ ,  $\bar{x}_i$  by the hypothesis). We refer to Fig. 1 for an illustration.

To better understand the role played by the quadrangle ( $x_i$ ,  $y_i$ ,  $\bar{x}_i$ ,  $\bar{y}_i$ ) in our reduction, we make the following observation that captures well the difficulty of the problem. Indeed, every vertex in a quadrangle can be chosen as the starting vertex of a distance-preserving ordering. However, the vertex diametrically opposed cannot be chosen as the second vertex to be eliminated. We will make use of a similar trick in our reduction so as to mimic a truth table with variable gadgets, ensuring that the second vertex to be eliminated in  $x_i$ ,  $\bar{x}_i$  must be eliminated after one of each pair  $x_{i'}$ ,  $\bar{x}_{i'}$  has already been eliminated for any  $1 \le i' \le n$ .



**Fig. 1.** The three variable gadgets for the formula  $\Phi = (x_1 \lor x_2 \lor x_3) \land (\bar{x_1} \lor \bar{x_2} \lor \bar{x_3}) \land (\bar{x_1} \lor \bar{x_2} \lor x_3)$ .



**Fig. 2.** The clause tree for the formula  $\Phi = (x_1 \lor x_2 \lor x_3) \land (\bar{x_1} \lor \bar{x_2} \lor \bar{x_3}) \land (\bar{x_1} \lor \bar{x_2} \lor x_3)$ .

*Clause tree*. Second, a rooted tree of depth two with 8m + 1 vertices is added in  $G_{\phi}$ . More precisely, the tree is rooted at some newly added vertex  $r_{\phi}$  that has 2m children denoted by  $s_1, t_1, s_2, t_2, \ldots, s_m, t_m$ . Informally, for every  $1 \le j \le m$  both nodes  $s_j, t_j$  represent the *j*th clause of  $\phi$ . Moreover let  $C_j = l_p \lor l_q \lor l_r$  with p < q < r and  $l_i \in \{x_i, \bar{x}_i\}$  for every  $i \in \{p, q, r\}$ . Then, the internal node  $s_j$  has three children denoted by  $u_j(p, q), u_j(q, r)$  and  $u_j(r, p)$ , similarly the internal node  $t_j$  has three children denoted by  $u_j(p, q), u_j(q, r)$  and  $u_j(r, p)$ , similarly the internal node  $t_j$  has three children denoted by  $v_j(p, q)$ . Finally, let us describe how the clause tree is linked to the variable gadgets. Precisely, any leaf node  $u_j(p, q)$  is made adjacent to the pair of vertices  $a_{pj}, b_{qj}$ , and in the same way any leaf node  $v_j(p, q)$  is made adjacent to Fig. 2 for an illustration.

Our reduction will ensure that  $r_{\phi}$  is the unique common neighbour of  $s_j$ ,  $t_j$  in  $G_{\phi}$ . Consequently, by Corollary 2 in any distance-preserving ordering of  $G_{\phi}$  one of  $s_j$ ,  $t_j$  will need to precede vertex  $r_{\phi}$ . We will show that this implies that the *j*th clause of  $\phi$  is satisfied.

*Literal clique*. The final and most technical part of our reduction is to construct a clique of  $G_{\Phi}$  with 8*n* vertices so as to ensure that a distance-preserving ordering exists if  $\Phi$  is satisfiable. For every  $1 \le i \le n$ , the clique contains four vertices denoted by  $e_i$ ,  $f_i$ ,  $g_i$ ,  $h_i$  (related to variable  $x_i$ ). In the same way there are four vertices denoted by  $\bar{e}_i$ ,  $\bar{f}_i$ ,  $\bar{g}_i$ ,  $\bar{h}_i$  (related to the negated variable  $\bar{x}_i$ ).

This clique is connected to variable gadgets as follows. Vertex  $y_i$  (in the *i*th variable gadget) is made adjacent to each of the four vertices  $e_i$ ,  $f_i$ ,  $g_i$ ,  $h_i$ , and in the same way vertex  $\bar{y}_i$  is made adjacent to each of the four vertices  $\bar{e}_i$ ,  $\bar{f}_i$ ,  $\bar{g}_i$ ,  $\bar{h}_i$ . For every  $1 \le j \le m$  such that one of  $x_i$ ,  $\bar{x}_i$  is a literal of  $C_j$ , the four vertices  $a_{ij}$ ,  $b_{ij}$ ,  $c_{ij}$  and  $d_{ij}$  are made adjacent to each of the four vertices  $e_i$ ,  $f_i$ .



(a) Adjacency relations between vertices from the variable gadgets and those from the literal clique.



(b) Adjacency relations w.r.t. literal  $\bar{x_1}$  and clause  $C_3 = \bar{x_1} \lor \bar{x_2} \lor x_3$ .

**Fig. 3.** The literal clique, for the formula  $\Phi = (x_1 \lor x_2 \lor x_3) \land (\bar{x_1} \lor \bar{x_2} \lor \bar{x_3}) \land (\bar{x_1} \lor \bar{x_2} \lor x_3)$ .

Then, the clique is connected to the clause tree as follows. For any  $1 \le j \le m$ , let  $C_j = l_p \lor l_q \lor l_r$  with p < q < r and  $l_i \in \{x_i, \bar{x}_i\}$  for every  $i \in \{p, q, r\}$ , then:

- the three vertices u<sub>j</sub>(p, q), u<sub>j</sub>(q, r), u<sub>j</sub>(r, p) are, respectively, made adjacent to the 4-tuples of vertices: (e<sub>p</sub>, g<sub>p</sub> and e<sub>q</sub>, g<sub>q</sub>); (e<sub>q</sub>, g<sub>q</sub> and e<sub>r</sub>, g<sub>r</sub>); (e<sub>r</sub>, g<sub>r</sub> and e<sub>p</sub>, g<sub>p</sub>);
- similarly, the three vertices  $v_j(p, q)$ ,  $v_j(q, r)$ ,  $v_j(r, p)$  are, respectively, made adjacent to the 4-tuples of vertices:  $(f_p, h_p \text{ and } \bar{f}_q, \bar{h}_q)$ ;  $(f_q, h_q \text{ and } \bar{f}_r, \bar{h}_r)$ ;  $(f_r, h_r \text{ and } \bar{f}_p, \bar{h}_p)$ ;
- last, vertex  $s_j$  is made adjacent to the twelve vertices  $e_i, g_i$  and  $\bar{e}_i, \bar{g}_i$  with  $i \in \{p, q, r\}$ ; similarly, vertex  $t_j$  is made adjacent to the twelve vertices  $f_i, h_i$  and  $\bar{f}_i, \bar{h}_i$  with  $i \in \{p, q, r\}$ .

Let  $\mathcal{E} = \bigcup_{1 \le i \le n} \{e_i, \bar{e}_i\}$ ,  $\mathcal{F} = \bigcup_{1 \le i \le n} \{f_i, \bar{f}_i\}$ ,  $\mathcal{G} = \bigcup_{1 \le i \le n} \{g_i, \bar{g}_i\}$  and  $\mathcal{H} = \bigcup_{1 \le i \le n} \{h_i, \bar{h}_i\}$  partition the clique. The root vertex  $r_{\phi}$  of the clause tree is made adjacent to every vertex in  $\mathcal{G} \cup \mathcal{H}$ . We refer to Fig. 3 for a partial illustration.

The resulting graph  $G_{\phi}$  has diameter at most five. Indeed, all vertices but the  $x_i$ ,  $\bar{x_i}$  with  $1 \le i \le n$  are adjacent to the literal clique, therefore it is a 2-distance dominating clique. We will show later how to lower the diameter (Section 3.3). Note that several vertices play almost identical roles in the reduction. This redundancy is necessary in order to ensure that most pairs of vertices that are at distance two in  $G_{\phi}$  only have one common neighbour. Indeed, the latter will impose necessary conditions on an elimination ordering of  $G_{\phi}$  to be distance-preserving.

## 3.2. Proof of correctness

We are now ready to prove that it is NP-hard to decide whether a given graph *G* admits a distance-preserving elimination ordering. We divide the proof in two propositions, as follows.

#### **Proposition 5.** If $\Phi$ is satisfiable, then $G_{\Phi}$ admits a distance-preserving ordering.

**Proof.** Let us fix a boolean assignment of the variables  $x_i$  satisfying  $\Phi$ , that exists by the hypothesis. In particular, let  $\{l_i, \overline{l_i}\} = \{x_i, \overline{x_i}\}$  be such that  $l_i$  is true, let  $V_0 = \{\overline{l_i} \mid 1 \le i \le n\}$  and let  $V_1 = \{l_i \mid 1 \le i \le n\}$ . Now, consider the following partition of the vertex-set of  $G_{\Phi}$  into eleven subsets  $S_k$ , with  $1 \le k \le 11$ . Let  $G_0 := G_{\Phi}$ , and let  $G_k := G_{k-1} \setminus S_k$  for every  $1 \le k < 11$ . We will exhibit from the partition a distance-preserving ordering of  $G_{\Phi}$ . Precisely, we will prove that for every  $1 \le k \le 11$  and for any total ordering  $S'_k$  of  $S_k$ , the elimination ordering  $S'_1, S'_2, \ldots, S'_{11}$  is distance-preserving.

The partition is defined as follows:

- The variable gadgets are partitioned into five subsets  $S_1, S_2, S_7, S_8, S_9$ . Furthermore,  $S_1 = V_1 = \{l_i \mid 1 \le i \le n\}, S_8 = V_0 = \{\bar{l_i} \mid 1 \le i \le n\}, S_7 = \bigcup_{1 \le i \le n} \{y_i, \bar{y_i}\}$ . The subsets  $S_2, S_9$  contain the vertices  $a_{ij}, b_{ij}, c_{ij}, d_{ij}$  that are, respectively, adjacent to a vertex of  $V_1, V_0$ .
- The clause tree is partitioned into four subsets  $S_3$ ,  $S_4$ ,  $S_5$ ,  $S_{10}$ . Furthermore,  $S_5 = \{r_{\phi}\}$ ,  $S_4 = \{s_1, t_1, s_2, t_2, \dots, s_m, t_m\}$ . The subset  $S_3$  contains the vertices  $u_j(p, q)$ ,  $v_j(p, q)$  such that the *j*th clause is satisfied by one of  $l_p$ ,  $l_q \in V_1$ ; similarly, the subset  $S_{10}$  contains the vertices  $u_j(p, q)$ ,  $v_j(p, q)$  such that the *j*th clause is neither satisfied by  $l_p$  nor  $l_q$ .
- The literal clique is partitioned into two subsets  $S_6 = \mathcal{G} \cup \mathcal{H}$  and  $S_{11} = \mathcal{E} \cup \mathcal{F}$ .

In what follows, we will prove that for every  $1 \le k \le 11$ , the pair  $\langle G_{k-1}, S_k \rangle$  satisfies the sufficient condition of Corollary 3. The latter will prove, as claimed above, that for every  $1 \le k \le 11$  and for any total ordering  $S'_k$  of  $S_k$ , the elimination ordering  $S'_1, S'_2, \ldots, S'_{11}$  is distance-preserving.

- Let  $S_1 = V_1 = \{l_i \mid 1 \le i \le n\}$ . Let  $l_i \in S_1$ . Neighbours of  $l_i$  in  $G_0$  are  $y_i$ ,  $\bar{y}_i$  and every of  $a_{ij}$ ,  $b_{ij}$ ,  $c_{ij}$ ,  $d_{ij}$  such that  $l_i \in C_j$ . Let  $\alpha$ ,  $\beta \in N_{G_0}(l_i)$  be non-adjacent. There are four subcases.
  - if  $\{\alpha, \beta\} = \{y_i, \overline{y_i}\}$  then  $\overline{l_i}$  is a common neighbour of  $\alpha, \beta$ ;
  - if one of  $\alpha$ ,  $\beta$  is equal to  $y_i$  and the other is amongst  $a_{ij}$ ,  $b_{ij}$ ,  $c_{ij}$ ,  $d_{ij}$  for some j, then  $e_i$ ,  $f_i$  are common neighbours of  $\alpha$ ,  $\beta$ ;
  - similarly, if one of  $\alpha$ ,  $\beta$  is equal to  $\bar{y}_i$  and the other is amongst  $a_{ij}$ ,  $b_{ij}$ ,  $c_{ij}$ ,  $d_{ij}$  for some j, then  $\bar{e}_i$ ,  $\bar{f}_i$  are common neighbours of  $\alpha$ ,  $\beta$ ;
  - if  $\alpha$  is amongst  $a_{ij}$ ,  $b_{ij}$ ,  $c_{ij}$ ,  $d_{ij}$  for some j, and  $\beta$  is amongst  $a_{ij'}$ ,  $b_{ij'}$ ,  $c_{ij'}$ ,  $d_{ij'}$  for some j', then  $e_i$ ,  $f_i$  and  $\bar{e_i}$ ,  $\bar{f_i}$  are common neighbours of  $\alpha$ ,  $\beta$ .

Therefore, in all cases  $\alpha$ ,  $\beta$  have a common neighbour in  $G_1$ , and Corollary 3 applies. In other words,  $G_1 = G_{\phi} \setminus S_1$  is isometric and for every total ordering  $S'_1$  of  $S_1$ , for any prefix  $S''_1$  of  $S'_1$ ,  $G_{\phi} \setminus S''_1$  is isometric.

- Let  $S_2$  contain every  $a_{ij}$ ,  $c_{ij}$ ,  $d_{ij}$  such that clause  $C_j$  is satisfied by  $l_i$ . Let  $w \in S_2$ . There exist  $j \le m$ ,  $p < q < r \le n$  such that neighbours of w in  $G_1$  are composed of  $e_p$ ,  $f_p$ ,  $\overline{e_p}$ ,  $\overline{f_p}$  and one of  $u_j(p, q)$ ,  $u_j(r, p)$ ,  $v_j(p, q)$  or  $v_j(r, p)$ . Let  $\alpha$ ,  $\beta \in N_{G_1}(w)$  be non-adjacent. Note that w has only one neighbour in  $G_1$  that is not in the literal clique. Consequently, one of  $\alpha$ ,  $\beta$  is amongst  $u_j(p, q)$ ,  $u_j(r, p)$ ,  $v_j(p, q)$ ,  $v_j(r, p)$ . Since the latter four vertices have some neighbour in the literal clique by construction, therefore  $\alpha$ ,  $\beta$  have a common neighbour in  $G_2$  and Corollary 3 applies. In other words,  $G_2 = G_1 \setminus S_1$  is isometric and for every total ordering  $S'_2$  of  $S_2$ , for any prefix  $S''_2$  of  $S'_2$ ,  $G_1 \setminus S''_2$  is isometric.
- Let  $S_3$  contain  $u_j(p, q)$ ,  $v_j(p, q)$  for every  $j \le m$  and  $p, q \le n$  such that one of  $l_p$ ,  $l_q$  satisfies clause  $C_j$ . Let  $w \in S_3$ . There exist  $j \le m$ ,  $p, q \le n$  such that either  $w = u_j(p, q)$  or  $w = v_j(p, q)$ . Two cases thus need to be distinguished:
  - Case  $w = u_j(p, q)$ . In particular, the neighbours of w in  $G_2$  are  $s_j, e_p, g_p, \bar{e_q}, \bar{g_q}$  and at most one amongst  $a_{pj}, b_{qj}$ . Furthermore, let  $\alpha, \beta \in N_{G_2}(w)$  be non-adjacent. If  $a_{pj} \in N_{G_2}(w)$  then  $\alpha, \beta \in N_{G_2}[e_p]$ , otherwise  $\alpha, \beta \in N_{G_2}[\bar{e_q}]$ .
  - Case  $w = v_j(p, q)$ . In particular, the neighbours of w in  $G_2$  are  $t_j, f_p, h_p, \bar{f_q}, \bar{h_q}$  and at most one amongst  $c_{pj}, d_{qj}$ . Furthermore, let  $\alpha, \beta \in N_{G_2}(w)$  be non-adjacent. If  $c_{pj} \in N_{G_2}(w)$  then  $\alpha, \beta \in N_{G_2}[f_p]$ , otherwise  $\alpha, \beta \in N_{G_2}[f_q]$ .

In both cases, any two non-adjacent neighbours  $\alpha$ ,  $\beta$  of w have a common neighbour in  $G_3$  and so, Corollary 3 applies. In other words,  $G_3 = G_2 \setminus S_3$  is isometric and for every total ordering  $S'_3$  of  $S_3$ , for any prefix  $S''_3$  of  $S'_3$ ,  $G_2 \setminus S''_3$  is isometric. • Let  $S_4 = \{s_1, t_1, s_2, t_2, \ldots, s_m, t_m\}$  be the vertices representing each clause. Let  $w \in S_4$ . Clearly, there exists  $j \leq m$  such that either  $w = s_j$  or  $w = t_j$ . Furthermore, by the choice of a boolean assignment satisfying  $\Phi$ , there exists  $l_p \in S_1$  satisfying  $C_j$ . Up to cyclic permutation of the indices for the variables, this implies by construction  $u_i(p, q), u_i(r, p), v_i(p, q), v_i(r, p) \in S_3$  for some q, r > p. Two cases need to be distinguished.

- Case  $w = s_j$ . In particular, the neighbours of w in  $G_3$  are  $r_{\Phi}$ , the twelve vertices  $e_i, g_i, \bar{e}_i, \bar{g}_i$  with  $i \in \{p, q, r\}$ , and possibly  $u_j(q, r)$ . Recall that  $r_{\Phi}$  is adjacent to all the vertices of  $\mathcal{G} \cup \mathcal{H}$ , furthermore  $u_j(q, r)$  is adjacent to  $e_q, g_q$  and  $\bar{e}_r, \bar{g}_r$ . Therefore,  $N_{G_3}(w) \subseteq N[g_q] \cap N[\bar{g}_r]$ . In this situation for any two non-adjacent neighbours  $\alpha, \beta$  of w in  $G_3$  we have  $\alpha, \beta \in N_{G_3}[g_q]$  (resp.,  $\alpha, \beta \in N_{G_3}[\bar{g}_r]$ ).

Let us point out that in the full graph *G*, the two vertices  $u_j(p, q)$  and  $u_j(r, p)$  are also neighbours of  $w = s_j$ in *G*. Furthermore, by construction *w* is the unique common neighbour of  $u_j(p, q)$  and  $u_j(r, p)$  in *G*. Hence, it is crucial that since  $\Phi$  is satisfiable, and so,  $C_j$  is satisfied by some literal  $l_p$ , the two vertices  $u_j(p, q)$  and  $u_j(r, p)$  are eliminated in  $S_3$ . - Case  $w = t_j$ . In particular, the neighbours of w in  $G_3$  are  $r_{\phi}$ , the twelve vertices  $f_i$ ,  $h_i$ ,  $\bar{f}_i$ ,  $\bar{h}_i$  with  $i \in \{p, q, r\}$ , and possibly  $v_j(q, r)$ . Recall that  $r_{\phi}$  is adjacent to all the vertices of  $\mathcal{G} \cup \mathcal{H}$ , furthermore  $v_j(q, r)$  is adjacent to  $f_q$ ,  $h_q$  and  $\bar{f}_r$ ,  $\bar{h}_r$ . Therefore,  $N_{G_3}(w) \subseteq N[h_q] \cap N[\bar{h}_r]$ . In this situation for any two non-adjacent neighbours  $\alpha$ ,  $\beta$  of w in  $G_3$  we have  $\alpha$ ,  $\beta \in N_{G_3}[h_q]$  (resp.,  $\alpha$ ,  $\beta \in N_{G_3}[\bar{h}_r]$ ).

As before, let us point out that in the full graph G, the two vertices  $v_j(p, q)$  and  $v_j(r, p)$  are also neighbours of  $w = t_j$  in G. Furthermore, by construction w is the unique common neighbour of  $v_j(p, q)$  and  $v_j(r, p)$  in G. Hence, it is crucial that since  $\Phi$  is satisfiable, and so,  $C_j$  is satisfied by some literal  $l_p$ , the two vertices  $v_j(p, q)$  and  $v_j(r, p)$  are eliminated in  $S_3$ .

In both cases, any two non-adjacent neighbours  $\alpha$ ,  $\beta$  of w have a common neighbour in  $G_4$ . By Corollary 3,  $G_4 = G_3 \setminus S_4$  is isometric and for every total ordering  $S'_4$  of  $S_4$ , for any prefix  $S''_4$  of  $S'_4$ ,  $G_3 \setminus S''_4$  is isometric.

- Let  $S_5 = \{r_{\phi}\}$ . By construction the neighbourhood of  $r_{\phi}$  in the full graph *G* is equal to  $S_4 \cup \mathcal{G} \cup \mathcal{H}$ . Note that for every  $j \leq m, r_{\phi}$  is the unique common neighbour of  $s_j$  and  $t_j$  in *G*, hence  $G \setminus r_{\phi}$  is not isometric. However, since all vertices in  $S_4$  have been eliminated at this step,  $r_{\phi}$  is simplicial in  $G_4$ , *i.e.*, its neighbourhood  $N_{G_4}(r_{\phi}) = \mathcal{G} \cup \mathcal{H}$  induces a complete subgraph. It is thus straightforward that Corollary 3 applies. In other words,  $G_5 = G_4 \setminus r_{\phi}$  is isometric.
- Let  $S_6 = \mathcal{G} \cup \mathcal{H}$ . Let  $w \in S_6$ . There are four cases to be considered.
  - If  $w = g_i$  for some *i*, then neighbours of  $g_i$  in  $G_5$  are those in the literal clique, vertex  $y_i$  and every  $u_j(i, q) \notin S_3$ . Therefore,  $N_{G_5}[w] \subseteq N_{G_5}[e_i]$ ;
  - if  $w = \bar{g}_i$  for some *i*, then neighbours of  $\bar{g}_i$  in  $G_5$  are those in the literal clique, vertex  $\bar{y}_i$  and every  $u_j(p, i) \notin S_3$ . Therefore,  $N_{G_5}[w] \subseteq N_{G_5}[\bar{e}_i]$ ;
  - if  $w = h_i$  for some *i*, then neighbours of  $h_i$  in  $G_5$  are those in the literal clique, vertex  $y_i$  and every  $v_j(i, q) \notin S_3$ . Therefore,  $N_{G_5}[w] \subseteq N_{G_5}[f_i]$ ;
  - else,  $w = \bar{h_i}$  for some *i*, hence neighbours of  $\bar{h_i}$  in  $G_5$  are those in the literal clique, vertex  $\bar{y_i}$  and every  $v_j(p, i) \notin S_3$ . Therefore,  $N_{G_5}[w] \subseteq N_{G_5}[\bar{f_i}]$ .

Since,  $e_i, \bar{e}_i, f_i, \bar{f}_i \in V(G_6)$ , therefore Corollary 3 applies. In other words,  $G_6 = G_5 \setminus S_6$  is isometric and for every total ordering  $S'_6$  of  $S_6$ , for any prefix  $S''_6$  of  $S'_6$ ,  $G_5 \setminus S''_6$  is isometric.

- Let  $S_7$  contain  $y_i$ ,  $\bar{y_i}$  for every  $1 \le i \le n$ . Let  $w \in S_7$ . There is some *i* such that neighbours of *w* in  $G_6$  are vertex  $\bar{l_i}$  and either  $e_i$ ,  $f_i$  (if  $w = y_i$ ) or  $\bar{e_i}$ ,  $\bar{f_i}$  (if  $w = \bar{y_i}$ ). Moreover, recall that we assume the existence of some  $1 \le j \le m$  such that  $\bar{l_i}$  appears in clause  $C_j$ . Indeed, all variables are assumed to appear positively and negatively in the clauses of  $\Phi$ . In particular, by construction  $a_{ij}$ ,  $b_{ij}$ ,  $c_{ij}$ ,  $d_{ij} \notin S_2$  and so,  $a_{ij}$ ,  $b_{ij}$ ,  $c_{ij}$ ,  $d_{ij} \in V(G_6)$ . The latter four vertices are adjacent to every of  $\bar{l_i}$ ,  $e_i$ ,  $f_i$  and  $\bar{e_i}$ ,  $\bar{f_i}$  by construction of  $G_{\Phi}$ . As a result, for any  $\alpha$ ,  $\beta \in N_{G_6}(w)$  non-adjacent,  $\alpha$ ,  $\beta$  have a common neighbour in  $G_7$  and so, Corollary 3 applies. In other words,  $G_7 = G_6 \setminus S_7$  is isometric and for every total ordering  $S'_7$  of  $S_7$ , for any prefix  $S''_7$  of  $S'_7$ ,  $G_6 \setminus S''_7$  is isometric.
- Let  $S_8 = V_0 = \{\bar{l}_i \mid 1 \le i \le n\}$ . Let  $\bar{l}_i \in S_8$ . Neighbours of  $\bar{l}_i$  in  $G_7$  are those  $a_{ij}, b_{ij}, c_{ij}, d_{ij}$  such that  $\bar{l}_i$  appears in  $C_j$ . Every such neighbour is adjacent to the 4-tuple  $e_i, f_i, \bar{e}_i, \bar{f}_i$  of the literal clique, hence Corollary 3 applies. In other words,  $G_8 = G_7 \setminus S_8$  is isometric and for every total ordering  $S'_8$  of  $S_8$ , for any prefix  $S''_8$  of  $S'_8, G_7 \setminus S''_8$  is isometric.
- Let  $S_9$  contain every  $a_{ij}$ ,  $b_{ij}$ ,  $c_{ij}$ ,  $d_{ij}$  such that  $\bar{l}_i$  appears in  $C_j$ . The proof for this case is similar as for  $\bar{S}_2$ . Let  $w \in S_9$ . There are  $j \leq m$ ,  $p < q < r \leq n$  such that neighbours of w in  $G_8$  are  $e_p$ ,  $f_p$ ,  $\bar{e}_p$ ,  $\bar{f}_p$  and at most one of  $u_j(p, q)$ ,  $u_j(r, p)$ ,  $v_j(p, q)$  or  $v_j(r, p)$ . Let  $\alpha$ ,  $\beta \in N_{G_8}(w)$  be non-adjacent. Necessarily, one of  $\alpha$ ,  $\beta$  must be one of  $u_j(p, q)$ ,  $u_j(r, p)$ ,  $v_j(p, q)$ ,  $v_j(r, p)$  because any other neighbour of w is in the literal clique. Furthermore,  $u_j(p, q)$ ,  $u_j(r, p)$ ,  $v_j(p, q)$ ,  $v_j(r, p)$  are, respectively, adjacent to  $e_p$ ,  $e_r$ ,  $f_p$ ,  $f_r$  in the literal clique, that are part of  $\mathcal{E} \cup \mathcal{F}$  and so, have not been eliminated with  $S_6$ . Therefore,  $\alpha$ ,  $\beta$  have a common neighbour in  $G_9$  and so, Corollary 3 applies. In other words,  $G_9 = G_8 \setminus S_9$  is isometric and for every total ordering  $S'_9$  of  $S_9$ , for any prefix  $S''_9$  of  $S'_9$ ,  $G_8 \setminus S''_9$  is isometric.
- Let  $S_{10}$  contain every  $u_j(p, q)$ ,  $v_j(p, q)$  such that  $\bar{l_p}$ ,  $\bar{l_q}$  appear in  $C_j$ . Equivalently, those are all of  $u_j(p, q)$ ,  $v_j(p, q)$  but the ones already in  $S_3$ . Let  $w \in S_{10}$ . There exist j, p, q such that neighbours of w in  $G_9$  are either  $e_p$ ,  $\bar{e_q}$  (if  $w = u_j(p, q)$ ) or  $f_p$ ,  $\bar{f_q}$  (if  $w = v_j(p, q)$ ). As a result, vertex w is simplicial. It thus follows that Corollary 3 trivially applies. In other words,  $G_{10} = G_9 \setminus S_{10}$  is isometric and for every total ordering  $S'_{10}$  of  $S_{10}$ , for any prefix  $S''_{10}$  of  $S'_{10}$ ,  $G_9 \setminus S''_{10}$  is isometric.
- Finally, let  $S_{11} = \mathcal{E} \cup \mathcal{F}$ , this is a clique and so, the vertices in  $S_{11}$  can be eliminated sequentially while leaving a sequence of isometric subgraphs.

To sum up, one obtains a distance-preserving ordering of  $G_{\phi}$  by sequentially eliminating vertices in  $S_1$  then in  $S_2$  and so on until  $S_{11}$ , in an arbitrary way.  $\Box$ 

## **Proposition 6.** If $G_{\Phi}$ admits a distance-preserving elimination ordering, then $\Phi$ is satisfiable.

**Proof.** Let  $\prec$  be a distance-preserving ordering of  $G_{\Phi}$ . For every  $1 \leq j \leq m$  we claim that there is  $1 \leq i \leq n$  such that some  $l_i \in \{x_i, \bar{x}_i\}$  satisfies clause  $C_j$ , and  $l_i \prec r_{\Phi}$ . Then, we will prove that this implies a boolean assignment of the variables satisfying  $\Phi$  by showing that  $r_{\Phi} \prec \bar{l}_i$ , where  $\{l_i, \bar{l}_i\} = \{x_i, \bar{x}_i\}$ .

To prove the claim, first observe that for every  $1 \le j \le m, r_{\phi}$  is the unique common neighbour of  $s_j$ ,  $t_j$  in  $G_{\phi}$ . By Corollary 2, it implies  $s_j \prec r_{\phi}$  or  $t_j \prec r_{\phi}$ . So, assume  $s_j \prec r_{\phi}$  (the case  $t_j \prec r_{\phi}$  is symmetrical to this one). Let  $u_j(p, q), u_j(q, r), u_j(r, p)$ 

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be the three children of  $s_j$  in the clause tree. Note that the latter three vertices pairwise share  $s_j$  as their unique common neighbour in  $G_{\phi}$ . Consequently, by Corollary 2 (applied twice) at least two of them must be eliminated before  $s_j$ . W.l.o.g., let  $u_j(p, q)$  be eliminated before  $s_j$ . In such case, note that  $u_j(p, q)$  is the unique common neighbour of  $a_{pj}$ ,  $b_{qj}$  by construction of  $G_{\phi}$ . Therefore, by Corollary 2,  $a_{pj} \prec u_j(p, q)$  or  $b_{qj} \prec u_j(p, q)$ . Suppose by symmetry that  $a_{pj} \prec u_j(p, q)$ . Let  $l_p \in \{x_p, \bar{x_p}\}$  appear in  $C_j$ . Since  $l_p$  and  $u_j(p, q)$  share  $a_{pj}$  as their unique common neighbour and  $a_{pj} \prec u_j(p, q)$ , by Corollary 2  $l_p \prec a_{pj} \prec r_{\phi}$ , that finally proves the claim.

To conclude let us prove for every  $1 \le i \le n$ , there is  $l_i \in \{x_i, \bar{x}_i\}$  such that either  $l_i \prec r_{\phi} \prec \bar{l}_i$  or  $r_{\phi} \prec l_i \prec \bar{l}_i$ . If so, then let us consider any boolean assignment of the variables satisfying for every  $1 \le i \le n$ ,  $l_i$  is assigned true if  $l_i \prec r_{\phi}$  (note that if  $r_{\phi} \prec l_i \prec \bar{l}_i$ , then  $x_i$  can be valuated in an arbitrary way). Since by the above claim, for every  $1 \le j \le m$ , there is  $l_i \prec r_{\phi}$  satisfying clause  $C_j$ , therefore any such assignment satisfies the formula  $\phi$ . By way of contradiction, suppose  $l_i \prec \bar{l}_i \prec r_{\phi}$  with  $\{l_i, \bar{l}_i\} = \{x_i, \bar{x}_i\}$  for some  $1 \le i \le n$ . Since  $y_i, \bar{y}_i$  share  $x_i, \bar{x}_i$  as their only two common neighbours in  $G_{\phi}$ , by Corollary 2  $y_i \prec \bar{l}_i$ . Or  $\bar{y}_i \prec \bar{l}_i$ . Suppose by symmetry  $y_i \prec \bar{l}_i$ . Then, since  $y_i$  is the unique common neighbour between  $\bar{l}_i$  and  $g_i, h_i$ , we have by Corollary 2 that  $g_i \prec y_i$  and  $h_i \prec y_i$ . However, we claim that the combination of  $g_i \prec y_i \prec r_{\phi}$  and  $h_i \prec y_i \prec r_{\phi}$  contradicts the fact that  $\prec$  is distance-preserving. Indeed,  $g_i, h_i$  are the only two common neighbours of  $r_{\phi}$  and  $y_i$ , so, this contradicts Corollary 2.  $\Box$ 

#### 3.3. Reduction to graphs with diameter at most two

As stated before, the graph  $G_{\Phi}$  resulting from our reduction in Section 3.1 has diameter at most five. In this section, we improve the result by lowering the diameter to two, thereby proving Theorem 4.

We base on the local view of Corollary 2, which states that in order to obtain a distance-preserving ordering of *G* it is necessary and sufficient to ensure that vertices at distance two in *G* still have a common neighbour in the graph at each time a vertex is eliminated. This motivates the following Definition 7 – to embed any graph *G* into a graph *G'* with diameter at most two such that any two vertices at distance two in *G* have the same set of common neighbours in *G* and *G'*.

**Definition 7.** Let *G* be a connected graph with *n* vertices, let  $\mathcal{H} = \{\{u, v\} \mid u, v \in V(G) \text{ and } d_G(u, v) \ge 3\}$  and let  $p = |\mathcal{H}|$ . The graph *G'* is obtained from *G* by adding a clique *Z* of n + p vertices, defined as follows.

The graph G is obtained from G by adding a chique Z of n + p vertices, defined as

For every vertex  $v \in V(G)$ , there is  $z_v \in Z$  that is adjacent to v in V(G). For every  $u, v \in V(G)$  such that  $d_G(u, v) \ge 3$ , *i.e.*,  $\{u, v\} \in \mathcal{H}$ , there is  $z_{uv} \in Z$  that is adjacent to u, v in V(G).

**Lemma 8.** For any connected graph G, let G' be as in Definition 7, G' has diameter at most two.

**Proof.** Let  $u, v \in V(G')$ . If  $u \in Z$  or  $v \in Z$  then  $d_{G'}(u, v) \leq 2$  because either  $u, v \in Z$  are adjacent or, w.l.o.g.,  $u \in Z$  and  $z_v \in Z$  is a common neighbour of u, v in G' by Definition 7. Else,  $u, v \in V(G)$  and so,  $d_{G'}(u, v) \leq d_G(u, v)$  because G is an induced subgraph of G'. Moreover, if  $d_G(u, v) \geq 3$  then by Definition 7 there is  $z_{uv} \in Z$  adjacent to u, v in G', therefore  $d_{G'}(u, v) = 2$ .  $\Box$ 

**Lemma 9.** For any connected graph G, let G' be as in Definition 7, G admits a distance-preserving ordering if and only if G' admits one.

**Proof.** Let  $(v_1, v_2, ..., v_n)$  be a distance-preserving ordering of *G*. For every  $1 \le i < n$ , let  $G_i := G \setminus (v_1, ..., v_i)$  be an isometric subgraph of *G*, let  $G'_i$  be the subgraph of *G'* induced by  $V(G_i) \cup Z$  (by convention,  $G_0 := G$ ,  $G'_0 := G'$ ). We claim that for every  $1 \le i < n$ ,  $G'_i$  is an isometric subgraph of *G'*. Note that if the claim holds, then  $(v_1, v_2, ..., v_n)$  can be completed into a distance-preserving ordering of *G'* as follows: vertices  $v_1, v_2, ..., v_n$  are sequentially eliminated, then vertices of the clique *Z* are eliminated in an arbitrary way.<sup>2</sup> To prove the claim, by Lemma 1 it suffices to prove that any two  $x, y \in N_{G'_{i-1}}(v_i)$  non-adjacent share a common neighbour in  $G'_i$ . If  $x, y \in V(G_{i-1})$ , then by Lemma 1 they share a common neighbour in  $G_i$ , hence in  $G'_i$ . Else, one of x, y is in Z, w.l.o.g. say  $x \in Z$  and so,  $z_y \in Z$  is a common neighbour of x, y in  $G'_i$ .

Conversely, let G' admit a distance-preserving ordering. Let  $\prec$  be a distance-preserving elimination ordering of G', and let us consider the restriction  $(v_1, v_2, \ldots, v_n)$  of the total ordering  $\prec$  to the vertices of G. We claim that it is a distance-preserving elimination ordering of G. By contradiction, let i be the least index such that  $G_i := G \setminus (v_1, v_2, \ldots, v_i)$  is not an isometric subgraph of G (by convention,  $G_0 := G$ ). Let j be such that  $v_i$  is the jth vertex to be eliminated in G' w.r.t.  $\prec$ , and let  $G'_j$  be obtained from G' by removing the j first vertices to be eliminated in G' w.r.t.  $\prec$ . Note that  $G'_j$  is an isometric subgraph of G' because  $\prec$  is distance-preserving by the hypothesis. Moreover, since  $(v_1, v_2, \ldots, v_n)$  is assumed not to be distance-preserving, then by Lemma 1, there exist  $x, y \in N_{G_{i-1}}(v_i)$  non-adjacent whose unique common neighbour in the subgraph  $G_{i-1}$  is  $v_i$ . In such case,  $d_G(x, y) = 2$ , therefore x, y have no common neighbour in the clique Z by Definition 7. However,  $V(G_i) \subseteq V(G'_i) \subseteq Z$  by construction, therefore x, y have no common neighbour in  $G'_j$ , that contradicts the fact that  $G'_i$  is an isometric subgraph of G' by Lemma 1.  $\Box$ 

<sup>&</sup>lt;sup>2</sup> In fact, if vertices  $z_{v_1}, z_{v_2}, \ldots, z_{v_n}$  are the last removed in *Z* then one obtains a breadth-first search ordering rooted at  $z_{v_n}$ . This proves that the problem of deciding whether there exists a breadth-first search ordering that is distance-preserving is NP-complete.

Altogether, we can now prove our main result as follows.

**Proof of Theorem 4.** The problem is in NP. In order to prove the NP-hardness, let  $\Phi$  be any instance for 3-SAT. The graph  $G_{\Phi}$ , described in Section 3.1, can be constructed from  $\Phi$  in polynomial time. Furthermore, by the combination of Propositions 5 and 6,  $G_{\Phi}$  admits a distance-preserving ordering if and only if  $\Phi$  is satisfiable. Finally, let  $G'_{\Phi}$  be obtained from  $G_{\Phi}$  as defined in Definition 7. By Lemma 8,  $G'_{\Phi}$  has diameter at most two, furthermore by Lemma 9,  $G'_{\Phi}$  admits a distance-preserving ordering if and only if  $\Phi$  is satisfiable. Since 3-SAT is NP-complete [13], this proves the hardness and so, the result.  $\Box$ 

## 4. A polynomial case

In this section, we prove that the problem of computing a distance-preserving ordering when there exists one is fixedparameter-tractable in the treewidth.

A tree-decomposition  $(T, \mathcal{X})$  of a graph G = (V, E) is a pair consisting of a tree T and of a family  $\mathcal{X} = (X_t)_{t \in V(T)}$  of subsets of V indexed by the nodes of T and satisfying:

- (i)  $\bigcup_{t \in V(T)} X_t = V$ ;
- (ii) for any edge  $e = \{u, v\} \in E$ , there exists  $t \in V(T)$  such that  $u, v \in X_t$ ;
- (iii) for any  $v \in V$ ,  $\{t \in V(T) \mid v \in X_t\}$  induces a subtree, denoted by  $T_v$ , of T.

The sets  $X_t$  are called *the bags* of the decomposition. Furthermore, the width of  $(T, \mathcal{X})$  is equal to  $\max_{t \in V(T)} |X_t| - 1$ , and the *treewidth* of *G* is the minimum possible width of its tree-decompositions.

It is well-known that many NP-hard problems are fixed-parameter tractable (FPT) in the treewidth [18]. Furthermore, the existence of distance-preserving orderings has been proved useful in the comparative study of treewidth with some other properties of the tree-decompositions of graphs [17]. We prove that it can be decided in polynomial-time whether a given bounded treewidth graph admits a distance-preserving ordering, and if so, one such ordering can also be computed in polynomial-time. More precisely, we prove in what follows that the problem is FPT with the treewidth as parameter.

**Theorem 10.** For every G = (V, E) with treewidth at most k, it can be decided whether a distance-preserving ordering exists in time  $2^{2^{O(k)}} \cdot n^{O(1)}$ . Furthermore, if it is the case, then a distance-preserving ordering for G can also be computed within the same amount of time.

**Proof.** For simplicity, we will work on a specific kind of tree-decompositions, called nice tree-decompositions. A tree-decomposition (T, X) is *nice* if T is rooted in some node  $r \in V(T)$ , any node of T has at most two children and, for any  $t \in V(T)$ ,

- either *t* is a leaf of *T* and  $|X_t| = 1$  (*Leaf Node*);
- or *t* has one child *u* and there exists  $v \in V$  such that  $X_t = X_u \setminus \{v\}$  (Forget Node);
- or *t* has one child *u* and there exists  $v \in V$  such that  $X_t = X_u \cup \{v\}$  (*Introduced Node*);
- or *t* has two children *u* and *w* and  $X_u = X_w = X_t$  (*Join Node*).

In what follows, let  $(T, \mathcal{X})$  be a nice tree-decomposition of width  $\mathcal{O}(k)$ . It can be computed in time  $2^{\mathcal{O}(k)}n$  [4]. For every  $t \in V(T)$ , let  $T_t$  be the subtree rooted at node t and let  $V_t = \bigcup_{u \in T_t} X_u$ . We aim at computing all the orderings on  $V_t$  that can be extended to a distance-preserving ordering of G. In order to do so, we will represent an ordering on  $V_t$  as follows:

- its subordering  $\prec_t$  on  $X_t$ ;
- the collection  $C_t$  of pairs  $(N(v) \cap X_t, pos_v)$  for every  $v \in V_t \setminus X_t$ , where  $pos_v$  is the number of neighbours in  $N(v) \cap X_t$  preceding vertex v;
- finally, a set  $\mathcal{P}_t$  of pairs  $x, y \in X_t$  at distance two in G such that both x and y are preceded by all their common neighbours in  $V_t$ .

Note that for any fixed vertex  $v \in V_t$ , there are  $2^{\mathcal{O}(k)}$  possibilities for  $N(v) \cap X_t$  and  $\mathcal{O}(k)$  possibilities for  $pos_v$ . In particular, since  $C_t$  can be any subset of a set with  $\mathcal{O}(k)2^{\mathcal{O}(k)}$  elements, there are  $2^{\mathcal{O}(k)2^{\mathcal{O}(k)}}$  possibilities for  $C_t$ . Overall there are  $k! \cdot 2^{\mathcal{O}(k)2^{\mathcal{O}(k)}} \cdot \mathcal{O}(k^2) = 2^{2^{\mathcal{O}(k)}}$  possible representations.

Intuitively, we aim at computing for every node  $t \in V(T)$  the suborderings  $\prec_t$  of  $V_t$  that could be potentially extended to a distance-preserving elimination ordering of *G*. In order to do so, let  $\prec$  be any distance-preserving elimination ordering of *G*, let  $t \in V(T)$  and let  $\prec_t$  be the subordering of  $\prec$  constrained to  $V_t$ . By Corollary 2, for every  $x, y \in V_t$  at distance two in *G*, there exists a common neighbour  $z \in N_G(x) \cap N_G(y)$  such that either  $x \prec z$  or  $y \prec z$ . Furthermore, if  $z \in V_t$  then we have either  $x \prec_t z$  or  $y \prec_t z$ , otherwise since  $z \notin V_t$  we have by the properties of a tree-decomposition that  $x, y \in X_t$ . Hence, we will consider a representation to be valid at node  $t \in V(T)$  if it represents an ordering  $\prec'_t$  of  $V_t$  with the following property: for every  $x, y \in V_t$  at distance two in *G*, there exists a common neighbour  $z \in N_G(x) \cap N_G(y)$  such that either  $\{x, y\} \in \mathcal{P}_t$  and  $z \in V \setminus V_t$ , or  $z \in V_t$  and one of x or y precedes z w.r.t.  $\prec'_t$ . For every  $t \in V(T)$ , the following algorithm will compute *all* the valid representations at node *t*. Let us observe that for every subordering  $\prec_t$  of  $V_t$  and for any child  $u \in V(T)$  of *t*, if  $\prec_t$  has a valid representation at node *t* then its restriction  $\prec_u$ to  $V_u$  also has a valid representation at node *u*. We will use this observation in what follows in order to compute the valid representations at every node by dynamic programming. Furthermore, if  $\prec$  is a distance-preserving ordering of *G* then as proved above, for every  $t \in V(T)$  its restriction  $\prec_t$  to  $V_t$  has a valid representation at node *t*. Conversely, by Corollary 2 a valid representations at the root is equivalent to the existence of a distance-preserving ordering of *G*, and so, the following algorithm is correct.

- Case of a Leaf Node. In this situation,  $V_t = X_t = \{v\}$  for some  $v \in V$ . So, there is a unique valid representation  $(\prec_t = (v), C_t = \emptyset, \mathcal{P}_t = \emptyset)$ .
- **Case of a Forget Node.** Let  $u \in V(T)$  be the unique child of node t and let  $v \in V$  be such that  $X_t = X_u \setminus \{v\}$ . Consider any valid representation at node u.

If there is a pair  $\{x, v\}$  containing v in  $\mathcal{P}_u$  then we claim that it cannot be extended to a valid representation at node t. Indeed, since  $v \in X_u \setminus X_t$  it has no neighbour in  $V \setminus V_t$  (by Property (ii) of tree-decompositions). Therefore, given any subordering on  $V_t$  that is mapped to this representation, the two vertices v and x are eliminated after all their common neighbours in *any* extension of this subordering to a total ordering on V. The latter falsifies the characterization of distance-preserving orderings given in Corollary 2, that proves the claim.

Else, there is no pair of  $\mathcal{P}_u$  containing v. In this situation, the representation can be transformed into a valid representation at node t by taking the restriction of  $\prec_u$  to  $X_t$  and by constructing  $\mathcal{C}_t$  as follows. First let us add the pair  $(N(v) \cap X_t, pos_v)$  in  $\mathcal{C}_t$ , that can be easily computed from  $\prec_u$  (recall that  $pos_v$  is the number of neighbours of v in  $X_u$  that are preceding v w.r.t.  $\prec_u$ ). Then for every pair  $(N, p) \in \mathcal{C}_u$ , either v is among the p first neighbours in N w.r.t.  $\prec_u$ , in which case let us add  $(N \setminus v, p - 1)$  in  $\mathcal{C}_t$ , or let us add  $(N \setminus v, p)$  in  $\mathcal{C}_t$ .

- **Case of an Introduced Node.** Let  $u \in V(T)$  be the unique child of node t and let  $v \in V$  be such that  $X_t = X_u \cup \{v\}$ . Consider any valid representation at node u. We consider the O(k) possible ways to insert v w.r.t.  $\prec_u$ , in order to obtain the subordering  $\prec_t$ . For every  $\prec_t$ , we need to consider all vertices in  $V_t$  that are at distance two from v. We distinguish between two subcases.
  - First, let  $Y_u \subseteq X_u$  contain all the vertices x of  $X_u$  that are at distance two from v. For every  $x \in Y_u$ , we check whether there exists a common neighbour z such that either  $z \in X_u$  and it is preceded by one of x or v (this can be checked with  $\prec_t$ ), or  $z \notin V_t$ . If no such vertex z exists (that means that all common neighbours are in  $V_t$  and they all preced x and v in the current ordering) then we claim that it is not possible to extend to a valid representation at node t. Indeed, let us fix an arbitrary extension  $\prec$  of  $\prec_t$  to a total ordering on V. Suppose by way of contradiction that  $\prec$  is distance-preserving. By Corollary 2, there exists  $z' \in N(v) \cap N(x)$  such that  $x \prec z'$  or  $v \prec z'$ . Furthermore,  $z' \in V_t$  (else, we could choose z = z', that is a contradiction). By Property (ii) of tree-decompositions, v has no neighbours in  $V_t \setminus X_u$ , and so,  $z' \in X_u$ . However, since  $\prec$  is an extension of  $\prec_t$ , the latter implies that  $x \prec_t z'$  or  $v \prec_t z'$ . Hence we could choose z = z', that is a contradiction. Therefore, the claim is proved.

Otherwise, there exists a common neighbour *z* as defined above. In this situation, we will need to add the pair  $\{x, v\}$  in  $\mathcal{P}_t$  if and only if all possible choices for *z* are in  $V \setminus V_t$ . Note that after iterating on all the vertices of  $Y_u$ , we will also need to complete  $\mathcal{P}_t$  with the pairs  $\{x, y\} \in \mathcal{P}_u$  such that *x* and *y* have a common neighbour in  $V \setminus V_t$  and they are preceded by all their common neighbours in  $V_t = V_u \cup \{v\}$ . Furthermore, we need to check that for all the pairs  $\{x, y\} \in \mathcal{P}_u \setminus \mathcal{P}_t$ , vertex *v* is a common neighbour of *x* and *y* such that either  $x \prec_t v$  or  $y \prec_t v$  (otherwise, we cannot extend to a valid representation and  $\prec_t$  can be discarded).

- Second, let us consider all vertices  $x \in V_t \setminus X_u$  that are at distance two from v. Note that since by Property (ii) of tree-decompositions v has no neighbours in  $V_t \setminus X_u$ , we have that for every  $x \in V_t \setminus X_u$ , x is at distance two from v if and only if  $(N(x) \cap X_u) \cap N(v) \neq \emptyset$ . Precisely, all the common neighbours of v and x are in  $X_u$  (and in  $X_t$ ). So, let us consider all the pairs  $(N, p) \in C_u$  such that  $N \cap N(v) \neq \emptyset$  (intuitively, this corresponds to a vertex  $x \in V_t \setminus X_u$  that has a common neighbour with v).

For every such pair (N, p), let us define  $N^+$  as the subset obtained from N by removing its p first vertices w.r.t.  $\prec_u$ . Similarly, let  $N^+(v)$  be the vertices of  $N(v) \cap X_u$  that are preceded by v w.r.t.  $\prec_t$ . We check whether either  $N^+(v) \cap N \neq \emptyset$  or  $N^+ \cap N(v) \neq \emptyset$ . Intuitively, the former corresponds to the case where v preceeds one common neighbour of x and v, and the latter corresponds to the case where x preceeds one common neighbour of x and v, with x being such that  $(N(x) \cap X_u, pos_x) = (N, p)$ . If the test fails then we claim that we cannot extend to a valid representation at node t (and so, the current subordering  $\prec_t$  can be discarded).

Indeed, let  $\prec$  be any extension of  $\prec_t$  to a total ordering on *V*. Suppose by way of contradiction that  $\prec$  is distancepreserving. Let  $x \in V_t \setminus X_u$  be such that  $(N(x) \cap X_u, pos_x) = (N, p)$ . Note that *x* and *v* are at distance two. So, by Corollary 2, there exists a common neighbour  $z \in X_u$  that is preceded by at least one of *v* or *x*. Furthermore, let us denote by  $N^+(x) = N^+$  the subset of  $N(x) \cap X_u$  obtained by removing its  $pos_x$  first neighbours in  $X_u$  w.r.t.  $\prec_t$ . We get that either *v* precedes *z*, and so,  $N^+(v) \cap N(x) \neq \emptyset$ , or *x* precedes *z*, and so,  $N^+(x) \cap N(v) \neq \emptyset$ . The latter contradicts that neither  $N^+(v) \cap N \neq \emptyset$  nor  $N^+ \cap N(v) \neq \emptyset$ , therefore the claim is proved.

Conversely, let us point out that if for every  $(N, p) \in C_u$  such that  $N \cap N(v) \neq \emptyset$ , either  $N^+(v) \cap N \neq \emptyset$  or  $N^+ \cap N(v) \neq \emptyset$ , then the following holds for every  $x \in V_t \setminus X_u$  at distance two from v: either  $N^+(v) \cap N(x) \neq \emptyset$ ,

and so, there exists a common neighbour *z* preceded by *v*, or  $N^+(x) \cap N(v) \neq \emptyset$ , and so, there exists a common neighbour *z* preceded by *x*.

Note that the collection  $C_u = C_t$  is not modified.

• **Case of a Join Node.** Let u, w be the two children nodes of t. Recall that  $X_u = X_w = X_t$ . Consider any valid representation at node u, and any valid representation at node w. They can be merged into a valid representation at node t only if  $\prec_u = \prec_w$ . If so, let  $\prec_t = \prec_u$ , let  $\mathcal{P}_t = \mathcal{P}_u \cap \mathcal{P}_w$  and let  $\mathcal{C}_t = \mathcal{C}_u \cup \mathcal{C}_w$ .

In order to decide whether this can be extended into a valid representation at node t, we need to consider all the pairs of vertices in  $V_t$  at distance two in G that are neither both contained in  $V_u$  nor both contained in  $V_w$ . More precisely, we need to consider all the pairs of vertices  $v_u \in V_u \setminus X_u$ ,  $v_w \in V_w \setminus X_w$  at distance two in G. Notice that since by Property (ii) of tree-decompositions, there cannot be an edge between  $V_u \setminus X_u$  and  $V_w \setminus X_w$ , the pairs  $v_u \in V_u \setminus X_u$ ,  $v_w \in V_w \setminus X_w$  that need to be considered are exactly those such that  $(N(v_u) \cap X_u) \cap (N(v_w) \cap X_w) \neq \emptyset$ . Hence, let us consider all the pairs  $(N_u, p_u) \in C_u$ ,  $(N_w, p_w) \in C_w$  such that  $N_u \cap N_w \neq \emptyset$ .

For every two pairs  $(N_u, p_u) \in C_u$ ,  $(N_w, p_w) \in C_w$  such that  $N_u \cap N_w \neq \emptyset$ , let  $N_u^+$  be the subset obtained from  $N_u$  by removing its  $p_u$  first vertices w.r.t.  $\prec_t = \prec_u$ . Intuitively,  $N_u^+$  corresponds to the neighbours of some vertex  $v_u \in V_u \setminus X_u$  that are in  $X_u = X_t$  and preceded by  $v_u$ . Similarly, let  $N_w^+$  be the subset obtained from  $N_w$  by removing its  $p_w$  first vertices w.r.t.  $\prec_t = \prec_w$ . We check whether either  $N_u^+ \cap N_w \neq \emptyset$  or  $N_w^+ \cap N_u \neq \emptyset$ . If it is not the case then we claim that we cannot extend to a valid representation at node t (and so, the current subordering  $\prec_t$  can be discarded).

Indeed, let  $\prec$  be any extension of  $\prec_t$  to a total ordering on *V*. Suppose by way of contradiction that  $\prec$  is distancepreserving. Let  $v_u \in V_u \setminus X_u$ ,  $v_w \in V_w \setminus X_w$  be such that  $(N(v_u) \cap X_u, pos_{v_u}) = (N_u, p_u)$  and  $(N(v_w) \cap X_w, pos_{v_w}) = (N_w, p_w)$ . Since  $N(v_u) \cap N(v_w) = N_u \cap N_w \neq \emptyset$ ,  $v_u$  and  $v_w$  are at distance two. Therefore, by Corollary 2, there exists a common neighbour  $z \in X_t$  that is preceded by at least one of  $v_u$  or  $v_w$ . Furthermore, let us denote by  $N^+(v_u) = N_u^+$  the subset of  $N(v_u) \cap X_u$  obtained by removing its  $pos_{v_u}$  first neighbours in  $X_u$  w.r.t.  $\prec_t = \prec_u$ ; similarly, let us denote by  $N^+(v_w) = N_w^+$ the subset of  $N(v_w) \cap X_w$  obtained by removing its  $pos_{v_w}$  first neighbours in  $X_w$  w.r.t.  $\prec_t = \prec_w$ . We get that either  $v_u$ precedes z, and so,  $N^+(v_u) \cap N(v_w) \neq \emptyset$ , or  $v_w$  precedes z, and so,  $N^+(v_w) \cap N(v_u) \neq \emptyset$ . The latter contradicts that neither  $N_u^+ \cap N_w \neq \emptyset$  nor  $N_w^+ \cap N_u \neq \emptyset$ , therefore the claim is proved.

Conversely, let us point out that if for every  $(N_u, p_u) \in C_u$ ,  $(N_w, p_w) \in C_w$  such that  $N_u \cap N_w \neq \emptyset$ , either  $N_u^+ \cap N_w \neq \emptyset$ or  $N_w^+ \cap N_u \neq \emptyset$ , then the following holds for every  $v_u \in V_u \setminus X_u$ ,  $v_w \in V_w \setminus X_w$  at distance two in *G*: either  $N^+(v_u) \cap N(v_w) \neq \emptyset$ , and so, there exists a common neighbour *z* preceded by  $v_u$ , or  $N^+(v_w) \cap N(v_u) \neq \emptyset$ , and so, there exists a common neighbour *z* preceded by  $v_w$ .  $\Box$ 

#### 5. Exact algorithms and heuristics

The purpose of the section is to describe algorithms in order to compute a distance-preserving ordering for a given graph *G* when it exists. Exhaustive-search on all possible vertex-orderings of the graph would require  $\mathcal{O}^*(n!) = 2^{\mathcal{O}(n \log n)}$ -time,<sup>3</sup> and the algorithm parameterized by treewidth that we have presented in Section 4 has huge constants which makes it rather impractical.

In this section, we describe exact and heuristic algorithms that can effectively be used to decide if a graph has a distancepreserving ordering, and return one when it exists.

#### 5.1. Exact exponential time algorithm

A meta-theorem for computing vertex-orderings in graphs with given properties was proved in [3]. It bases on dynamic programming. Here, we prove that the theorem of [3] also applies to distance-preserving orderings. For any elimination ordering  $(v_1, v_2, ..., v_n)$  of a graph G = (V, E) and for any  $1 \le i \le n$ , let  $V_{i+1} = \{v_{i+1}, v_{i+2}, ..., v_n\} = \{u \in V \mid v_i \prec u\}$ .

**Theorem 11** ([3]). Let f be a polynomial time computable function mapping each 3-tuple, consisting of a graph G = (V, E), a vertex set  $S \subseteq V$ , and a vertex  $v \in V$  to an integer.

Then we can compute in  $\mathcal{O}^*(2^n)$ -time and space, or in  $\mathcal{O}^*(4^n)$ -time and polynomial-space, the following values for a given graph G = (V, E):

- $\min_{\prec} \max_{v_i \in V} f(G, V_{i+1}, v_i);$
- $\min_{\prec} \sum_{v_i \in V} f(G, V_{i+1}, v_i).$

**Corollary 12.** The problem of deciding whether a given graph admits a distance-preserving elimination ordering can be solved in  $\mathcal{O}^*(2^n)$ -time and space, or in  $\mathcal{O}^*(4^n)$ -time and polynomial-space.

<sup>&</sup>lt;sup>3</sup> The notation  $\mathcal{O}^*(f(n))$  is for a complexity  $f(n) \cdot n^{\mathcal{O}(1)}$ .

**Proof.** Let the function f map every 3-tuple (G, S, v) to the number of pairs  $x, y \in S \cap N_G(v)$  of nonadjacent vertices with no common neighbour in S. Given a graph G = (V, E) our aim is to compute an elimination ordering  $(v_1, v_2, ..., v_n)$  of G that minimizes  $\max_{1 \le i < n} f(G, V_{i+1}, v_i)$ , with  $V_{i+1} = \{v_{i+1}, v_{i+2}, ..., v_n\}$ . Indeed, by Corollary 2, G admits a distance-preserving elimination ordering if and only if there is one such ordering such that for every  $1 \le i \le n$ ,  $f(G, V_{i+1}, v_i) = 0$ , *i.e.*,  $\max_{1 \le i < n} f(G, V_{i+1}, v_i) = 0$ . By Theorem 11 and since f is polynomial-time computable an ordering that minimizes  $\max_{1 \le i < n} f(G, V_{i+1}, v_i)$  can be computed in  $\mathcal{O}^*(2^n)$ -time and space, or in  $\mathcal{O}^*(4^n)$ -time and polynomial-space.  $\Box$ 

#### 5.2. Integer linear programming

Integer linear programming (ILP) formulations have been proved useful in practical computation of vertex orderings [8,16]. For completeness, we hence propose an ILP formulation that fits to our problem. Like in [16], total ordering on the vertices is expressed through  $n^2$  binary variables  $x_{v,i}$ , each denoting whether vertex  $v \in V$  is amongst the *i* first vertices to be eliminated.

$$\sum_{v \in V} x_{v,i} = i \qquad \forall \ 1 \le i \le n \tag{1}$$

$$x_{v,i} \le x_{v,i+1} \qquad \forall v \in V, \ \forall \ 1 \le i < n \tag{2}$$

In order to ensure that the total ordering is distance-preserving, we impose that for all pairs of vertices  $u, v \in V$  at distance two in G, at least one of u or v must be eliminated before some of their common neighbours w. It can be expressed as follows:

$$\sum_{w \in N_G(u) \cap N_G(v)} x_{w,i} \le x_{u,i} + x_{v,i} + (|N_G(u) \cap N_G(v)| - 1)$$
(3)

 $\forall u, v \text{ s.t. } d_G(u, v) = 2, \forall 1 \le i \le n$ 

The correctness of our formulation directly follows from Corollary 2.

## 5.3. Heuristics

In this section, we present three heuristics to decide whether a graph admits a distance-preserving ordering. Then, we propose two ways to generate graphs admitting distance-preserving orderings.

*Heuristic Greedy\_Pruning*. The first heuristic, very naive, attempts to find a distance preserving ordering greedily. Precisely, given a graph *G*, it computes the set *C* of all vertices *v* such that  $G \setminus v$  is an isometric subgraph of *G*. Note that, by Lemma 1, this can be done by checking only the vertices at distance at most two for every vertex in *G*. Once the set *C* of candidates has been computed, one vertex *v* is randomly chosen in it (this will be the first vertex of the tried ordering) and the process goes on  $G \setminus v$ . If  $C = \emptyset$ , the process stops and returns that no distance preserving ordering has been found. If *G* has no more vertices, the algorithm returns the found ordering. The pseudo-code of this heuristic is presented in Algorithm 1.

Algorithm 1 Greedy\_Pruning

**Require:** A graph G = (V, E), a layout L of a subset  $S \subseteq V$  of the vertices of G 1:  $H := G[V \setminus S]$ 2: if  $V(H) = \emptyset$  then return L 3: 4:  $C := \emptyset$ 5: for all  $v \in V \setminus S$  do **if**  $H \setminus v$  is an isometric subgraph of H **then** 6.  $C := C \cup \{v\}$ 7: 8: if  $C = \emptyset$  then return "No ordering found" ٩· 10: Let  $v \in C$  randomly chosen 11: **return** Greedy\_Pruning  $(G, L \odot v)$ 

*Heuristic Greedy\_Reverse\_Pruning*. The second heuristic attempts to build the ordering starting from its last vertex. Precisely, it guesses the last vertex (all vertices of the graph *G* may be considered as last vertex). From the current vertex, the algorithm tries to guess its predecessor in the ordering. Precisely, assuming that the algorithm has already computed a partial layout  $(v_{i+1}, \ldots, v_n)$  of a set  $S = \{v_{i+1}, \ldots, v_n\} \subseteq V$ , it aims at finding a vertex  $v_i$  such that G[S] is an isometric subgraph of  $G[\{v_i\} \cup S]$ . For this purpose, it computes the set *C* of all vertices  $v \in N(S) = \{v \in V(G) \setminus S \mid \exists u \in S, \{u, v\} \in E(G)\}$  that satisfies this property. By Lemma 1, a vertex  $v \in N(S)$  is added to *C* if any two non-adjacent neighbours  $x, y \in N(v) \cap S$  have another common neighbour in *S*. Once the set *C* of candidates has been computed, if it is empty, then the process stops and returns that no distance preserving ordering has been found. Otherwise, there are two variants of the heuristic:

- In the first one, one vertex v is randomly chosen in C.
- In the second case, one vertex v is randomly chosen in the set of the vertices of C that have maximum degree in S.

In both cases, the chosen vertex v is added as first vertex of the current layout. The pseudo-code of this heuristic (second variant) is presented in Algorithm 2. For the first variant, the only difference is that Line 9 must be replaced by "Let  $C^* := C$ ".

Algorithm 2 Greedy\_Reverse\_Pruning

**Require:** A graph G = (V, E), a layout L of a subset  $S \subseteq V$  of the vertices of G 1: if S = V then 2: return L 3:  $C := \emptyset$ 4: for all  $v \in N(S) = \{v \in V(G) \setminus S \mid \exists u \in S, \{u, v\} \in E(G)\}$  do 5: if  $\forall x, y \in N_G(v) \cap S, N(x) \cap N(y) \cap S \neq \emptyset$  or  $\{x, y\} \in E$  then 6:  $C := C \cup \{v\}$ 7: if  $C = \emptyset$  then return "No ordering found" 8. 9: Let  $C^* \subseteq C$  be the set of the vertices in *C* with maximum degree in *S* 10: Let  $v \in C^*$  randomly chosen 11: **return** Greedy\_Reverse\_Pruning  $(G, v \odot L)$ 

The intuition behind the fact that it seems preferable to take a vertex with maximum degree in S (Line 9 of Algorithm 2) is clear since it will maximize the number of pairs of vertices already having a common neighbour in S (which is a required condition to compute C on Line 5 of Algorithm 2).

*Graph generation.* To generate graphs with distance preserving ordering (in order to test the heuristics), we propose the following two algorithms.

- The first algorithm (INC) creates a graph by adding the vertices one by one. Precisely, assuming that a graph *G* (admitting a distance-preserving ordering) has already been created, the algorithm adds a new vertex as follows. First a vertex  $x \in V(G)$  is randomly chosen. Then, the algorithm randomly chooses a set  $X \subseteq \{w \in V(G) \mid dist(x, w) \le 2\}$  with the property that any two non-adjacent vertices in *X* have a common neighbour is *G*. Finally, a new vertex *v* is added to *G* by making *v* adjacent to every vertex in  $X \cup \{x\}$ . The cardinality of *X* can additionally be bounded.
- The second algorithm (AUG) aims at augmenting a given graph into a super-graph of it admitting a distance-preserving ordering. For this purpose, the algorithm starts from a given graph G = (V, E) and first computes a random ordering  $L = (v_1, \ldots, v_n)$  of V. Then, we aim at adding edges to G in order to make L a distance-preserving ordering of the resulting super-graph of G. Precisely, the algorithm considers the vertices one by one from  $v_1$  to  $v_n$ . When considering  $v_i$ , if  $G_{i+1} = G[\{v_{i+1}, \ldots, v_n\}]$  is an isometric subgraph of  $G_i$ , then no edges are added. Otherwise, by Lemma 1, this means that two non-adjacent neighbours  $x, y \in V(G_{i+1}) \cap N(v_i)$  of  $v_i$  have no common neighbour in  $G_{i+1}$ . Hence, the algorithm adds edges between every such a pair of vertices.

We have used these generators to perform basic experiments on a standard laptop, using the *Sagemath* open-source mathematical software [30] to implement the algorithms and IBM Ilog CPLEX [23] to solve the ILP formulations. Our first observation is that the ILP formulation is generally able to decide if a graph with up to 50 nodes has a distance-preserving ordering in a few minutes (we also tried Erdős–Rényi and Barabási–Albert random graphs). However, it can hardly be used for larger graphs due to excessive running time. Our second observation is that the Greedy\_Pruning heuristic is not effective at all. It is able to find a distance-preserving ordering on very few small graphs (less than 20 nodes) only. The Greedy\_Reverse\_Pruning heuristic guided by the maximum degree is much more efficient. We have executed it on graphs generated by the INC generator (100 *n*-node graphs, for each  $n \in \{20, 30, \ldots, 100\}$ ). The heuristic has been able to confirm that more than 96% of these graphs have a distance-preserving ordering. Also, this heuristic appears to be particularly efficient on dense graphs. Precisely, we performed many experiments on Erdős–Rényi random graphs (100 *n*-node graphs, for each  $n \in \{100, \ldots, 200\}$  and  $p \in \{0.1, 0.2, \ldots, 0.5\}$ ) and our heuristic returns that more than 99% of them actually have a distance-preserving ordering the supports a recent conjecture from [27]. Further experimental and theoretical investigations are needed to determine the minimum probability upon which Erdős–Rényi random graphs have a distance-preserving ordering asymptotically almost surely. We let this interesting question as an open problem for future research.

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