

# Table of Content

Agradecimientos	iv
Table of Content	vi
<b>1 Introduction</b>	<b>1</b>
1.1 Research objectives	3
1.2 A review of Navier-Stokes equations with some variations	3
1.2.1 Notations	4
1.2.2 The equations for the direct problem	4
1.2.3 Existence and uniqueness of weak solutions for the direct problem	5
<b>2 Analysis of obstacles in viscous fluids using Brinkman's law</b>	<b>11</b>
2.1 Introduction	11
2.2 Preliminaries and notations	13
2.3 Stokes system with mixed boundary conditions	14
2.3.1 Preliminary results	15
2.3.2 Main results	17
2.4 Navier-Stokes equation with Dirichlet boundary conditions	18
2.4.1 Preliminary results	18
2.4.2 Main results	21
2.5 Numerical examples	23
2.5.1 Stokes equation	25
2.5.2 Navier-Stokes equation	26
2.6 Conclusions	28
<b>3 A stability result for Navier-Stokes equations</b>	<b>30</b>
3.1 An historic introduction to Carleman inequalities and its applications	30
3.2 Introduction and main model	31
3.3 A Carleman estimate	33
3.4 Main result	38
3.5 Numerical results	45
3.5.1 Recovering a smooth function	45
3.5.2 Recovering a non-smooth function	48
3.6 Conclusions	51
<b>4 A distributed resistance inverse method: the Oseen problem</b>	<b>53</b>
4.1 Introduction	53
4.2 Model problem	55

4.3	Existence of solution . . . . .	56
4.4	First order necessary optimality condition . . . . .	57
4.5	Second order sufficient optimality condition. . . . .	60
4.6	Numerical results . . . . .	67
4.6.1	Reference test . . . . .	67
4.6.2	Numerical solution of the inverse problem . . . . .	69
4.6.3	Measurements of MRI type . . . . .	71
4.6.4	Measurements of ultrasound imaging type . . . . .	75
4.7	Conclusions . . . . .	77
<b>5</b>	<b>A distributed resistance inverse method: the Navier-Stokes problem</b>	<b>79</b>
5.1	Introduction . . . . .	79
5.2	Model problem . . . . .	80
5.3	Existence of solution . . . . .	81
5.4	First order necessary optimality condition . . . . .	82
5.5	Second order sufficient optimality condition . . . . .	89
5.6	Numerical Results . . . . .	98
5.6.1	2D reference test . . . . .	99
5.6.2	Numerical solution of the inverse problem in 2D . . . . .	100
5.6.3	Measurements of MRI type in 2D . . . . .	102
5.6.4	3D reference test . . . . .	106
5.6.5	Numerical solution of the inverse problem in 3D . . . . .	108
5.6.6	Measurements of MRI type in 3D . . . . .	109
5.7	Conclusions . . . . .	111
<b>6</b>	<b>Conclusions and future work</b>	<b>112</b>
	<b>Bibliography</b>	<b>114</b>