

Analysis and evolution of air quality monitoring networks using combined statistical information indexes

By AXEL OSSES^{1,2,3*}, LAURA GALLARDO^{3,4} and TANIA FAUNDEZ¹, ¹*Centro de Modelamiento Matemático, Universidad de Chile – CNRS, Blanco Encalada 2120, Piso 7, Santiago, Chile;* ²*Departamento de Ingeniería Matemática, Universidad de Chile, Blanco Encalada 2120, Piso 5, Santiago, Chile;* ³*Center for Climate and Resilience Research (CR2), Santiago, Chile;* ⁴*Departamento de Geofísica, Universidad de Chile, Blanco Encalada 2002, Santiago, Chile*

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ABSTRACT

In this work, we present combined statistical indexes for evaluating air quality monitoring networks based on concepts derived from the information theory and Kullback–Liebler divergence. More precisely, we introduce: (1) the standard measure of complementary mutual information or ‘specificity’ index; (2) a new measure of information gain or ‘representativity’ index; (3) the information gaps associated with the evolution of a network and (4) the normalised information distance used in clustering analysis. All these information concepts are illustrated by applying them to 14 yr of data collected by the air quality monitoring network in Santiago de Chile (33.5 S, 70.5 W, 500 m a.s.l.). We find that downtown stations, located in a relatively flat area of the Santiago basin, generally show high ‘representativity’ and low ‘specificity’, whereas the contrary is found for a station located in a canyon to the east of the basin, consistently with known emission and circulation patterns of Santiago. We also show interesting applications of information gain to the analysis of the evolution of a network, where the choice of background information is also discussed, and of mutual information distance to the classifications of stations. Our analyses show that information as those presented here should of course be used in a complementary way when addressing the analysis of an air quality network for planning and evaluation purposes.

Keywords: information theory, optimal network design, air quality monitoring, Santiago de Chile

1. Introduction

The objectives of a monitoring network are multiple and usually include: compliance of air quality standards, which in turn may trigger control procedures, evolution of air quality and efficiency of curbing measures, and impacts on human health, ecosystems and climate, and so on (see e.g. Ainslie et al., 2009). Also, optimal network design must take into consideration practical constraints related to costs, security, and so on. Thus, the question of how to best sample airborne pollutants in a monitoring network is non-trivial. Over the last two decades or so, an increasing amount of research has been oriented towards optimal network design, particularly in the area of air quality, for example, Caselton and Zidek (1984); Haas (1992); Pérez-Abreu and Rodríguez (1996); Zidek et al. (2000);

Chow et al. (2002); Elkamel et al. (2008); Pesch et al. (2008); Ruiz-Cárdenas et al. (2010); Zidek and Zimmerman (2010); Saunier et al. (2011); Wu and Bocquet (2011); Ruiz-Cárdenas et al. (2012).

Among the multiple statistical approaches to evaluate and optimise monitoring networks, we apply here statistical indexes tied to Shannon’s information theory (Shannon, 1948) and Kullback–Leibler divergence (Kullback, 1959), in particular, those derived from the concepts of information gain and mutual information. The novelty is that we use both concepts in a complementary manner and in a normalised version considering what we call information gain or ‘representativity’, and mutual information or ‘specificity’ indexes. The information gain index relates to the contribution of a station to the total information of a network (‘representativity’), while the mutual information index refers to the amount of information provided by a single station that cannot be retrieved from other stations in a network (‘specificity’). Using solely one of these

*Corresponding author.
email: axosses@dim.uchile.cl

indexes results in misleading conclusions and they must be applied in a complementary way. We will illustrate the use of these concepts by applying them to air quality data collected in Santiago de Chile (33.5 S, 70.5 W, 500 m a.s.l.) between 1997 and 2010, where air pollution is an issue of concern, and where air quality monitoring has taken place since the late 1980s, and regularly within the framework of an attainment plan since 1997 (e.g. Gallardo et al., 2012a). The current network configuration is shown in Fig. 1 and described in Table 1. This air quality network was primarily conceived to address the compliance of air quality standards intended to protect the population from adverse health impacts. Today, it is still largely devoted to evaluate the compliance or not of air quality standards, particularly those related to inhalable particulate matter. Its ability to do so has been partially evaluated on the basis of statistical tools. Silva and Quiroz (2003) applied mutual information to classify the stations in Santiago, suggesting downtown stations as those that could be expendable if authorities wanted to re-distribute those stations. Gramsch et al. (2006) used principal component analysis and clustering techniques to identify groups of stations

with similar behaviour in terms of emission patterns. We revisit those analyses using more general indexes and currently available data in a larger set of air quality network stations.

The article is organised as follows. In Section 2, we review and define several statistical information indexes in a general setting. Section 3 describes the data sets considered in this study along with the main emission and circulation patterns of Santiago. Section 4 shows the application of ‘specificity’ and ‘representativity’ indexes. The evolution of the network between the late 1980s and the present in terms of information content is shown in Section 5. We perform clustering analysis using information distance in Section 6. Finally, summary and conclusions are presented in Section 7.

2. Statistical information indexes for network analysis

We present in this section some statistical information indexes for evaluating air quality monitoring networks based on the concept of relative information by Kullback

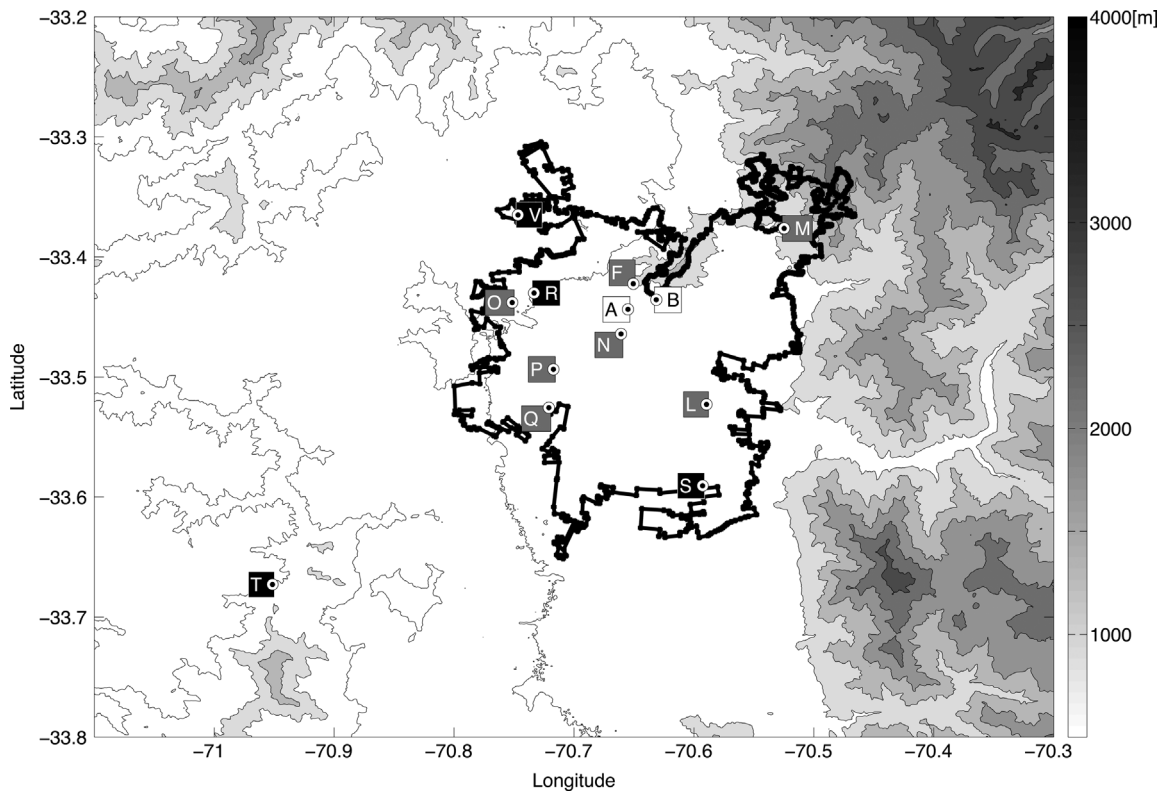


Fig. 1. Location of monitoring stations in Santiago’s air quality network since the 1980’s (for details see text). The symbols correspond to the names of the stations A: Gotuzzo, B: Providencia (not used in this study, in white), F: Independencia, L: La Florida, M: Las Condes, N: Parque O’Higgins, O: Pudahuel, P: Cerrillos, Q: El Bosque (seven stations continuously working on the period 1997–2008, in grey), R: Cerro Navia, S: Puente Alto, T: Talagante, V: Quilicura (four more stations added on the period 2009–2010, in black). The limit of the current urban area is indicated by a heavy line. Main topographic features of the Santiago basin are also shown.

Table 1. Description of the air quality monitoring stations belonging over time to Santiago’s monitoring network and the two periods of data used in this study.

Period and data used	Char	Name	Lon	Lat	Height	Type	Working	
			W	S	m a.s.l.			
2009–2010 (PM ₁₀ , PM _{2.5} , O ₃)	Not used { 1997–2008 (CO, PM ₁₀ , O ₃ , SO ₂)	A	Gotuzzo	70 655	33 444	576	Commerce/services	1988–1997
		B	Providencia	70 631	33 436	592	Close to main road/medium income	1988–2002
		F	Independencia	70 649	33 419	565	Commerce/services	Since 1988
		L	La Florida	70 586	33 513	594	Residential/low-medium income	Since 1997
		M	Las Condes	70 523	33 374	775	Residential/high income	Since 1988
		N	P. O’Higgins	70 658	33 461	545	In a park/close to highway	Since 1988
		O	Pudahuel	70 748	33 435	494	Residential/low income	Since 1997
		P	Cerrillos	70 713	33 493	511	Residential/industrial	Since 1997
		Q	El Bosque	70 664	33 544	582	Residential/industrial	Since 1997
		R	Cerro Navia	70 733	33 430	498	Residential/low income	Since 2008
		S	Puente Alto	70 593	33 591	680	Residential/low income	Since 2009
T	Talagante	70 951	33 673	401	Rural	Since 2009		
V	Quilicura	70 747	33 365	489	Residential/low-medium income	Since 2009		

and Liebler as described in Kullback (1959). More precisely, we introduce four indexes: (1) complementary relative mutual information or ‘specificity index’, (2) relative information or ‘representativity index’, (3) information gaps associated with the evolution of a network and (4) normalised information distance used in clustering analysis.

These indexes are all defined for arbitrary probability densities but we provide the formulas to compute them in the particular case of normally distributed densities. In fact, most of the information indexes presented here will be applied assuming that the underlying statistical densities of the measurements are log-normal so when we refer to the measurements in the normal case we implicitly mean the logarithm of the measurements. Notice that (see Table 2) other distributions could better fit the measurements, as is the case of gamma distributions, but no simple expressions for the Kullback–Liebler divergence for multivariable

gamma densities are known, except for the bivariate case (see e.g. Chatelain et al., 2008) even if it seems theoretically plausible (see Nielsen and Nock, 2010). Therefore, we only consider the log-normal multivariate case in this study.

All the aforementioned indexes can be derived from the Kullback–Liebler divergence or relative information of a distribution q_X with respect to other reference distribution p_X :

$$\text{KL}(p_X \parallel q_X) = \int p_X(x) \ln \frac{p_X(x)}{q_X(x)} dx, \quad (1)$$

where X represents the multivariate random vector of measurements and the integral is taken over all the possible outcomes x . Then, if there are n stations and m species, the previous integral is in $n \times m$ variables and it is difficult to compute in practice. In the normal case, $p_X \sim \mathcal{N}(\mu_0, \Sigma_0)$, $q_X \sim \mathcal{N}(\mu_1, \Sigma_1)$ with mean μ_0 , μ_1 and invertible covariance

Table 2. Relative quadratic error in percentage using different statistical models for fitting the 1997–2008 data for 7 stations and 4 measured species and for the 2009–2010 data for 11 stations and 3 measured species.

	Normal			Log-normal			Gamma		
	All	S	W	All	S	W	All	S	W
For fitting the 1997–2008 hourly data									
CO	26.9	24.1	18.1	14.9	23.9	10.9	5.17	8.07	4.66
O ₃	9.76	10.5	8.99	11.1	19.7	8.87	3.93	10.5	2.06
PM ₁₀	10.5	6.46	8.96	1.87	1.50	3.94	0.63	0.41	1.17
SO ₂	37.1	42.7	26.0	41.1	40.2	30.5	21.0	24.2	12.7
For fitting the 2009–2010 hourly data									
PM ₁₀	16.3	7.63	8.55	1.78	1.08	3.38	2.25	0.70	1.06
PM _{2.5}	9.84	4.69	9.59	1.36	1.49	2.29	0.71	0.48	0.95
O ₃	10.9	12.6	6.79	9.81	16.9	6.89	3.85	9.78	3.30

All data (All), segregated by summer (S: Dec, Jan, Feb) or winter (W: Jun, Jul, Aug) months.

matrices Σ_0, Σ_1 , the expression for $\text{KL}(p_X \parallel q_X)$ simplifies to

$$\frac{1}{2} \left(\text{tr}(\Sigma_1^{-1} \Sigma_0) - nm - \ln \frac{|\Sigma_0|}{|\Sigma_1|} + \Sigma_1^{-1} (\mu_0 - \mu_1)^2 \right), \quad (2)$$

where tr and $|\cdot|$ denote, respectively, the trace and determinant of the corresponding matrices and Ax^2 where A is a matrix and x is a vector is a short notation for the inner product $x^T Ax$. Notice that $\text{KL}(p \parallel q)$ is always non-negative (essentially since $\alpha - 1 - \ln \alpha \geq 0$ for $\alpha > 0$), invariant against any invertible transformation, non-symmetric and it vanishes only if $p_X = q_X$.

In the following sections, we consider n monitoring stations with measurements of m different species given by the vectors X_1, \dots, X_n and complementary measurement vectors X_1^c, \dots, X_n^c , where X_i^c represents the measurements of all the stations except for the i -th station. The total measurement vector of the whole network is then $X = (X_i, X_i^c)$ (rearranged in increasing index order) for any $i = 1, \dots, n$.

2.1. Mutual information and specificity index

The mutual information I_M^i between the station i and its complementary stations is given by

$$I_M^i = \text{KL}(p_X \parallel p_{X_i} p_{X_i^c}),$$

where $p_{X_i}, p_{X_i^c}$ are the marginal densities for the measurements of station i and its complement, respectively and p_X is the joint density distribution of all the measurements. If all the densities are normally distributed, $p_{X_i} = \mathcal{N}(\mu_{X_i}, \Sigma_{X_i})$, $p_{X_i^c} = \mathcal{N}(\mu_{X_i^c}, \Sigma_{X_i^c})$, $p_X = \mathcal{N}(\mu, \Sigma_X)$, with marginal covariance matrices $\Sigma_{X_i}, \Sigma_{X_i^c}$ and joint covariance Σ_X then the mutual information can be simply computed from (2) as follows:

$$I_M^i = -\frac{1}{2} \ln \frac{|\Sigma_X|}{|\Sigma_{X_i^c}| |\Sigma_{X_i}|}.$$

We define the *specificity index* s_i associated with the i -th station as the complementary relative mutual information given by (\max_j stands for the maximum over $j \in \{1, \dots, n\}$):

$$s_i = 1 - \frac{I_M^i}{\max_j I_M^j}, i = 1, \dots, n. \quad (3)$$

The specificity index measures how difficult it is to reproduce the measurements of the i -th station from the measurements of the other stations. We have $0 \leq s_i \leq 1$ and the station with highest specificity in the network corresponds to higher s_i (not necessarily 1) and the station with lowest specificity to the minimum s_i (always 0). The definition s_i is quite arbitrary since we could replace it by

any other decreasing function of I_M^i . For instance $s_i = \frac{\max_j I_M^j - I_M^i}{I_M^j - I_M^i}$ is another choice. We can also consider an index between 0 and 1 by defining (we use this choice to build Figs. 4, 5 and 7)

$$s_i = 1 - \frac{I_M^i - \underline{I}_M}{\bar{I}_M - \underline{I}_M}, I_M = \min_j I_M^j, \bar{I}_M = \max_j I_M^j.$$

In any case, we are interested in the ordering induced by this index which is independent of the decreasing function of I_M^i you may choose.

The definition we have chosen corresponds exactly to the concept of *effectiveness* already present in the literature (e.g. Pérez-Abreu and Rodríguez, 1996; Silva and Quiroz, 2003). Nevertheless, we consider that the denomination ‘effectiveness’ could lead to confusion. Indeed, the index s_i is a relative measure of information and it does not consider the total information of the network itself as it was already noticed in Bocquet (2009). Hence, a complementary index taking into account this intrinsic information of the network should be introduced to better evaluate if an station is effective or not. Following this remark, we introduce a new index in the next subsection.

2.2. Information gain and representativity index

If we represent by the densities $q_{X_i^c}$ and p_X the situations before and after the measurements X_i are known, then the *information gain* I_G^i achieved by the measurements of the i -th station is defined by

$$I_G^i = \text{KL}(p_X \parallel q_{X_i^c}).$$

Notice that, in order to model $q_{X_i^c}$, we will need some a priori background information about the measurements at the i -th station. Let us precise this statement for the normal case. We take $p_X = \mathcal{N}(\mu_X, \Sigma_X)$ as in the previous section and, if μ_{b_i} and B_i are some a priori background mean and covariance that characterise the situation without knowledge at the i -th measurement site, we choose $q_{X_i^c} = \mathcal{N}(\mu_i', \Sigma_i')$ where $\mu_i' = (\mu_{b_i}, \mu_{X_i^c})$, $\Sigma_i' = \text{diag}(B_i; \Sigma_{X_i^c})$ denote the mean and diagonal by block’s covariance matrix with increasing ordering of indexes. With this, using that $\text{tr}((\Sigma_i')^{-1} \Sigma_X) = \text{tr}(B_i^{-1} \Sigma_{X_i}) + m(n-1)$ from (2) we obtain

$$I_G^i = \frac{1}{2} (\text{tr}(B_i^{-1} \Sigma_{X_i}) - m) - \ln \frac{|\Sigma_X|}{|\Sigma_{X_i^c}| |B_i|} + B_i^{-1} (\mu_{X_i} - \mu_{b_i})^2. \quad (4)$$

Notice that if $\mu_{b_i} = \mu_{X_i}$ and $B_i = \Sigma_{X_i}$, then one can reproduce from the previous formula the expression for mutual information.

Notice that in our applications, the interesting case corresponds to

$$\alpha = \frac{|\Sigma_X|}{|\Sigma_{X^c}| |B_i|} < 1$$

(reduction of uncertainty after the i -th-station is gauged) so we could also define the information gain as $I_G^i = \frac{1}{2}(-\ln \alpha + B_i^{-1}(\mu_{X_i} - \mu_{b_i})^2)$ with a similar behaviour. Moreover, we could also select the simpler and classical definition $I_G^i = -\frac{1}{2} \ln \alpha$ (entropy decrease or Shannon information increase). Nevertheless, in practice, we found useful to include the term $B_i^{-1}(\mu_{X_i} - \mu_{b_i})^2$ giving more representativity to measurements with high averages (μ_{b_i} will be taken to be of zero mean value) and this naturally arises from Kullback–Liebler divergence. In this sense, the approach chosen in this study based on the definition of information gain from Kullback–Liebler divergence is near but not totally equivalent to the so-called entropy-based network design methods introduced by Zidek and collaborators (see Caselton and Zidek, 1984; Le and Zidek, 2006; Ainslie et al., 2009 and references therein).

We define the *representativity index* r_i of the i -th station as the relative information gain by

$$r_i = \frac{I_G^i}{\max_j I_G^j}, \quad i = 1, \dots, n. \quad (5)$$

The representativity index r_i represents the relative information gain after adding the i -th station to the network. This definition is also arbitrary and can be replaced by another increasing function of I_G^i . For instance, in order to have an index between 0 and 1 (we use this choice to build Figs. 4, 5 and 7) we could take

$$r_i = \frac{I_G^i - \underline{I}_G}{\bar{I}_G - \underline{I}_G}, \quad \underline{I}_G = \min_j I_G^j, \quad \bar{I}_G = \max_j I_G^j.$$

In any case, we are interested in the ordering induced by this index which is independent of the increasing function of I_M^i you may choose.

Concerning the background mean and covariance, in this work we will simply take

$$\mu_{B_i} = (\mu_{i1}, \dots, \mu_{im}) \text{ and } B_i = \text{diag}(\sigma_{b,i1}^2; \dots; \sigma_{b,im}^2).$$

where μ_{ij} and $\sigma_{b,ij}$ are a priori mean and standard deviations of the measurements of the j -th species in the i -th station.

Notice that other choices are possible. For instance, one could take into account the knowledge about the spatial distribution of the measuring sites by estimating the background values for the i -th measurement site as the optimal interpolation obtained from all other stations where geostatistical or other dispersion space embedding methods can be introduced (see Ainslie et al., 2009). This

aspect is beyond the scope of this study, and for the sake of simplicity, we decided to introduce our indexes using diagonal covariance matrices. Nevertheless, in order to illustrate the importance of this point, we consider in the last sections a different choice of a priori covariances estimated from Barnes-type interpolation for a single species.

More generally, we can compute the information gain I_G^K associated with a subset of stations $K \subset \{1, \dots, n\}$ of cardinality k by

$$I_G^K = \text{KL}(p_X \parallel q_{K^c}) = \frac{1}{2} \left(\sum_{j \in K} \text{tr}(B_j^{-1} \Sigma_{X_j}) - mk \right) - \ln \frac{|\Sigma_X|}{|\Sigma_{K^c}| \prod_{j \in K} |B_j|} + \sum_{j \in K} B_j^{-1} (\mu_{X_j} - \mu_{b_j})^2,$$

where the density q_{K^c} represents the situation of the network with the complementary stations K^c . In the normal case, $q_{K^c} = \mathcal{N}(\mu', \Sigma')$ where $\mu' = (\{\mu_{b_j}\}_{j \in K^c}, \mu_{K^c})$ and $\Sigma' = \text{diag}(\{B_j\}_{j \in K^c}; \Sigma_{K^c})$, where μ_{K^c} y Σ_{K^c} are obtained after eliminating all the components of μ_X and all the rows and columns of Σ_X associated with K , and μ_{b_j} , B_j are background mean and covariance matrices associated with each station in K as before.

2.3. Evolution of total information and information gaps

Suppose we change the active monitoring stations in the network from K_1 to K_2 , both subsets of $\{1, \dots, n\}$ with cardinalities k_1 and k_2 , and that we represent the situations before and after this change by the densities q_{K_1} and q_{K_2} . We define the *information gap* or change associated with this evolution by

$$\Delta I^{K_1, K_2} = \text{KL}(p_X \parallel q_{K_1}) - \text{KL}(p_X \parallel q_{K_2}) = I_G^{K_1} - I_G^{K_2}. \quad (6)$$

Notice that the information gap can be positive or negative and it is additive, that is, $\Delta I^{K_1, K_2} + \Delta I^{K_2, K_3} = \Delta I^{K_1, K_3}$. In the particular case where $K_1 \subseteq K_2$ and the measurements are normally distributed the information gain is exactly the (non-negative) quantity $\text{KL}(q_{K_2} \parallel q_{K_1})$. This is true if the a priori information does not change after changing the configuration of the network, otherwise (6) is more general.

Using this concept, we can compute the successive gaps or changes in information content over the evolution of a network on the basis of the data corresponding to the final configuration of n stations (see Fig. 2). Thus, in order to compare past and present configurations of the network we can use current measurements.

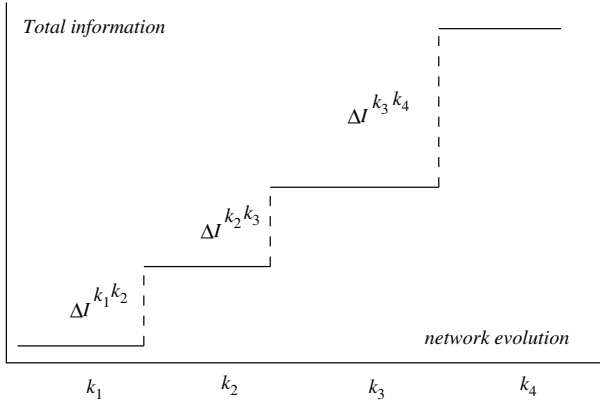


Fig. 2. Schematic evolution of the total information of the network.

2.4. Normalised information distance and clustering

The mutual information between two stations i and j is given by

$$I_M^{ij} = \text{KL}(p_{X_i, X_j} \parallel p_{X_i} p_{X_j}). \quad (7)$$

The *normalised information distance* between two stations i and j is defined as in Coeurjolly et al. (2007):

$$d_{ij} = 1 - \frac{I_M^{ij}}{\max(H_i, H_j)}, \quad (8)$$

where $H_i = -\sum_x p_{X_i}(x) \ln p_{X_i}(x)$ is the Shannon entropy of the measurements X_i . This distance is zero only if p_{X_i} and p_{X_j} are independent and it is equal to one if $i=j$. Notice that in the normal case, for one species, we have

$$I_M^{ij} = -\frac{1}{2} \ln \frac{\sum_{ii} \sum_{jj} - \sum_{ij}^2}{\sum_{ii} \sum_{jj}} = -\frac{1}{2} \ln(1 - \rho_{ij}^2),$$

where ρ_{ij} is Pearson's correlation coefficient. Thus, the normalised information distance d_{ij} is strongly related to Pearson's distance $1 - \rho_{ij}^2$. But, for non-normal distributions zero correlation does not imply independence and zero mutual information does. Therefore, since (7) and (8) are easy to compute without assuming any normality, it is always better to use the normalised information distance d_{ij} instead of Pearson's distance for measuring statistical independence, notably, when performing clustering analysis of the network stations, where the normal or log-normal fit of data is only approximate.

3. Santiago's characteristics

The city of Santiago is located in a semi-arid basin (annual rainfall less than 350 mm) in the central part of Chile bounded by the Andes Cordillera (4500 m altitude on average) to the East, a lower parallel mountain range to the

West (1500 m altitude on average), and two east-to-west mountain chains to the North and South of the basin, respectively. The climate of Santiago is characterised by the quasi-permanent influence of the subtropical Pacific high, and the intrusion of occasional cold fronts, which bring precipitation in wintertime. The South Pacific high determines quasi-stagnant anti-cyclonic conditions that are further intensified, especially in fall and winter by the presence of sub-synoptic features known as coastal lows (e.g. Gallardo et al., 2002; Garreaud et al., 2002). There is a characteristic thermally driven circulation that defines up-slope south-westerly winds in the afternoon and down-slope north-easterly winds in the night and morning hours, more strongly so in summer (e.g. Saide et al., 2011).

The regional office of the Ministry of Health was in charge of monitoring Santiago's air quality from the late 1980s until 2011. Nowadays, this activity is continued by the recently created Ministry for the Environment. A historic record of the data (1988–2008) is available (as in September 2012) on the internet via the Chilean Ministry of Health at <http://www.seremisaludrm.cl> and <http://www.asrm.cl>. A copy of those data and of data collected in stations currently in operation can be found at the web page of the Chilean Ministry for the Environment at <http://sinca.mma.gob.cl>. Instruments and quality control procedures of the Santiago monitoring network follow recommendations from the Environmental Protection Agency of the United States of America, and are subject to public scrutiny and to occasional external review panels.

The specific air quality standards applied over time in Santiago can be found elsewhere in the literature (e.g. Zhu et al., 2012) that synthesises the situation in various megacities, including South American cities and Santiago.

The species measured are so-called criteria pollutants: carbon monoxide (CO), sulphur dioxide (SO₂), ozone (O₃) and partially inhalable particles (PM₁₀). Since 2000, nitrogen oxides are measured at three stations, and fully inhalable particles (PM_{2.5}) at four stations. In the current configuration all species are measured at all stations. Wind velocity, temperature, relative humidity are also continuously measured at the monitoring stations. The network's configuration is shown in Fig. 1. In sum, there are seven stations (F, L, M, N, O, P and Q) for which rather continuous and simultaneous time series are available for the period between 1997 and 2008 for carbon monoxide (CO), sulphur dioxide (SO₂), ozone (O₃) and partially inhalable particles (PM₁₀). We will restrict the analyses of 'specificity' and 'representativity' to this set of data. Evolution and clustering will consider PM₁₀, PM_{2.5} and ozone data collected in the current network configuration, that is, for 11 stations (F, L, M, N, O, P, Q, R, S, T and V) operating in 2009 and 2010. We provide some basic

Table 3. Main statistics (mean, standard deviation and maximum) for each of the 7 monitoring stations working during the period 1997–2008 based on hourly averages during all the year (All), summer (S: Dec, Jan, Feb) and winter (W: Jun, Jul, Aug).

Species		F	L	M	N	O	P	Q	
CO (ppb)	All	1.2	1.2	0.7	1.6	1.1	1.4	1.2	
		1.1	1.2	0.5	1.7	1.4	1.4	1.3	
		5.5	6	2.8	8.6	8.8	6.7	6.9	
	S	0.5	0.6	0.4	0.6	0.4	0.5	0.6	
		0.4	0.4	0.2	0.5	0.3	0.5	0.5	
		4.4	5.1	1.9	5.7	4.1	4	6.7	
	W	1.8	1.9	1.0	2.2	1.8	1.9	1.9	
		1.2	1.4	0.6	1.9	1.8	1.6	1.6	
		5.5	6	2.8	8.6	8.8	6.7	6.9	
	O ₃ (ppb)	All	19.6	21.2	24.9	23.1	19.0	20.1	20.3
			17.0	20.0	24.4	18.6	15.9	16.5	16.3
			71	82	106	78	64	69	66
S		23.3	27.1	33.4	27.2	23.3	24.7	24.4	
		18.4	21.7	27.9	19.3	16.6	17.0	17.2	
		71	82	106	78	64	69	66	
W		12.4	12.5	13.7	14.9	11.8	12.6	12.9	
		11.4	13.4	13.8	13.9	11.6	12.3	11.6	
		71	82	106	78	64	69	66	
PM ₁₀ (µg/m ³ N)		All	72.1	80.9	56.7	74.2	77.8	75.9	80.3
			43.5	53.8	36.7	50.6	58.4	52.7	54.9
			244	309	197	288	359	293	312
	S	57.7	68.5	54.3	57.7	62.6	64.4	66.5	
		28.2	34.0	29.1	30.8	36.8	38.2	33.7	
		239	309	196	286	358	293	290	
	W	88.3	94.4	57.9	92.6	95.9	90.9	94.7	
		52.6	67.2	43.2	61.9	73.6	63.6	67.8	
		244	309	197	288	359	293	312	
	SO ₂ (ppm)	All	4.97	4.46	3.43	5.02	4.1	4.96	5.05
			3.4	3.3	2.1	3.7	2.7	3.4	3.8
			22	23	14	23	16	21	27
S		4.0	3.6	3.0	3.8	3.2	3.8	4.3	
		2.6	2.8	1.9	2.8	2.0	2.5	3.6	
		22	23	14	23	16	21	27	
W		6.3	5.2	3.9	6.4	5.1	6.5	5.9	
		4.0	3.6	2.3	4.3	3.1	3.9	4.0	
		22	23	14	23	16	21	27	

descriptive statistics for each measured species at each station (see Tables 3 and 4).

We applied various quality control checks to the data. After a careful visual inspection of the time series, extreme values were suppressed from the database by excluding the 1 percentile upper and lower tails of the distribution of the logarithm of the values. The time series were also checked with respect to the detection limit of the instruments, and we removed the values lower than twice the lower instrument detection limit, which is nevertheless usually below the lower 1-percentile cut.

We also replaced isolated missing values by the corresponding average concentration of that hour for that season of that year and station (in any case this is only around 0.5% of the data). Table 5 describes the data set before and after applying the filtering and cleansing procedures mentioned earlier.

4. Specificity and representativity analysis of the network (1997–2008)

As discussed before, the definition of the statistical concepts to be used here does not depend on the statistical distributions of the data. However, the computation of the indexes becomes much simpler when normal or log-normal distributions are assumed. For simplicity, we will calculate the statistical indexes assuming log-normal distributions for all data. We explored the actual data distributions by fitting statistical models to the data. The results are shown in Table 2 and see also Fig. 3. The log-normal distribution fits the collected data better than ca. 20% relative quadratic error for all species except sulphur dioxide. We attribute this misfit to an unfortunate rounding procedure applied to the data by the network operators possibly due to the low absolute values currently measured in Santiago (less than

Table 4. Main statistics (mean, standard deviation and maximum) for each of the 11 monitoring stations working during the period 2009–2010 based on hourly averages during all the year (All), summer (S: Dec, Jan, Feb) and winter (W: Jun, Jul, Aug).

Species		F	L	M	N	O	P	Q	R	S	T	V
O ₃ (ppb)	All	17.0	18.4	19.2	21.9	15.2	18.6	16.3	16.0	20.1	17.1	16.1
		16.0	18.2	20.4	17.0	14.6	15.5	15.0	14.9	16.5	11.7	15.5
		66	73	88	69	59	64	60	60	65	51	63
	S	21.5	25.3	28.0	26.0	21.0	24.3	21.8	21.3	25.2	18.6	22.1
		17.8	20.5	24.1	18.0	16.0	16.6	16.9	15.9	17.6	11.7	16.7
		66	73	88	69	59	64	60	60	65	51	63
	W	8.6	9.4	8.8	13.0	8.2	10.7	9.0	8.2	12.3	12.6	8.0
		8.5	9.6	9.2	10.3	8.5	9.2	8.2	8.3	11.0	9.9	8.9
		62	68	67	67	54	63	60	58	64	50	61
PM ₁₀ (µg/m ³ N)	All	50.1	57.1	45.7	55.8	48.3	58.9	61.9	52.3	49.5	37.4	73.3
		22.8	24.2	22.1	26.5	23.2	28.5	27.4	24.8	21.4	20.5	39.2
		161	215	143	206	244	199	210	292	158	142	285
	S	50.1	57.1	45.7	55.8	48.3	58.9	61.9	52.3	49.5	37.4	73.3
		22.8	24.2	22.1	26.5	23.2	28.5	27.4	24.8	21.4	20.5	39.2
		161	215	143	206	244	199	210	292	158	142	285
	W	69.3	79.1	46.8	80.7	81.5	74.9	79.4	88.2	55.4	51.7	83.3
		36.5	54.6	29.7	49.0	58.9	44.3	53.9	65.2	33.5	34.8	55.5
		174	268	146	234	271	204	248	295	164	156	289
PM _{2.5} (µg/m ³ N)	All	26.5	27.5	21.6	27.4	27.1	27.9	28.5	28.6	24.73	20.4	27.0
		14.7	16.1	12.1	17.8	22.2	19.5	21.1	25.9	14.4	16.3	18.5
		77	90	66	96	136	108	127	162	79	88	104
	S	20.4	24.8	20.4	21.4	20.0	19.7	21.9	18.1	20.7	14.1	21.2
		9.2	12.2	10.4	10.8	10.6	9.8	11.1	10.1	10.2	9.5	11.6
		60	86	66	92	136	104	100	141	77	87	98
	W	35.1	33.5	23.8	37.3	39.9	39.9	37.8	44.7	30.0	31.2	35.9
		16.7	19.2	14.2	21.3	29.9	24.2	27.4	35.1	17.2	20.6	22.1
		77	90	66	96	136	108	127	162	79	88	104

ca. 5 ppbm annual average). Notice that the data are generally well described by other statistical models as it is the case of gamma distributions, but, to our knowledge, simple expressions for (1) in the multivariate gamma case are not known, although mutual information (7) and distance (8) can still be easily computed for arbitrary distributions. All in all, the assumption of log-normal distributions seems justified for all species except for SO₂.

From the filtered data, we computed the ‘specificity’ and ‘representativity’ indexes according to their definitions (3) and (5) for each monitoring station. First, we consider a univariate analysis per species, per season, year-to-year and for all years (1997–2008). We then repeat this analysis considering a multivariate approach for all species at once. We use hourly averaged data. We explored other averaging windows finding similar results (not shown).

4.1. Univariate analysis

For species CO, O₃, PM₁₀ and SO₂ separately (univariate), we choose for the ‘representativity’ index calculation (see Section 2.2) background mean $\mu_{b_i} = (\mu_{i1}, \dots, \mu_{im})$, where μ_{ij} are chosen such that $\exp \mu_{ij} \approx 0$ (recall we work

Table 5. Percentage of available hourly data considering 7 stations (period 1997–2008) and 11 stations (period 2009–2010) for all years and months (All), summer (S: Dec, Jan, Feb) and winter (W: Jun, Jul, Aug).

Species		All	S	W
Period 1997–2008				
CO	% original data	95	92	98
	% after filtering	70	52	87
O ₃	% original data	96	94	97
	% after filtering	68	79	55
PM ₁₀	% original data	96	94	99
	% after filtering	94	93	94
SO ₂	% original data	91	90	92
	% after filtering	70	62	78
Period 2009–2010				
PM ₁₀	% original data	98	99	99
	% after filtering	96	98	95
PM _{2.5}	% original data	98	98	99
	% after filtering	96	97	94
O ₃	% original data	93	93	90
	% after filtering	79	86	72

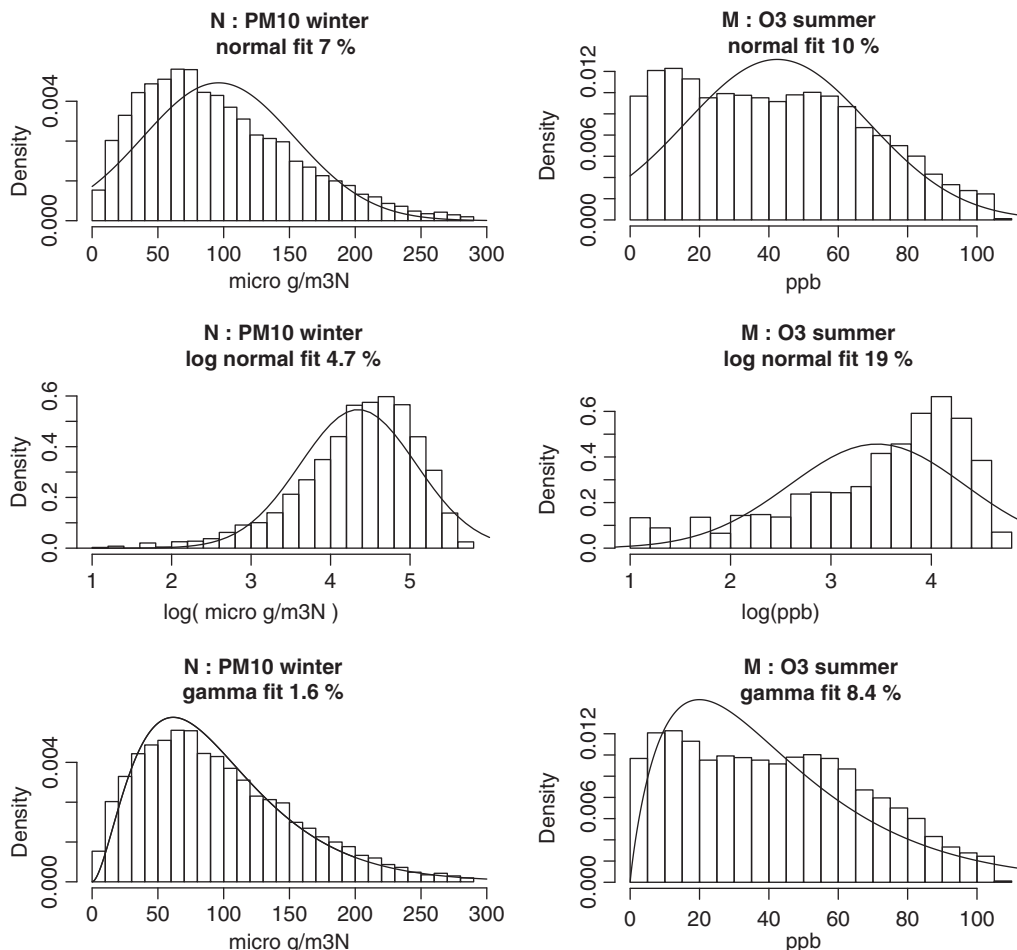


Fig. 3. Example of some statistical fitting. PM_{10} in winter for station N and O_3 for stations M for normal (top line), log-normal (middle line) and gamma (bottom line) fitting. The relative quadratic error is indicated on each case.

with the log of the data) and background covariance $B_i = \text{diag}(\sigma_{b,i}^2; \dots; \sigma_{b,im}^2)$ with $\sigma_{b,ij} = 2 \max_i \sqrt{\Sigma_{ii,j}}$, where $\Sigma_{.j}$ is the j -th block of the full covariance matrix corresponding to the j -th species. Again, this choice is subject to improvement by considering other a priori information such as spatial distribution of pollutants and stations obtained by linear interpolation, kriging, dispersion models, and so on. The ‘specificity’ index calculation (see Section 2.1) does not need any background information.

Furthermore, we split the analysis by considering only summer (Dec, Jan, Feb), winter (Jun, Jul, Aug) or the whole year for all hourly data for the period 1997–2008. The resulting ‘specificity’ and ‘representativity’ indexes for the univariate case considering all data for the 1997–2008 period are illustrated for the summer and winter periods in Figs. 4 and 5. For all species and seasons, station M shows the highest ‘specificity’. This is consistent with the location of the station in a high-income area of the city where

emissions patterns are different from elsewhere in Santiago and they consist of mostly residential sources and light duty vehicles (e.g. Gallardo et al., 2012b). Furthermore, this station is located at higher altitude (ca. 700 m a.s.l.) than other stations of the network in a relatively narrow canyon to the north-east of the basin. These characteristics make this station rather unique and thereby ‘specific’. Station El Bosque (Q) and other west located stations (O, P) are the second most specific stations at least with respect to sulphur dioxide in winter and PM_{10} in summer. Around station Q there are industries including smaller smelters that co-exist with a low-income area of the city, which explains the specific behaviour in terms of sulphur dioxide.

The ‘representativity’ index is linked, on the one hand, to the precision of the measurements (quantified by the inverse of the variance), and, on the other hand, by the magnitude of the measured values. Hence, in summer,

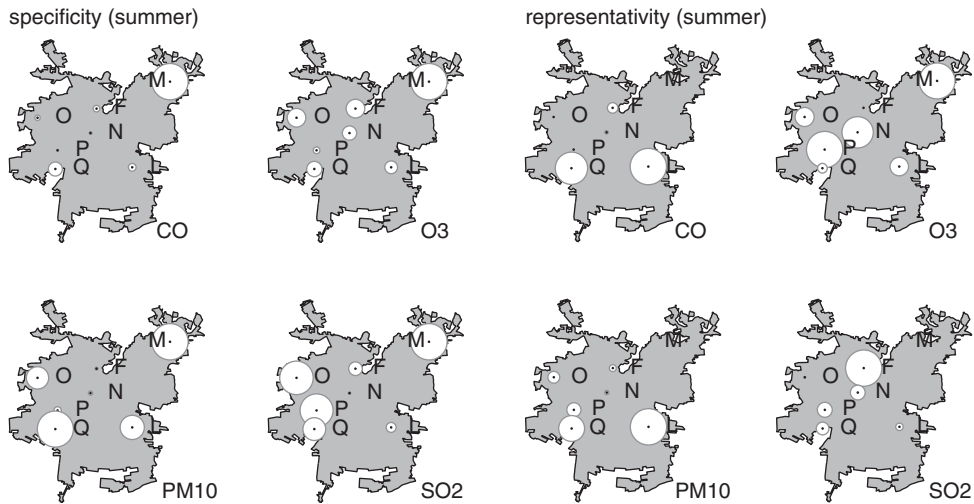


Fig. 4. Specificity (left) and representativity (right) for the univariate case for CO, O₃, PM₁₀, and SO₂ for summer for seven stations during 1997–2008. The larger the circle, the larger the index.

ozone shows highest ‘representativity’ at M where magnitudes and variances are persistently large, and at P and N where magnitudes and variances are persistently small. Notice that M shows high ‘representativity’ only for ozone in summer when the signal’s magnitude dominates over its lack of precision (large variance). Other species show no clear pattern in summer since the measured values have small magnitudes and large variances. In winter, the highest ‘representativity’ indexes for all species are found in downtown stations, mainly N and F, located in a relatively flat area of the Santiago basin. Here, signals show high

magnitude and variance for tracers largely associated with mobile sources.

We also compute the evolution of the ‘specificity’ and ‘representativity’ indexes from year-to-year, performing the calculations for successive summers, winters and for every year. The results for PM₁₀ in winter and O₃ in summer are depicted in Fig. 6. Notice that, for PM₁₀, the north-eastern peripheral station M shows the highest ‘specificity’ for both species in all years whereas downtown stations display the highest ‘representativity’. Similar results are found for other species CO and SO₂ (not shown). The situation is

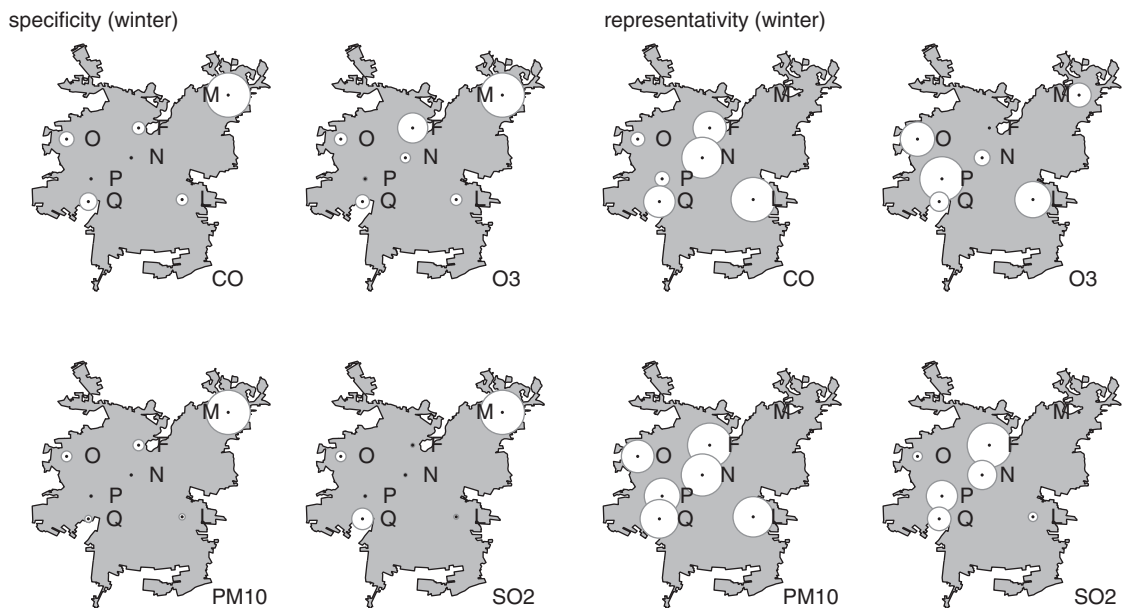


Fig. 5. Specificity (left) and representativity (right) for the univariate case for CO, O₃, PM₁₀ and SO₂ for winter for seven stations during 1997–2008. The larger the circle the larger the index.

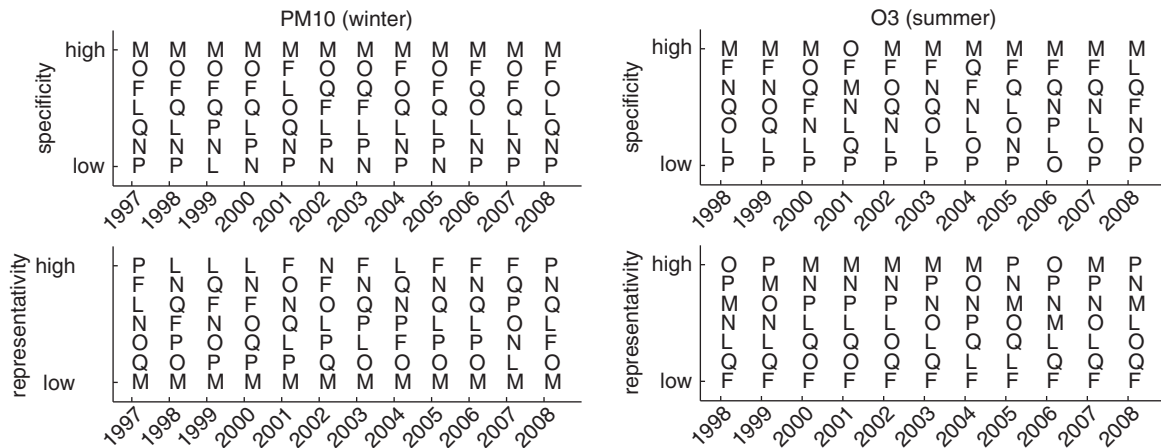


Fig. 6. Evolution of ‘specificity’ (upper panels) and ‘representativity’ (lower panels) indexes for PM₁₀ in winter and O₃ in summer respectively. See text for details.

only different for O₃ in summer: downtown stations and station M share high ‘representativity’ indexes. In other words, the classification is robust, stable in time and consistent with the east–west gradients in emissions and the east–west circulation pattern characteristic of Santiago. It is worth pointing out that these indexes can be viewed as dynamic indicators of the network since they continuously change according to each pollutant, temporal and spatial distribution of emissions and precursors, and circulation patterns. This could be relevant when using these indexes for analysing a network within the framework of defining long-term policies and curbing measures.

4.2. Multivariate analysis

The corresponding results for the multivariate case are shown in Fig. 7. Again, station M has the highest ‘specificity’. In general, downtown stations show highest ‘representativity’ indexes in winter. In summer, stations L and M are displayed as most representative of the overall behaviour of the network. We attribute this to the fact that the most prominent summer pollutant is the photochemically driven ozone, which maximises in the afternoon hours in the eastern-bound stations. In winter, changes in boundary layer height are primarily driven by solar radiation affecting the development of the mixing layer with nearly-collapsed conditions in nighttime that result in extremely high concentrations of particles and primary pollutants in the stations to the west of the basin (see Saide et al., 2011). Photochemical pollutants are also present in winter but to a lesser extent than in summer. Hence the ‘representativity’ of the stations is strongly modulated by emission and insolation cycles. Notice that station N, located in a relatively flat area of the basin, shows persistently a high ‘representativity’ index in the multivariate case. In this

sense, this is the least expendable station of all contrary to what a pure mutual information analysis would suggest (e.g. Silva and Quiroz, 2003).

5. Evolution analysis

First, we analyse the evolution of the total information of the network by computing the information gaps given by (6) for the network by 1988 consisting of three stations (F, N and M), then considering seven stations when the largest expansion of the network occurred in 1997. We then estimate the changes due to the addition of station R, and finally we address the expansion to peripheral stations V, S and T by 2009. We do the same choice of background mean and covariances as in Section 4. The results are shown for fully inhalable particles in Fig. 8 using the hourly data of PM_{2.5} from the network of 11 stations for the period 2009–2010. The increase in total information estimated for the network is roughly proportional to the number of monitoring stations added, and does not take into account their spatial distribution. This feature follows from the simple choice of a priori background mean and covariances. A different choice based on more sophisticated interpolation techniques such as kriging or air quality modelling (e.g. Wu and Bocquet, 2011) may improve the way in which the evolution of the network is quantified. This is beyond the scope of this study, but we give some insights about these techniques in the next sections.

In order to have an idea of the influence of the choice of the a priori variables in the calculations we used a very simple interpolation technique [more precisely what is called the first step of Barnes interpolation, Barnes, 1964] as an alternative method to estimate the a priori mean μ_b and covariances B_i at each step of the evolution of the network. More precisely, from measurements z_k at points

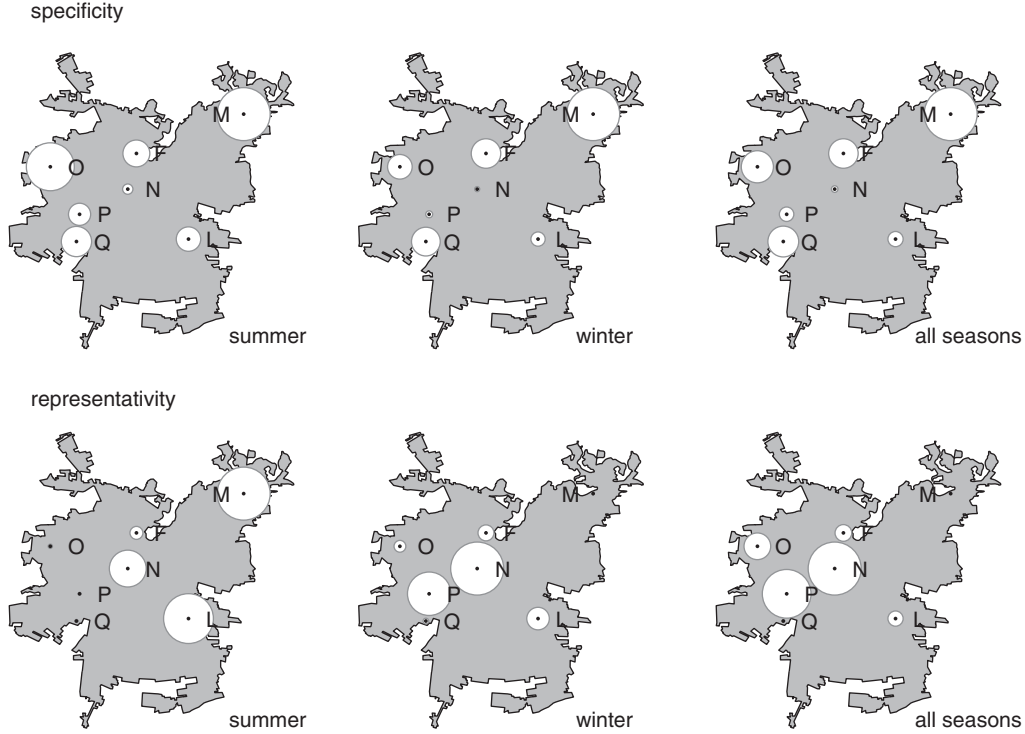


Fig. 7. Multivariate specificity (top) and representativity (bottom) indexes for simultaneously CO, O₃, PM₁₀ and SO₂ for hourly data for the period 1997–2008 separately for summer, winter and all seasons.

(x_k, y_k) we infer measurements \hat{z}_i at site (x_i, y_i) by the weighted mean

$$\hat{z}_i = \frac{\sum_k w_{ik} z_k}{\sum_k w_{ik}}, \quad w_{ik} = \exp\left(-\frac{(x_i - x_k)^2 + (y_i - y_k)^2}{L}\right),$$

where L is a characteristic length related to the discretisation step δ . Using the data of the network corresponding to some given year, we interpolate values at other potential network sites and we can easily compute the corresponding a priori mean and covariances from the interpolated data. More precisely, if μ_k and Σ_{kl} are the mean at point (x_k, y_k) and covariances between points (x_k, y_k) and (x_l, y_l) of the current network, the mean at point (x_i, y_i) and covariances between points (x_i, y_i) and (x_j, y_j) of the interpolated network can be obtained by

$$\hat{\mu}_i = \frac{\sum_k w_{ik} z_k}{\sum_k w_{ik}}, \quad \hat{\Sigma}_{ij} = \frac{\sum_k \sum_l w_{ik} w_{il} \Sigma_{kl}}{\sum_k w_{ik} \sum_l w_{jl}}.$$

From this we extract the background information μ_{b_i} and B_i . This is a simple and easy to implement method that takes into account the spatial distribution of the stations (see Fig. 9 computed with $L = 10,104 \delta^2/\pi$ and $\delta = 0.0133^\circ$ in a 50×50 grid). Notice also that Barnes interpolation converges to the nearest neighbour interpolation for small values of L when it is compared with the domain size.

To simplify the analysis, in a first approximation we can neglect covariances and we compute the new mean and just the new variances given by $\hat{\Sigma}_{ii} = \frac{\sum_k w_{ik}^2 \Sigma_{kk}}{(\sum_k w_{ik})^2}$. With this, we can obtain the information gaps directly using (2) where μ_1, Σ_1 and μ_0, Σ_0 correspond to the mean and variances estimated

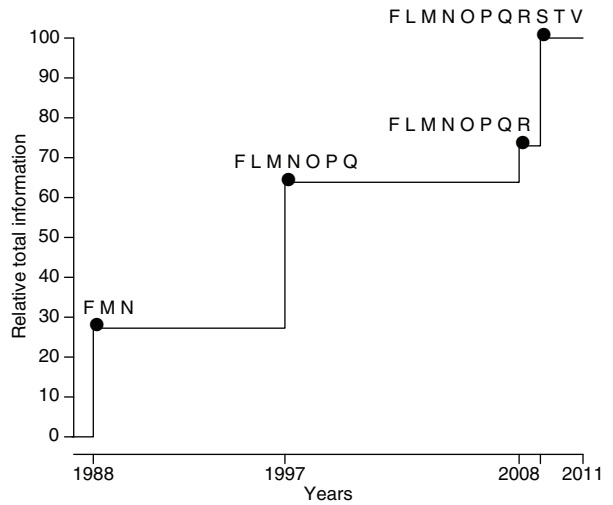


Fig. 8. Evolution of total information content of the air quality monitoring network in Santiago since the late 1980s relative to the current situation, considering PM_{2.5}.

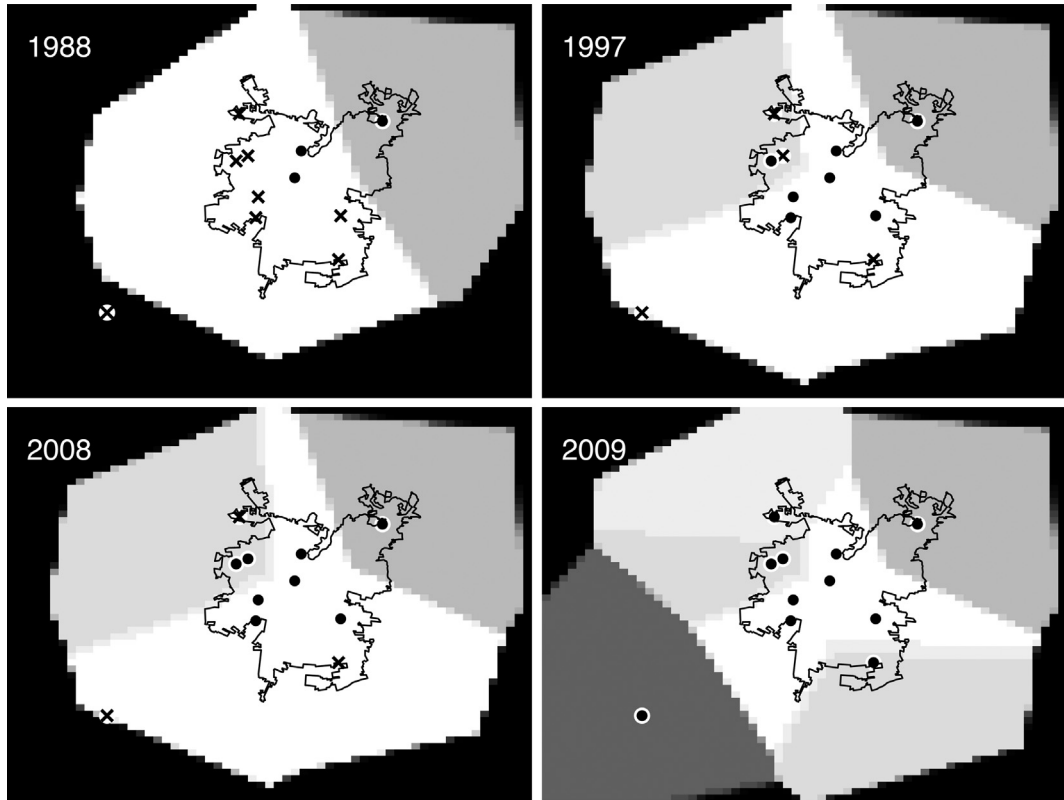


Fig. 9. Simulated interpolation of the measurements at some sites (x) from the available network (•) using Barnes interpolation (here for some typical log concentrations of PM₁₀ in greyscale, lighter = higher). To localise, we put 12 phantom zero measurement stations around the boundary. This allows to better estimate the a priori mean μ_b , and covariances B_i for the evolution of network total information taking into account the spatial distribution.

by interpolation before and after a change according to the new network distribution. As expected, we can see from Fig. 10, when compared to Fig. 8 that the addition of station R to the network has only a small influence on the total PM_{2.5} information since the new station R was very close to the already existing station O in the previous network. A similar situation can be verified for PM₁₀ (not shown).

Further analysis concerning the choice of a priori information without neglecting covariances requires applying other interpolation techniques such as kriging or dispersion modelling, which is beyond the scope of this work. We are currently working on this as this provides a way to select new observational sites.

For example, in Fig. 11, we see the total information gain obtained at each point of a spatial grid surrounding the stations, if we add a new virtual station with Barnes’s interpolated measurements at this point, and we recompute the total information after considering this new station. So we could try to add stations in the regions with highest information gain. Of course, these type of analysis are limited, and the use of more sophisticated dispersion and

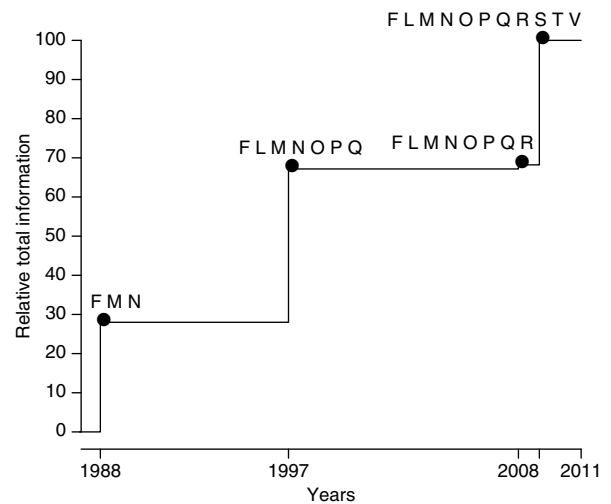


Fig. 10. Evolution of total information content of the air quality monitoring network in Santiago since the late 1980s relative to the current situation, considering PM_{2.5} using Barnes interpolation a priori information.

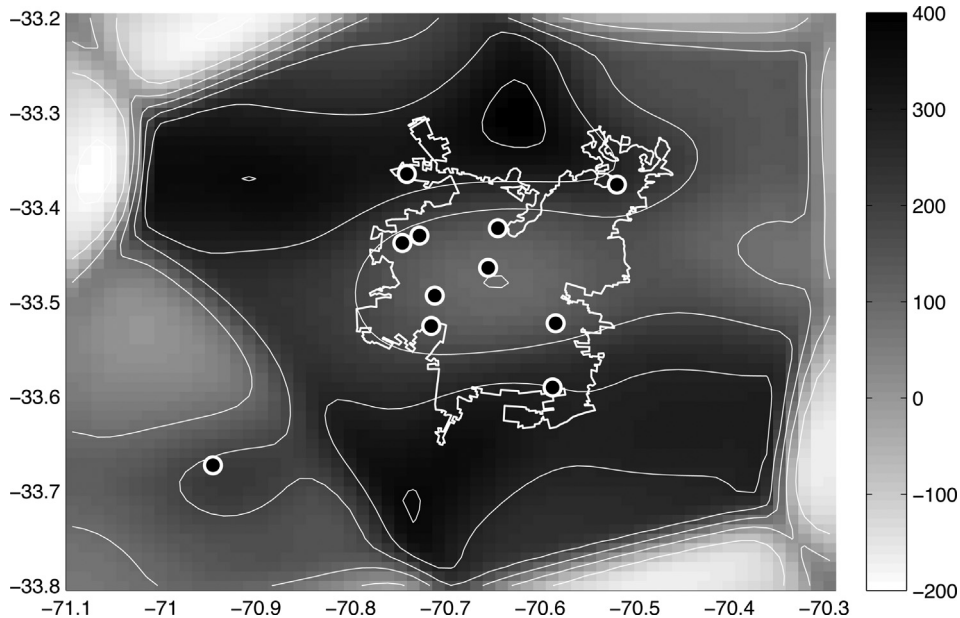


Fig. 11. Information gain map. At each point, the difference in information gain obtained by comparison of the total information gain of the original network and the total information gain obtained for a new network after adding a new station at this point with Barnes's interpolated values is indicated.

chemistry modelling is needed, so this should be the subject of further study.

6. Clustering analysis

We perform hierarchical clustering analysis of the network for 11 stations of $PM_{2.5}$ and PM_{10} hourly data in 2009–2010 and O_3 hourly data in 2009 using the normalised information distance defined in (8) without any normality assumption. The results of the clustering are depicted in Fig. 12. We select six clusters that are the same for particulate matter: M, T, Q, [L, S], [F, N], [V, P, O, R] and different for ozone: M, T, [L, S], [F, Q], [N, P], [V, O, R]. Similar results for particulate matter can be obtained by using Pearson's distance (see Section 2.4), after taking the logarithm of data, but they are slightly different for ozone. This is not surprising since both distances are related in the normal case, and from Table 2, we see that the log-normal adjustment is better for particulate matter than for ozone. This example illustrates that information distance is more robust than Pearson distance for other data distributions. Notice that we also checked k -means clustering analysis for $k = 5$ or 6 clusters with similar results.

Primarily, these clusters reflect the main circulation pattern of the Santiago basin, namely a thermally driven circulation with south-westerly winds peaking in the afternoon and north-easterly winds peaking in the night. Also, they respond to the east–west gradients in emissions of primary pollutants. This is clear in the case of the $PM_{2.5}$

winter clustering that is dominated by the distribution of traffic sources (e.g. Gallardo et al., 2012b). In the case of the summer ozone cluster, east–west differences are more smeared out due to the more intensive mixing. All in all, the main distinction is between the eastern and western bounds of the basin for all clusters, independently of season, species and distance considered. This pattern has been described elsewhere by various authors, for example, Gallardo et al. (2002); Gramsch et al. (2006); Saide et al. (2011). Also, a common feature for all clusters is that stations M and T show a very specific and distinct behaviour. M is located in a high-income area of the city where emissions patterns are different from elsewhere in Santiago and they consist of mostly residential sources and light duty vehicles (e.g. Gallardo et al., 2012b). Furthermore, this station is located at higher altitude (ca. 700 m a.s.l.) than other stations of the network in a relatively narrow canyon to the north-east of the basin. T, on the contrary, is the only suburban/rural station located to the west of the basin, at its south-westerly outflow. This analysis confirms the utility and importance of clustering analysis in the detection of common spatial patterns (see Ignaccolo et al., 2008).

7. Conclusions and outlook

We have introduced statistical concepts to quantify the information content as well as what we call the 'representativity' and 'specificity' indexes of air quality stations in a monitoring network. These indexes stem from

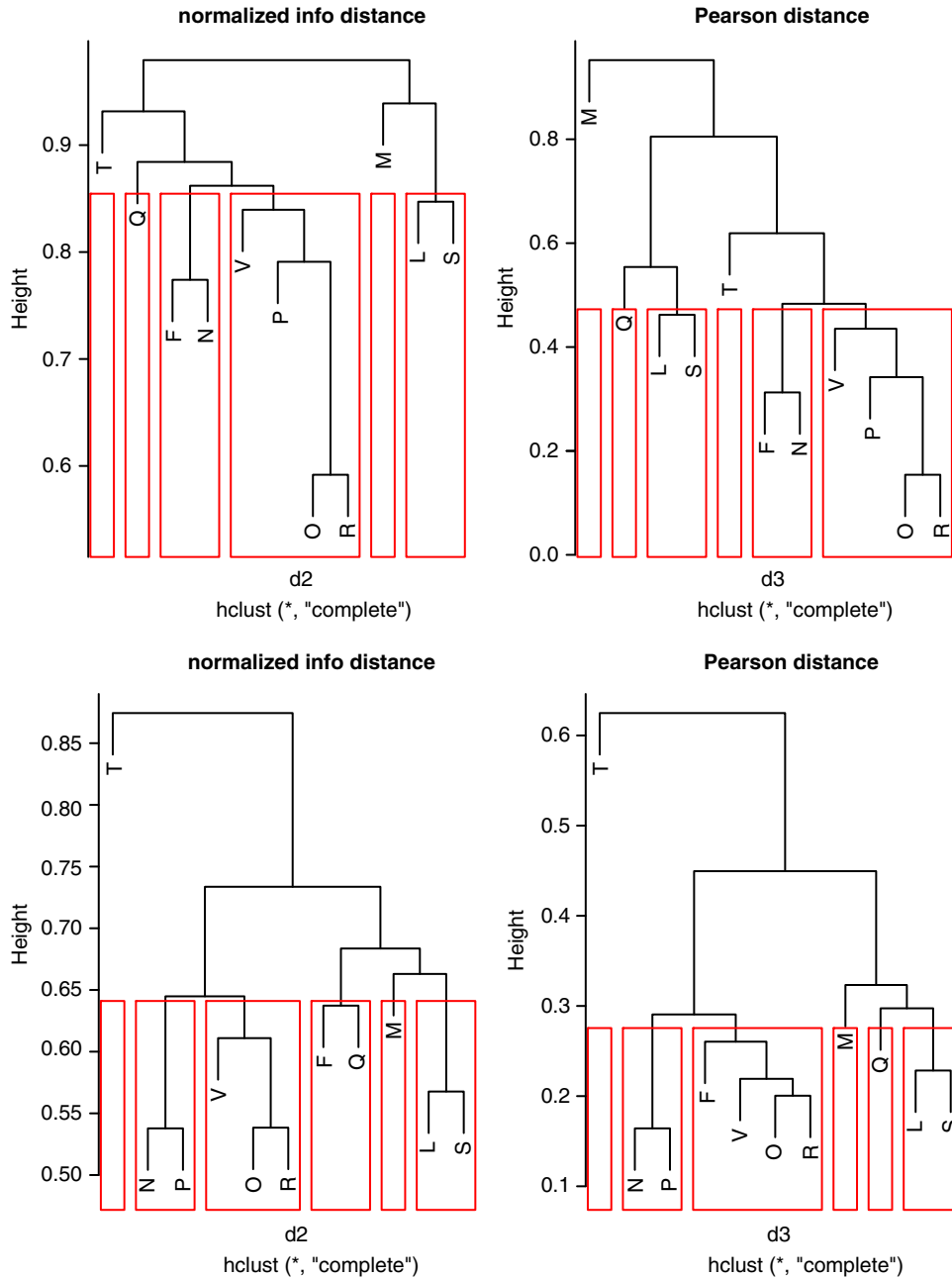


Fig. 12. Hierarchical clustering following the (not normal) normalised information distance (left column) defined in (8) compared with the Pearson correlation function (right column) for $PM_{2.5}$ (top line) and O_3 (bottom line).

information theory concepts, in particular mutual information and information gain. We emphasize that these indexes must be used concurrently if one wants to address the ‘goodness’ of monitoring network, in accordance with the international community agreement of multi-objective network design, and that looking at only one of them may lead to erroneous conclusions. Finally, we use clustering techniques to identify groups of stations with similar characteristics. Furthermore, we show how to assess the

temporal evolution of a network in terms of information content. We analysed 14 yr of data collected by the air quality monitoring network in Santiago de Chile to illustrate the use of the information indexes.

The ‘representativity’ and ‘specificity’ indexes are shown to be robust and consistent with known emission and circulation patterns in Santiago de Chile, namely persistent east–west gradients in emission patterns and the thermally driven circulation with up-slope winds in the afternoon and

down-slope winds during nighttime. We find that measurements in downtown stations, located in a relatively flat area of the Santiago basin, generally show, for all seasons and species, high ‘representativity’ and low ‘specificity’, whereas the contrary is found for a station located in a canyon to the east of the basin. Clustering results corroborate the characteristics identified using the indexes derived from information theory.

Regarding the evolution of a network, we showed how to quantify the corresponding changes in information content. We found that in the case of Santiago, the current network configuration is four times more informative than the initial configuration in the late 1980s, and twice as much as that of 1997. If we choose the simplest background a priori information, the changes in information content are roughly proportional to the changes in number of stations and this follows from a very simple choice for estimating the background mean and covariances that does not consider the spatial distribution of the stations. This can be avoided by using kriging or other interpolation techniques to better address the changes in information content linked to the spatial distribution of the monitoring stations in a network as illustrated by means of Barnes’ interpolation in Figs. 9–11. What seems important is that the indexes presented here, if used in combination with adequate interpolation tools, may be used to obtain the optimal location of new stations by maximising the total information of the network.

All in all, the statistical indexes presented here provide an objective manner to analyse monitoring networks in terms of information content, their evolution, and if used in combination with adequate interpolation techniques, a way to infer best locations for new stations.

8. Acknowledgments

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