

Three-dimensional elastic wave speeds in the northern Chile subduction zone: variations in hydration in the supraslab mantle

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SUMMARY

We use seismic tomography to investigate the state of the supraslab mantle beneath northern Chile, a part of the Nazca–South America Plate boundary known for frequent megathrust earthquakes and active volcanism. We performed a joint inversion of arrival times from earthquake generated body waves and phase delay times from ambient noise generated surface waves recorded by a combined 360 seismic stations deployed in northern Chile at various times over several decades. Our preferred model shows an increase in V_p/V_s by as much as 3 per cent from the subducting slab into the supraslab mantle throughout northern Chile. Combined with low values of both V_p and V_s at depths between 40 and 80 km, we attribute this increase in V_p/V_s to the serpentinization of the supraslab mantle in this depth range. The region of high V_p/V_s extends to 80–120 km depth within the supraslab mantle, but V_p and V_s both increase to normal to high values. This combination, along with the greater abundance of ambient seismicity and higher temperatures at these depths, suggest that conversion from basalt to eclogite in the slab accelerates and that the fluids expelled into the supraslab mantle contribute to partial melt. The corresponding maximum melt fraction is estimated to be about 1 per cent. Both the volume of the region affected by hydration and size of the wave speed contrasts are significantly larger north of $\sim 21^\circ\text{S}$. This latitude also delimits large coastal scarps and the eruption of ignimbrites in the north. Ambient seismicity is more abundant north of 21°S , and the seismic zone south of this latitude is offset to the east. The high V_p/V_s region in the north may extend along the slab interface to depths as shallow as 20 km, where it corresponds to a region of reduced seismic coupling and overlaps the rupture zone of the recent 2014 *M*8.2 Pisagua earthquake. A potential cause of these contrasts is enhanced hydration of the subducting oceanic lithosphere related to a string of seamounts located on the Iquique Ridge of the Nazca Plate.

Key words: Interferometry; Seismic tomography; Subduction zone processes; Continental margins: convergent; South America.

1 INTRODUCTION

It is generally agreed that subducting oceanic lithosphere transports an abundance of aqueous fluid and hydrated minerals into the Earth (e.g. Ulmer & Trommsdorff 1995; van Keken *et al.* 2011). While much of this fluid is released at shallow depths, it is thought to be responsible for hydration of the mantle wedge beneath the overriding plate (Peacock 1993; Peacock & Hyndman 1999; Iwamori 2000; Kamiya & Kobayashi 2000; Bostock *et al.* 2002). Depending on the age and speed of the subducting lithosphere, a significant amount of water may be carried to depths in excess of 200 km (van Keken *et al.* 2011). The effects of the transportation and release of water

in subduction zones are profound. For example, water can lower the melting temperature of the mantle by some 400 °C, resulting in the generation of magma that eventually finds its way to the surface in the form of a volcanic arc (Gill 1981; Moran *et al.* 1992; Peacock 1993; Plank & Langmuir 1993; Yogodzinski *et al.* 1995; Stern & Kilian 1996; Kelemen *et al.* 1998; Kerrick & Connolly 2001; Grove *et al.* 2006, 2009). Dehydration reactions and phase transitions within the subducted slab are believed to be responsible for the intermediate-depth seismicity within slabs (e.g. Kirby *et al.* 1996; Peacock 2001; Omori *et al.* 2002, 2004; Hacker *et al.* 2003; Abers *et al.* 2013). Water released in subduction zones by phase transition from basalt to eclogite (between 1.2 and 3.3 per cent, Hacker 1996)

appears to be important in forming serpentine in the mantle wedge above the slab (Fyfe & McBirney 1975; Bostock *et al.* 2002; Hacker *et al.* 2003; Hacker 2007). If the supraslab mantle is serpentinized in this corner of the uppermost mantle, its low shear strength may control the down-dip rupture limit of great megathrust earthquakes (e.g. Hyndman *et al.* 1997; Bostock *et al.* 2002).

Because elastic wave speeds are sensitive to both serpentinization and partial melt (e.g. Hammond & Humphreys 2000; Kerrick 2002; Carlson & Miller 2003; Hacker *et al.* 2003; Christensen 2004; Watanabe *et al.* 2007; Karato 2012; Ji *et al.* 2013), empirical evidence for the role of water in subduction has largely come from seismic imaging and earthquake locations. For example, seismic velocity models such as those from Cascadia (Bostock *et al.* 2002), Costa Rica (DeShon & Schwartz 2004), New Zealand (Eberhart-Phillips & Bannister 2010) and Japan (Kamiya & Kobayashi 2000; Zhang *et al.* 2010), suggest that serpentinization in the mantle wedge is on the order of 10–20 wt%. While these studies are enlightening, neither the extent to which the supraslab mantle is hydrated nor the amount of the partial melt generated within that part of the mantle is well known.

In this paper, we investigate the pervasiveness of hydration and partial melt in the supraslab mantle beneath the Nazca–South America Plate boundary in northern Chile by generating elastic wave speed images through joint inversion of observations of local earthquake body waves and ambient noise surface waves. Our motivation for choosing this particular area is partly the availability of an extensive data set directly above a mantle wedge, but also because the frequent occurrence of megathrust earthquakes and the prevalent arc volcanism along this plate boundary allows an opportunity to investigate the consequences of variations in supraslab wave speed anomalies for Andean margin seismicity and volcanism.

1.1 Overview of the northern Chile Plate boundary

The central Andes evolved over the past ~200 Ma as a series of magmatic arc systems related to the subduction of oceanic lithosphere beneath the South American continental margin (e.g. Isacks 1988; Scheuber *et al.* 1994; Allmendinger & Gubbels 1996; Allmendinger *et al.* 1997). Large volumes of calc-alkaline lavas and related plutons have been emplaced along trench-parallel provinces since the Jurassic, showing a general trend of eastward migration (Coira *et al.* 1982). The current magmatic arc commenced in Middle Miocene times (~27 Ma) (Baker & Francis 1978), and deposited significant volumes of volcanic material in northern Chile during Neogene times. The arc remains very active along its ~2000 km length.

The forearc region of the central Andes typically is subdivided into four morphotectonic units (e.g. Reutter *et al.* 1988; Fig. 1). From west to east, these include: (1) the Coastal Cordillera, which is the Jurassic age magmatic arc, (2) the Central Depression, a Jurassic back arc basin and mid-Cretaceous magmatic arc covered by younger sedimentary rocks, (3) the Precordillera, a late-Cretaceous magmatic arc with Mesozoic sediments lying unconformably upon metamorphic basement and plutonic rocks and (4) the Western Cordillera, the currently active volcanic arc with peaks in excess of 6000 m. The missing Jurassic forearc is presumed to have been tectonically eroded; the eastward migration of the volcanic front from the Coastal Cordillera to the Western Cordillera suggests that an EW section of more than 200 km has been consumed (Rutland 1971; Ziegler *et al.* 1981; Scheuber *et al.* 1994).

Topography in the forearc is highly variable. There is no well-developed accretionary wedge near the trench (Von Huene *et al.* 1999), and an extensional forearc is linked to the coast by a ~1000 m escarpment. The subdued relief of the Coastal Cordillera and Central Depression give way in the east to the steep western flank of the Precordillera and high altitudes of the Western Cordillera.

The Nazca–South American Plate boundary currently has one of the fastest convergence rates on Earth at about 6–7 cm yr⁻¹ (DeMets *et al.* 1990, 1994; Altamimi 2002; Sella *et al.* 2002). As a result, this boundary has produced on average one earthquake with magnitude $M_w \geq 7.9$ every 10 yr over the past 100 yr. The segment of the boundary in northern Chile presently is considered to be a seismic gap, having accumulated more than 9 m of slip deficit during the last 130 yr of interseismic coupling, and believed capable of generating an M_w 9.0 earthquake (Fig. 2). The recent 2014 M_w 8.2 Pisagua earthquake in northern Chile is considered by some to be a potential foreshock of that larger event.

Northern Chile and southern Peru together have experienced great earthquakes in the past (e.g. the 1868 M_w 8.7 southern Peru and 1877 M_w 8.9 northern Chile events (Comte & Pardo 1991)) (Fig. 2). By contrast, few shallow earthquakes related to the interplate coupled region have occurred within the forearc. Among rare examples is the 2007 M_w 5.7 Pisagua earthquake, located in the outer forearc region during the interseismic stage of the subduction seismic cycle (Allmendinger & González 2010).

Modelling of GPS and InSAR data suggests that during the interseismic phase of the earthquake cycle, the plate contact in northern Chile is locked to 35 km depth with a transition zone (brittle–ductile) between 35 and 55 km depth, but with variations in those limits along strike (Norabuena *et al.* 1998; Bevis *et al.* 2001; Khazaradze & Klotz 2003; Chlieh *et al.* 2004; Pritchard & Simons 2006; Béjar-Pizarro *et al.* 2010; Métois *et al.* 2013). Recently, Ortega-Culaciati *et al.* (2015) re-analysed decades of geodetic data and obtained a detailed map of interplate coupling along the seismic gap in northern Chile (Fig. 2). To first order, they observe that the part of the boundary between Pisagua (~21°S) and Antofagasta (~23°S) is highly coupled, while that north of ~21°S is heterogeneous but generally less coupled. They found an isolated, highly coupled patch offshore of Pisagua surrounded by low coupled areas, in agreement with the findings of Métois *et al.* (2013). The coseismic slip of the 2014 M_w 8.2 Pisagua earthquake occurred in this isolated patch while the postseismic slip occurred in the neighbouring low coupled regions. Despite this variability, interseismic coupling models suggest that the northern Chile seismic gap remains capable of generating a large megathrust earthquake.

2 DATA AND METHODOLOGY

The data analysed in this study are a combination of arrival times from earthquake generated body waves and phase delay times from ambient noise generated surface waves recorded by seismic stations deployed in northern Chile for different periods of time over the past three decades (Fig. 3).

2.1 Body waves from local earthquakes

The abundance of local earthquake data collected from this region (Fig. 3 and Table 1) is largely in response to the frequent megathrust events and the anticipated end of the current seismic cycle in northern Chile. For example, a rapid deployment of 10 broad-band stations before, and 16 broad-band stations after, the 2014 M_w 8.2

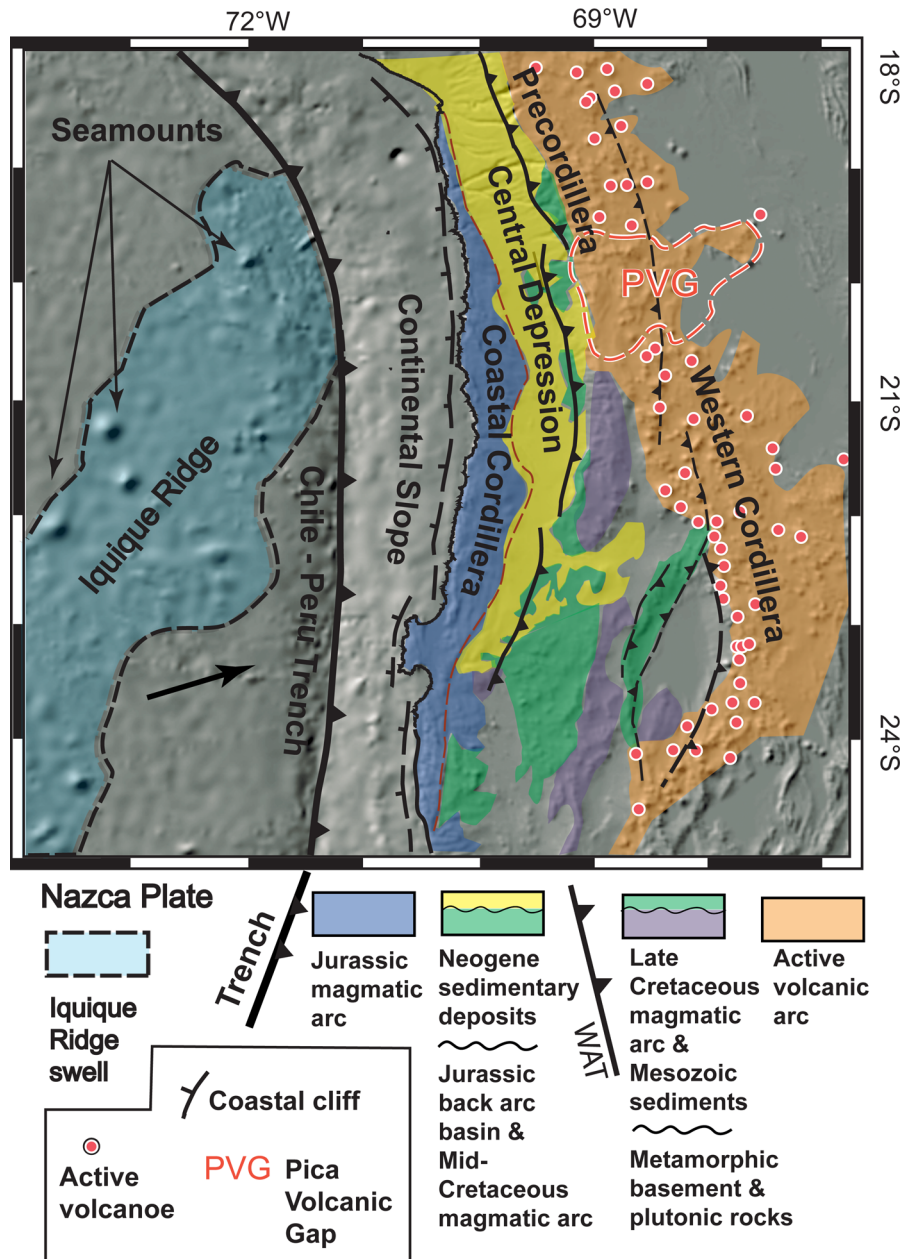


Figure 1. Simplified geologic map of northern Chile. The arrow to the left of the trench indicates the direction of the Nazca plate relative to South America.

Pisagua main shock by the Oficina Nacional de Emergencia (ONEMI), the Departamento de Geofísica of the Universidad de Chile (DGF) and the Chilean Centro Sismológico Nacional (CSN), together with the Iquique Local Network (ILN-IPOC) and GeoForschungsZentrum (GFZ) deployments, resulted in the highest density of stations ever deployed in this region.

The initial body wave data set derived from these deployments consists of P and S arrival times from 33 351 events recorded over a period of 25 yr by a variety of networks comprising 360 stations (Table 1; Figs 3 and 4). From this combined data set, we selected earthquakes that were recorded by at least 10 stations and with predicted arrival times within an initial outlier residual threshold of the larger of 2 s and 10 per cent of the total traveltime (essentially this means we presume the initial model is, on average, within about ± 10 per cent of the actual structure). Application of these criteria resulted in a reference data set of 11 874 events with 110 640 P and

106 680 S wave arrival times. These arrival times and their associated uncertainties are estimated manually. Nominal uncertainties for P wave arrival times are between 0.1 and 0.5 s while those for S waves typically are about twice that amount.

2.2 Ambient noise data and preprocessing

Most of the ambient noise analyzed in this study was recorded by 18 broad-band stations operated by the Integrated Plate Boundary Observatory Chile (IPOC), CSN and ONEMI over a period of 3 yr (2012 January 1–2014 December 31). This primary dataset is supplemented by recordings from 29 broad-band stations deployed by the DGF, CSN and ONEMI near Pisagua for 4 months (2014 March 29–2014 July 31) and 12 broad-band stations of the Iquique network operated by GFZ Potsdam for 7 months (2012 January 10–2013 September 5). The 59 total stations in these combined

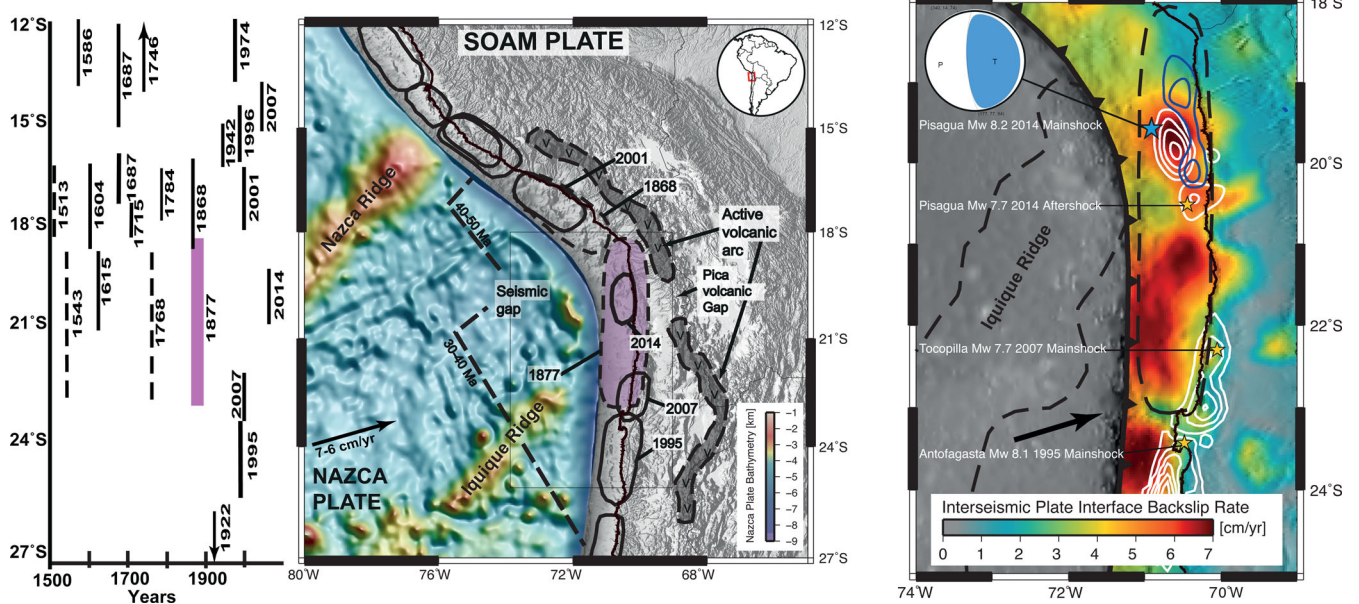


Figure 2. Seismotectonic setting of northern Chile and southern Peru. Left-hand panel: estimated ruptures of historic seismicity are shown at the far left; the bold purple line corresponds to the last rupture of the northern Chile seismic gap in 1877. Recent ruptures are indicated on the map by the year in which they occurred. Map colours correspond to bathymetry of the Nazca plate as shown in the palette at the lower right. Ages of the subducting Nazca plate are shown next to dashed lines. Thin rectangle locates the map on the right. Right-hand panel: interseismic plate interface backslip rate, coseismic slip (white contours) for 2014 (M_w 8.2) Pisagua main shock and largest (M_w 7.7) aftershock, post-seismic slip (blue contours) induced by Pisagua main shock event, all determined from GPS observations by Ortega-Culaciati *et al.* (2015). The epicentre (blue star) and focal mechanism are shown for the 2014 Pisagua main shock event. Coseismic slip (white contours) is also shown for the other recent large earthquakes in the study area: the Antofagasta (M_w 8.1) 1995 (Pritchard & Simons 2006) and Tocopilla (M_w 7.7) 2007 (Béjar-Pizarro *et al.* 2010) events.

networks (Fig. 3) provide 1422 contemporaneous station pairs from which Green's functions may be estimated.

For the most part we followed the pre-processing steps described in Bensen *et al.* (2007) to generate estimated Green's functions (EGFs) from the vertical component of cross-correlated noise, using a version of the CU-Boulder ANCC software,¹ modified to permit sample rates and frequency bands appropriate for our data. Running-mean normalization was used to reduce contamination by coherent signals (mostly from earthquakes), and we pre-processed a band between periods of 2 and 150 s.

Cross-correlations for each contemporary station-pair were generated for each day of record, and then stacked over the duration of co-recording. In an attempt to improve the signal-to-noise ratio (SNR) of the final stack we iteratively removed daily correlations that deviated by more than one standard deviation from the overall stack. However, we found that generally neither the shape of the EGF nor the SNR were significantly different from those obtained from a simple stack of the entire data set.

We measured phase velocity dispersion using a technique based on that described in Yao *et al.* (2006). The EGFs are narrow-band filtered at 1 s intervals between 4 and 30 s in a pass-band of ± 0.2 s of the central period and windowed within 3 cycles of an estimated arrival time. Noise is sampled in a part of the seismogram before the expected arrival, and seismograms with an SNR less than a given threshold (usually 10) are excluded. Those remaining are transformed to a velocity versus period space and a phase velocity dispersion curve is determined by tracking amplitude maxima over available periods. In practice, simply following the maxima does not guarantee immunity from cycle skips, and hence as a pre-processing

step we generated a pilot dispersion curve from a least squares fit to all of the original curves that appear to fall within the correct cycle. In this case the pilot curve for phase velocity c (in km s^{-1}) as a function of period T (in seconds) was represented by the polynomial

$$c(T) = 3.142226 + 0.03087T - 0.0002410516 T^2 - 0.00000065 T^3. \quad (1)$$

For each EGF we choose the cycles that most closely follow this curve. Points without a clear maximum near the pilot curve were visually re-examined and discarded if ambiguous. Dispersion curves were generated for a band between 5 and 20 s period. Examination of dispersion curves from several station pairs suggests that cycle skips could be reliably identified at periods longer than 5 s; hence we adopt that as a minimum period. The choice of 20 s maximum period comes from abiding by the three-wavelength rule of Bensen *et al.* (2007) which in this case excludes nearly all but the N-S paths at longer periods.

Because of the proximity of the stations to the Pacific Ocean (Fig. 3), and the strong dependence of path length on azimuth (most N-S paths are long, most E-W paths are short), one may be concerned that an azimuthally inhomogeneous distribution of noise could significantly bias the phase velocities determined from the EGFs. This concern was reinforced by both the asymmetry of some of the EGFs and discrepancies in dispersion curves generated by the causal and acausal sides of some of the cross correlations.

To estimate and correct for this bias we employed a technique based on that described by Yao & van der Hilst (2009). To summarize their approach, we first determine the azimuthal distribution of noise $E(\theta)$ by considering that the observed cross correlation $C_n(\omega, t, d_n)$ for station pair n as a function of frequency ω , time t , and interstation distance d_n can be constructed as a weighted sum of monochromatic plane waves. Taking the Fourier transform (FT) of this construction

¹ Available at: <http://ciei.colorado.edu/Products/>.

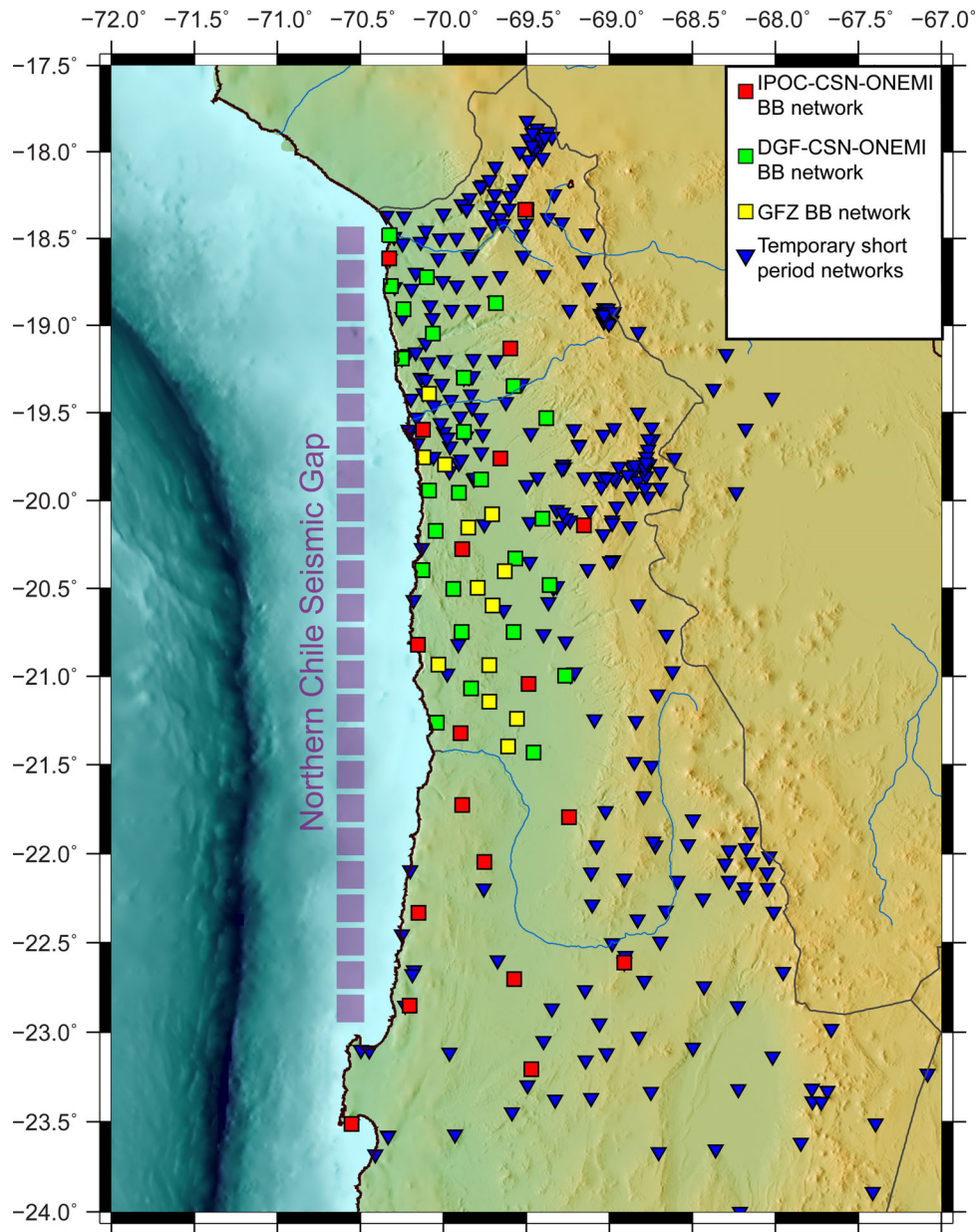


Figure 3. Locations of seismic stations used in this study, with symbols indicating provenance as shown in the insert at the upper right. The location of the northern Chile seismic gap is shown by the dashed purple line.

gives

$$FT[C_n(\omega, t, d_n)W_n(t, d_n)] = \sum_{m=1}^M E(\theta_m) \times FT\{\cos[\omega(t - \delta t_{nm})]H_{nm}(t, \delta t_{nm})W_n(t, d_n)\}, \quad (2)$$

where θ_m is the m th azimuth and δt_{nm} is the phase delay time, calculated by integrating the inverse of the phase velocity along the path between the two stations. W_n and H_{nm} are time windows for the surface wave train in the EGF and the obliquely arriving monochromatic waves, respectively, assuming a range of wave speeds from 2 to 5 km s⁻¹. The distribution of noise $E(\theta)$ is then determined by minimizing the energy in the difference between the observed and calculated real and imaginary parts of the Fourier transform of the cross correlations for all station pairs.

We slightly modify this approach by noting that, for any pair of stations, the cross correlation at each station depends only on

that part of E within the 180° of azimuth that travels towards that station. Hence, the sum in eq. (2) is a concatenation of two independent equations relevant to the causal and acausal parts of the cross correlation. Separating the two is advantageous for many station pairs where one side of the cross correlation has little energy above the noise level as the other side can still be used. Hence, we split the single eq. (2) into two sums over the relevant azimuths and add a row to the normal equations for each side of the cross correlation.

Having estimated $E(\theta)$, we use (1) to calculate a phase shift $\delta\phi_n$ between an observed cross-correlation and one which would have resulted from an isotropic distribution of noise (i.e. $E(\theta)$ is a constant) and define a bias μ as

$$\mu = -\frac{\delta\phi_n}{\omega t_n} = \frac{t_n^{iso} - t_n}{t_n}, \quad (3)$$

Table 1. Summary of the deployments that recorded the data used in this investigation. Operator and network abbreviations refer to the Universidad de Chile (UCH), Universidad de Antofagasta (UA), Institut de Recherche pour le Developpement (IRD) the Institut de Physique du Globe de Strasbourg (IPGS), GeoForschungsZentrum (GFZ), Freie Universität Berlin (FUB), the Integrated Plate Boundary Observatory Chile (IPOC), the Chilean Centro Sismológico Nacional (CSN) seismic networks, the Oficina Nacional de Emergencia (ONEMI), the Departamento de Geofísica of the Universidad de Chile (DGF), and the Iquique Local Network (ILN-IPOC). Instrument types are short period (sp) and broad band (BB). Start and end times of deployment are in year and Julian day (JD). Data from IPOC (doi:10.14470/PK615318) is available online via the GFZ website. All other data available on request from DGF.

Operator	Seismic network Name	Start		End		Number and type of sensor
		Year	JD	Year	JD	
IRD-UCH-UA	ANTOFAGASTA PERMANENT	1990	313	1995	209	10 sp
DGF	IQUIQUE 1991	1991	194	1991	227	21 sp
DGF-GFZ-FUB	CALAMA 1994	1994	88	1994	114	34 sp + 5 BB
IRD-IPGS-DGF	ARICA 1996	1996	173	1996	225	46 sp
UTA	ARICA PERMANENT	1997	91	2002	273	16 sp
DGF	TMP 1	2005	349	2006	38	10 sp
DGF	TMP 2	2005	182	2005	212	16 sp
DGF	TMP 3	2006	127	2006	265	15 sp
DGF	TMP 4	2006	274	2007	3	14 sp
DGF	TMP 5	2007	244	2007	320	12 sp
DGF	TMP 6	2007	324	2008	5	12 sp
DGF	TMP 7	2007	146	2007	241	17 sp
IPOC-CSN-GFZ	IPOC + CSN	2007	318	2014	91	16 BB + 4 BB
DGF	TMP 8	2009	183	2009	365	23 sp
DGF	TMP 9	2011	207	2012	211	15 sp
DGF	TMP 10	2011	319	2011	348	15 sp
DGF	TMP 11	2012	183	2012	270	10 sp
DGF	PISAGUA 2013	2013	143	2013	280	26 sp
IPOC-GFZ-CSN-ONEMI	IPOC + CSN + CSNTemporary	2014	92	2014	240	46 BB + 12 BB
GFZ-IPOC	ILN	2012	91	2013	120	10 BB

where t_n is an estimate of the phase delay time between station-pair n derived from a 2-D phase velocity map using dispersion curves generated from averaged cross correlations (causal and acausal). The estimates of the ‘true’ phase delay time, t^{iso} , are then used to update the phase velocity maps. This process may be iterated until the estimates of t^{iso} stabilize. For the data set used here, stability was achieved after a single iteration.

As may be expected, the noise distribution we determined for northern Chile (Fig. 5) is dominated by sources from the west, although the direction of propagation for the maximum is slightly north of east (about 70° azimuth). The biases resulting from this noise distribution are variable but generally small (<0.6 per cent) (Fig. 6). These estimated biases were used to adjust the surface wave phase delay times and new phase velocity maps (Fig. 7) were computed. The phase delay times derived from these maps are then used in the joint inversion with the body wave arrival times.

2.3 Joint inversion methodology

Like most joint inversions, the simultaneous fitting of body wave arrival times and surface wave phase delay times is motivated by complementary sensitivities of these observations to different parts of the model. In this case, surface waves are included mostly to reduce potential trade-offs in crustal and mantle structure caused by the lack of local earthquake activity in the crust. Surface waves also provide additional constraints on shear wave speeds that compensate for the lower number of, and higher uncertainties in, shear wave arrival times.

The joint inversion methodology is based on an approach described in Nunn *et al.* (2014), modified for the local event case using procedures described in Roecker *et al.* (2004, 2006). The

subsurface is parameterized by specifying P and S wave speeds on a 3-D grid of nodes spaced at 5 km intervals in depth and latitude and about the same distance in longitude (increments in longitude are everywhere 0.04717°). Intragrid wave speeds are determined by trilinear interpolation. Body wave traveltimes within the medium are calculated using a 3-D eikonal equation solver in a spherical (Earth-centred) coordinate system (Li *et al.* 2009; Zhang *et al.* 2012). Surface wave phase delay times at a given frequency ω in a given 3-D V_s model are determined by first assuming that such a model can be constructed by combining 1-D models at each areal grid point (Montagner 1986). With this assumption, we calculate phase velocities c and partial derivatives $\partial c/\partial V_s$ for the 1-D model at each areal point using the locked-mode method of Gombert & Masters (1988). The phase delay times between any two points are then calculated by integrating the reciprocal of the phase velocity along the great circle path between them.

The inverse problem is a standard linearized expansion of the forward problem, and partial derivatives for each observation are calculated along the ray paths. Following a procedure used in Roecker *et al.* (2004) we solve for perturbations to P slowness ($U_p = 1/V_p$) and the ratio $r = V_p/V_s = U_s/U_p$ rather than to shear wave slowness itself by setting $\Delta U_s = \Delta(rU_p) = U_p \Delta r + r \Delta U_p$ and including a shear wave observation using

$$T_{so} - T_{sc} = \sum_{k=1}^4 \frac{\partial T_{sc}}{\partial h_k} \Delta h_k + \sum_{i=1}^m \frac{\partial T_{sc}}{\partial U_{si}} [U_{pi} \Delta r_i + r_i \Delta U_{pi}], \quad (4)$$

where T_{so} and T_{sc} are the observed and calculated shear wave traveltimes, respectively. The partial derivatives are taken with respect to the 4 hypocentre parameters h_k and the m values of U_{si} that exhibit sensitivity to the shear wave time (i.e. those that bound the

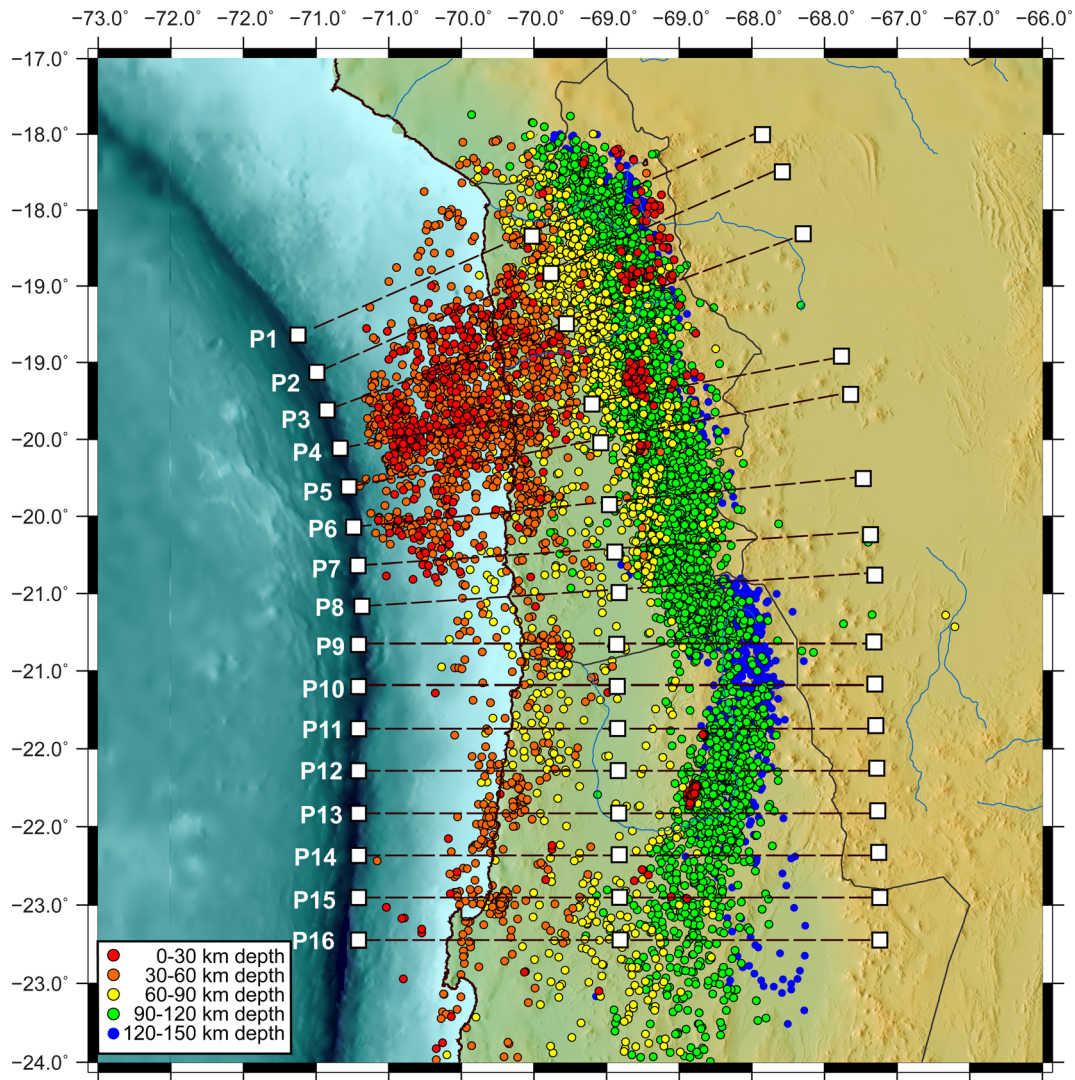


Figure 4. Locations of earthquakes used in this study, indicated by circles filled with colours corresponding to depth ranges shown in the insert at the lower left. White squares joined by dashed lines and labelled P1–P16 locate the ends and midpoint origins ($X = 0$) in the cross sections shown in Figs 10–12.

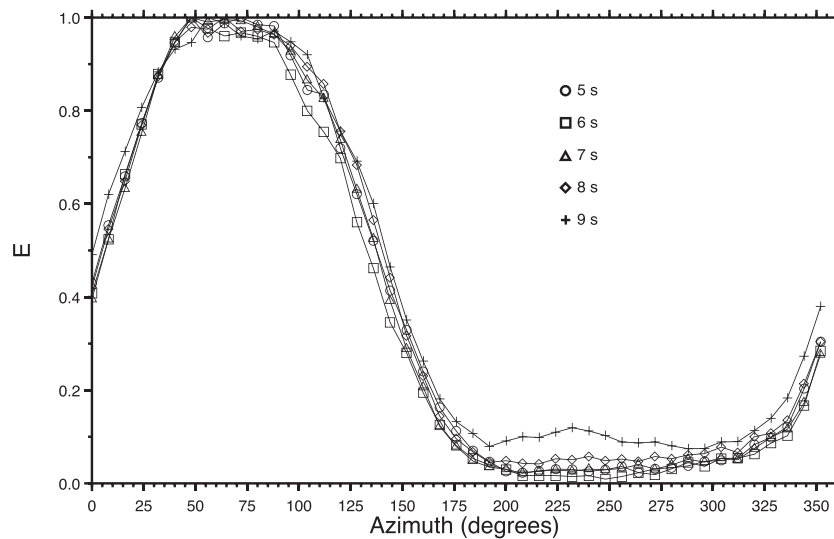


Figure 5. Normalized noise distribution E as a function of propagation azimuth for a selection of periods (5–9 s). Note that most of the noise propagates to the ENE, as may be expected from the proximity of the recording stations to the Pacific coast of South America.

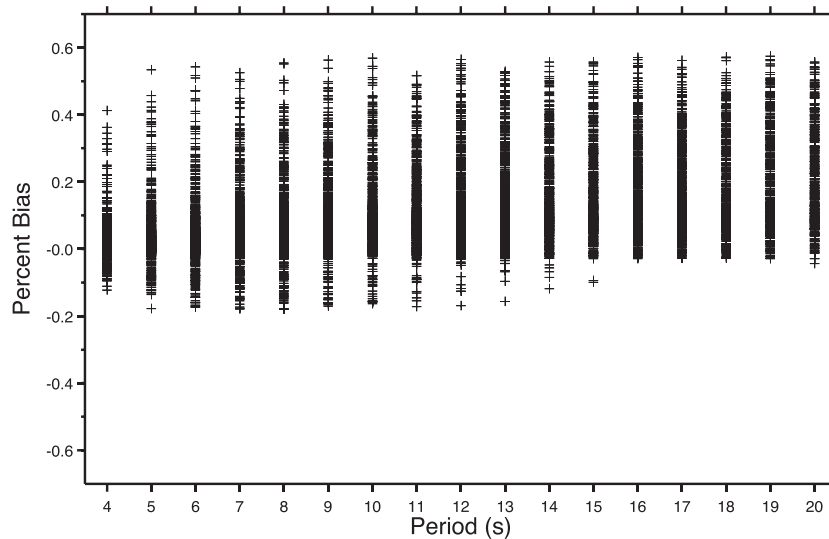


Figure 6. Phase velocity bias determined from the noise distributions shown in Fig. 5 as a function of period. Despite the heterogeneity in the noise distribution, the expected bias is small (<0.6 per cent) for all station pairs.

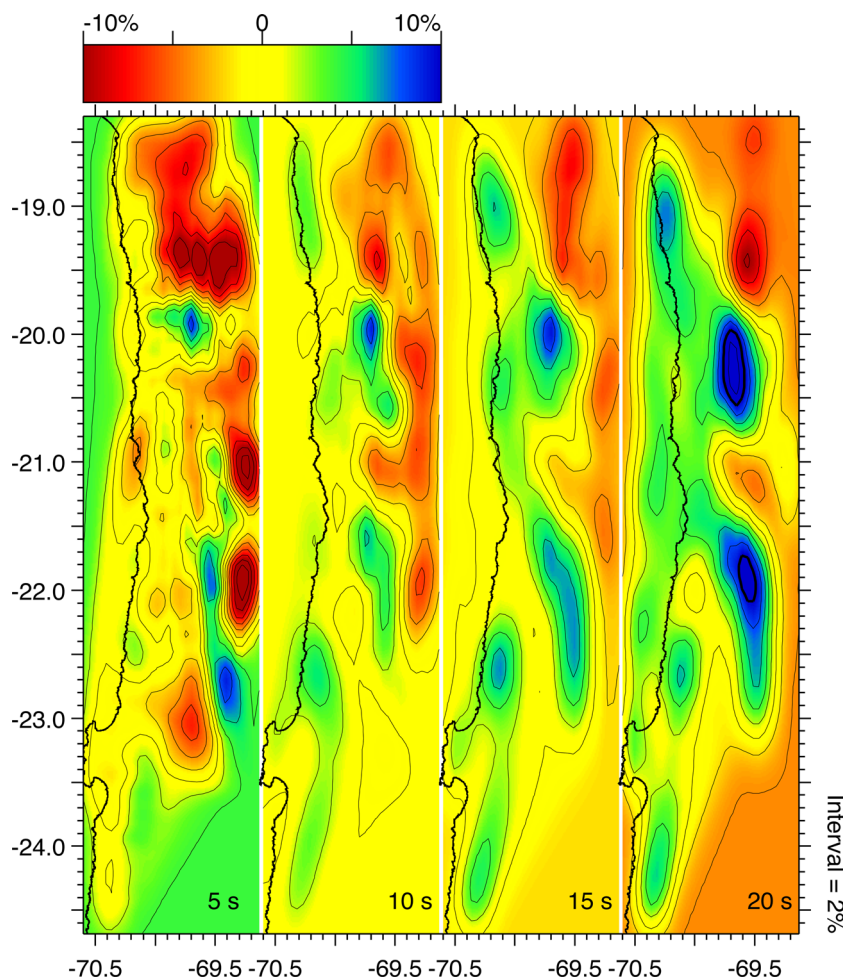


Figure 7. Phase velocity maps at selected periods (indicated at the lower right of each panel) determined from ambient noise generated Rayleigh waves. The coastline of northern Chile is plotted as a reference. Values are percent differences from an average 1-D background, and the contour interval is 2 per cent.

elementary volumes through which the ray passes). A revised shear wave speed model is then determined from $U_s = rU_p$ after modifying r and U_p with Δr and ΔU_p . We take this approach partly for technical reasons—it allows the S wave model to take advantage

of the greater resolving power of P waves and provides a means to couple the sensitivity to U_s of the surface waves to perturbations in U_p —but also because we ultimately seek to interpret variations in r as proxies for hydration and melt fraction. Determining r by

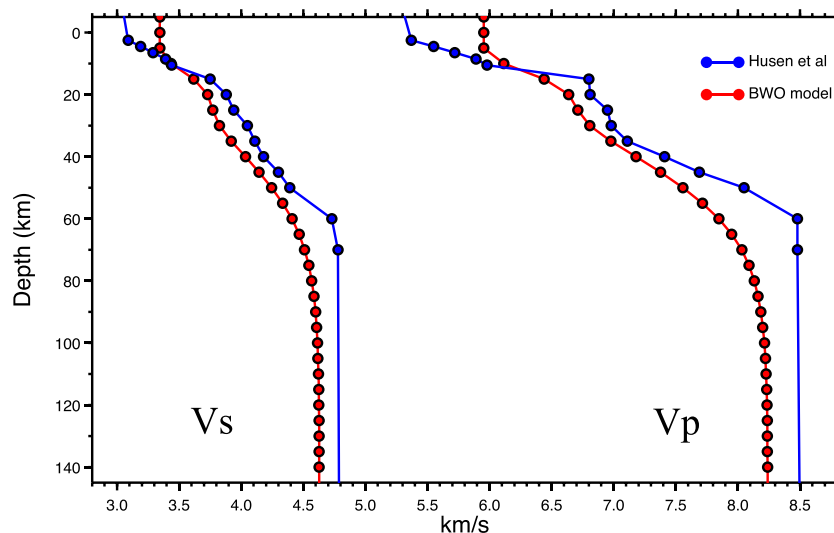


Figure 8. 1-D starting models used in this study. Blue lines show V_p and V_s from Husen *et al.* (1999) used in the BWO inversion. Red lines show a model deduced from a 1-D average of the BWO inversion. V_s from this model is used as a starting model for the SWO inversion.

dividing individually determined V_p and V_s is problematic because of differences in the level of resolution for these quantities.

Phase delay times of surface waves at any frequency ω are included in a similar way by relating derivatives of shear wave slowness U_s with respect to phase velocity $c(\omega)$ by the chain rule:

$$T_{so}(\omega) - T_{sc}(\omega) = \sum_{i,j} \frac{\delta T(\omega)}{\delta c_{ij}(\omega)} \sum_k \frac{\delta c_{ij}(\omega)}{\delta U_{sijk}} \times [U_{pijk} \Delta r_{ijk} + r_{ijk} \Delta U_{pijk}], \quad (5)$$

where the indices i, j and k refer to the latitude, longitude and depth coordinates, respectively, of each node in the model.

Each row of the system of linear equations is weighted to reflect the uncertainties in the observations. Body wave arrivals are weighted by the inverse of the square of the associated time uncertainty. Surface wave phase delay times are similarly weighted by estimating an uncertainty based on the SNR of the EGF used in generating the dispersion curve, multiplied by a factor related to the period (longer periods generally have less well defined maxima). Uncertainty estimates thus obtained range from a few tenths of a second to several seconds but generally are about 3 per cent of the phase delay time. Outliers in the surface wave data set are identified and removed during the creation of phase velocity maps as part of the noise bias analysis. For body waves, data quality criteria are enforced at each iteration in order to eliminate potential outliers and to disqualify less well constrained hypocentres. Thresholds for outlier identification are applied at each iteration, and observations that exceed these thresholds are disqualified for that iteration (but may be reintroduced in subsequent iterations if a wave speed adjustment brings the residual under the threshold). These thresholds are generous at the start but gradually reduced over several iterations to the larger of 0.5 seconds or 5 per cent of the traveltime. Hypocentres with fewer than 10 acceptable P and S wave observations after the criteria are applied are excluded. For most runs this culling process retained about 95 per cent of the original observations over the course of inversion. We also applied different strategies for relative weighting of body and surface wave observations in a joint inversion, but in the end found that the best result was obtained by first inverting the surface wave phase delay times alone for several iterations prior to jointly inverting both the body and surface waves

with even weighting. This appears to be due to both the greater sensitivity of surface waves to shallow structure and the much larger number of body wave observations available.

The resulting system of linear equations is solved iteratively using the LSQR algorithm of Paige & Saunders (1982). In addition to regularization by damping, perturbations to the P and S models are smoothed after each iteration by averaging neighbouring nodes with a moving window. After trial-and-error tests of trade-off between variance reduction and model complexity we decided to use a window with 5 nodes in the E–W direction (the centre node and two nodes either side), 11 nodes in the NS direction (± 5 nodes from the centre) and 3 nodes (± 1 node from the centre) in the Z direction. The larger window in the N–S direction reflects an anticipated lesser degree of heterogeneity parallel to the strike of the Andes, but also compensates for the longer ray paths in that direction. Note that at each iteration we are smoothing the perturbations to the model as opposed to the model itself; hence smaller scale variations in wave speed still can appear over several iterations.

Hypocentre coordinates are included as variables in the inversion (eq. 3) but are also relocated in updated models prior to any iteration. The models shown here generally will have gone through about 10 iterations with only surface wave times followed by an additional 10 iterations with combined surface and body wave times. Generally, no significant change in variance nor in values of wave speeds are realized beyond that point.

2.4 Preliminary inversions and starting models

As mentioned above, we determined that the best way to incorporate surface wave observations was to allow them to adjust the model prior to the joint inversion. In developing a starting model for the surface wave only (SWO) inversion, we began with a body wave only (BWO) inversion that started with an adaptation of the 1-D model of Husen *et al.* (1999) for the Antofagasta region (Fig. 8). The resulting 3-D BWO model for V_p and V_p/V_s , obtained after 13 iterations, was averaged laterally to obtain a 1-D estimate of V_s . This step ensures some compatibility with the body waves, and also provides a means for determining appropriate values for regularization and thresholds for data misfit. Because surface wave inversions tend to retain biases introduced by interfaces like the

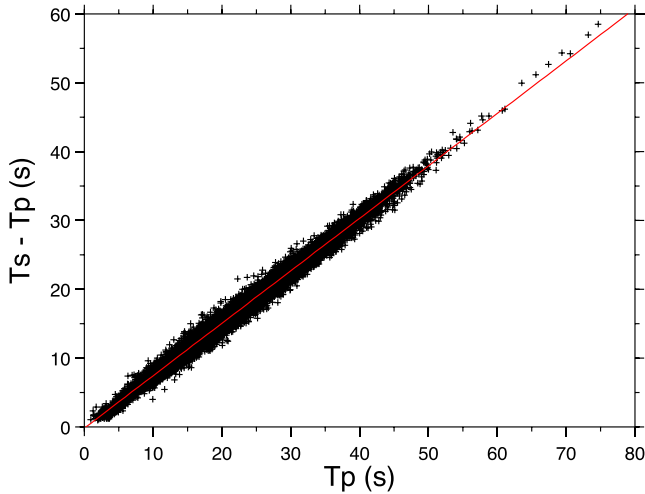


Figure 9. A Wadati plot [P traveltime (T_p) versus S - P traveltime ($T_s - T_p$)] for all arrival times in the dataset. The red line is a least-squares fit corresponding to a V_p/V_s of 1.7622 ± 0.0002 .

Moho, we smoothed the transition from crustal to mantle velocities over a range of depths (40–70 km) suggested by previous estimates of crustal thickness in this area (e.g. Beck *et al.* 1996; Yuan *et al.* 2000, 2002; McGlashan *et al.* 2008). This 1-D V_s model (Fig. 8) was then used as a starting model for the SWO inversion.

After 10 iterations of the SWO inversion, the wave speeds in the resulting 3-D V_s model were then multiplied by a constant V_p/V_s ratio to construct a starting 3-D V_p and V_s model for the joint inversion. Based on both the results from the BWO inversion and a linear fit to T_p versus $T_s - T_p$ for the entire body wave data set (Fig. 9), we take $V_p/V_s = 1.76$ as the preferred value. As discussed below, while the absolute values for the wave speeds and their ratios in the final models are sensitive to the choice of initial value of V_p/V_s , there are metrics that argue in favour of 1.76.

3 DESCRIPTION OF THE PREFERRED MODEL

Several trial inversions, discussed below, were performed to evaluate the effects of a variety of assumptions and choices of parameters on the final model. Those chosen for our preferred model (Figs 10–12) manage to fit the observations well while suppressing short wavelength artefacts. Relative to the 3-D starting model generated

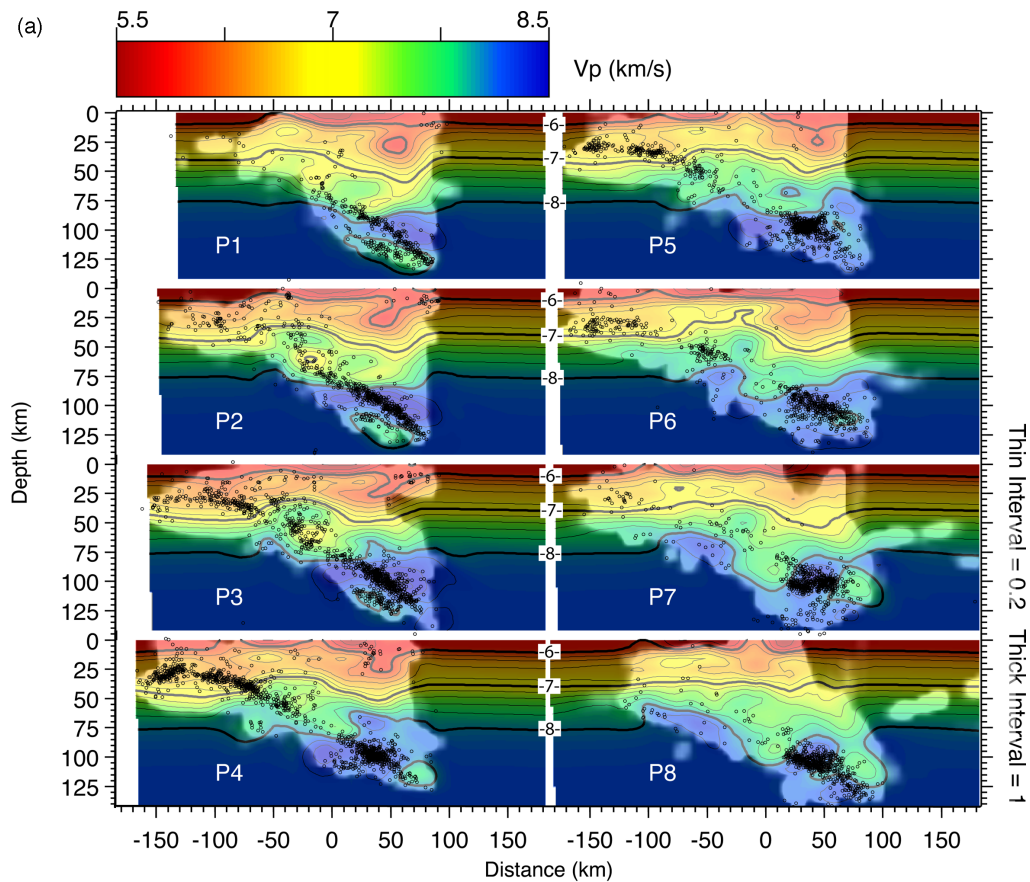


Figure 10. (a) Cross-sections P1–P8 of V_p for the preferred model. Locations of sections are shown in Fig. 4, and correspond to the labels in the lower left-hand corner in each section. Depth is relative to sea level, and distance is with respect to the midpoints of each section (plotted as white squares in Fig. 4). Values are indicated by the colour palette in the upper left part of the figure, and are shown for thick contours in between the sections. Thin contours are at 0.2 km s^{-1} intervals. The plots are shaded to reflect density of sampling, with the brightest regions corresponding to regions sampled by at least 10 ray paths. Cross-sections of hypocentres within $\pm 15 \text{ km}$ perpendicular to a vertical plane defined by the section are shown as small open circles. (b) Cross-sections P9–P16 of V_p for the preferred model. Meanings of symbols and colours are the same as in (a).

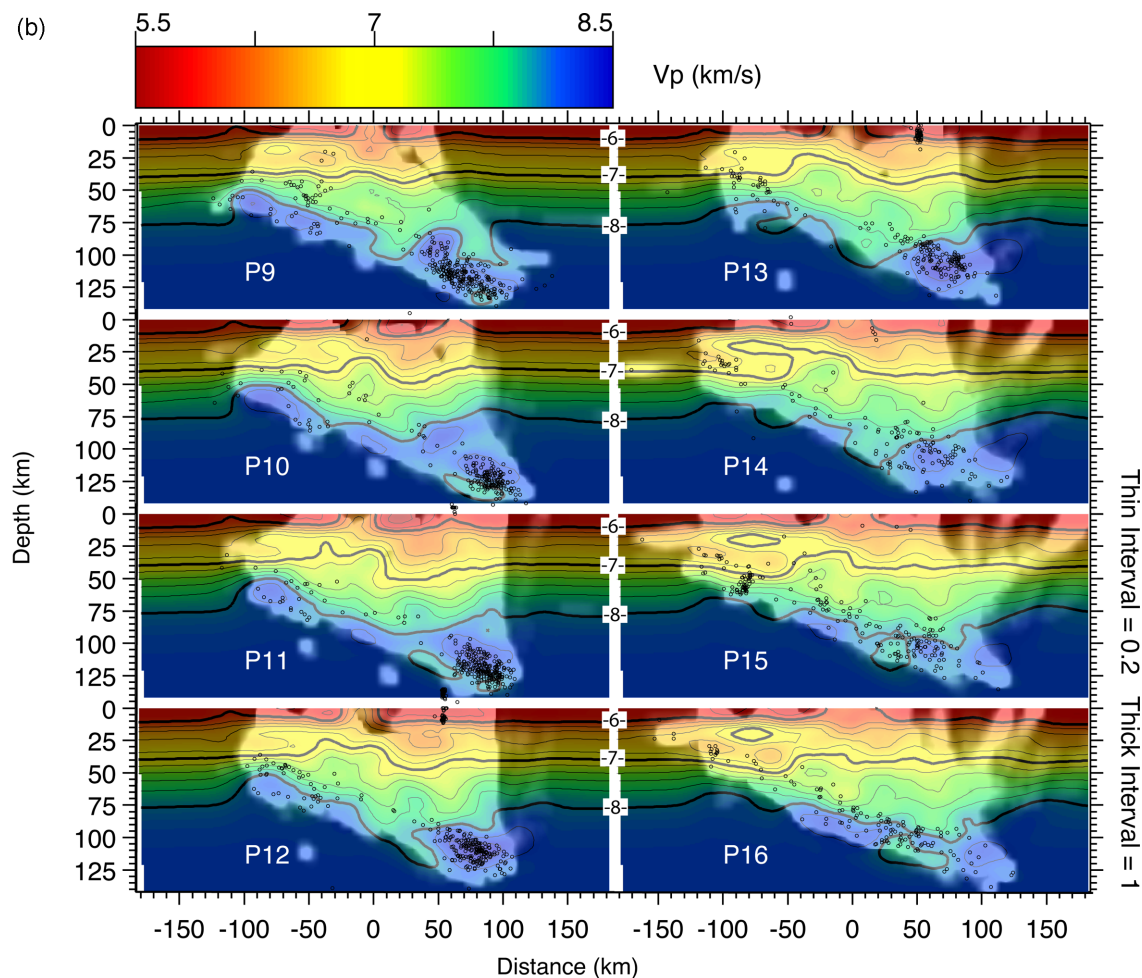


Figure 10 (Continued.)

by the SWO inversion described above, the preferred model reduces the variance in the residuals from 0.063 to 0.044 s^2 , or by about 30 per cent. The final variance is larger than the anticipated noise level variance of 0.024 s^2 , suggesting that the observations are not overfit. The body wave residual variance is slightly less than that generated by the original (and less regularized) BWO inversion (0.046 s^2) suggesting that the inclusion of the surface wave observations reduces the space of models that fit the body wave arrival times equally well. At the same time, as discussed below, these models are generally similar.

Because most of the trial runs we performed were designed to test the robustness of certain features of interest in the mantle, we mostly discuss wave speeds in the subducted slab and the supra-slab mantle (a discussion of finer scale crustal structure will appear in a companion paper). We also focus on larger scale features that our trial inversions show to be robust, in the sense that they are not overly sensitive to subjective choices concerning how the inversion is carried out.

One of the more conspicuous features of the preferred model is an ubiquitous positive gradient in V_p/V_s ratio, increasing from about 1.75 within the slab to 1.78–1.82 in the supra-slab mantle (Fig. 12). This gradient is in most cases perpendicular to the trend defined by the seismic zone and, while it varies in magnitude along strike, extends along much of the length of the slab within the mantle. Specifically, the contrast in the northern sections (P1–P8 in Fig. 12) is about 3 per cent while that in the south (P9–P16) is

closer to 2 per cent. The high V_p/V_s region also appears to extend over a significantly larger volume in the sections north of about 21° S. V_p/V_s within the slab itself is higher in the north (~ 1.76) than in the south (~ 1.74). In most sections, the supra-slab region of high V_p/V_s extends from about 40 km depth to the end of the seismic zone at about 120 km depth, and may extend to depths as shallow as 20 km in some of the northern sections (sections P1–P3 in Fig. 12a). Note that while V_p/V_s is high in the supra-slab region, both V_p and V_s are relatively low in the 40–80 km depth range (Figs 10 and 11). V_p and V_s both increase within the slab at depths of 80–100 km, and then remain high to the end of the seismic zone.

Sections with a well-defined double seismic zone at depths greater than 90 km (P1–P4 in Fig. 12) are characterized by a relatively low value of V_p/V_s in the area between the two zones. V_p and V_s at these depths are both lower in the lower part of the double seismic zone than in the upper part (e.g. sections P1–P3 in Figs 10 and 11).

4 TESTS OF RESOLUTION AND ROBUSTNESS

As no single type of trial inversion provides conclusive evidence about the quality of an image, a variety of tests with both real and synthetic data were performed to estimate the level of robustness of certain features in the preferred wave speed model. In order to account for the effects of observational uncertainty, each synthetic

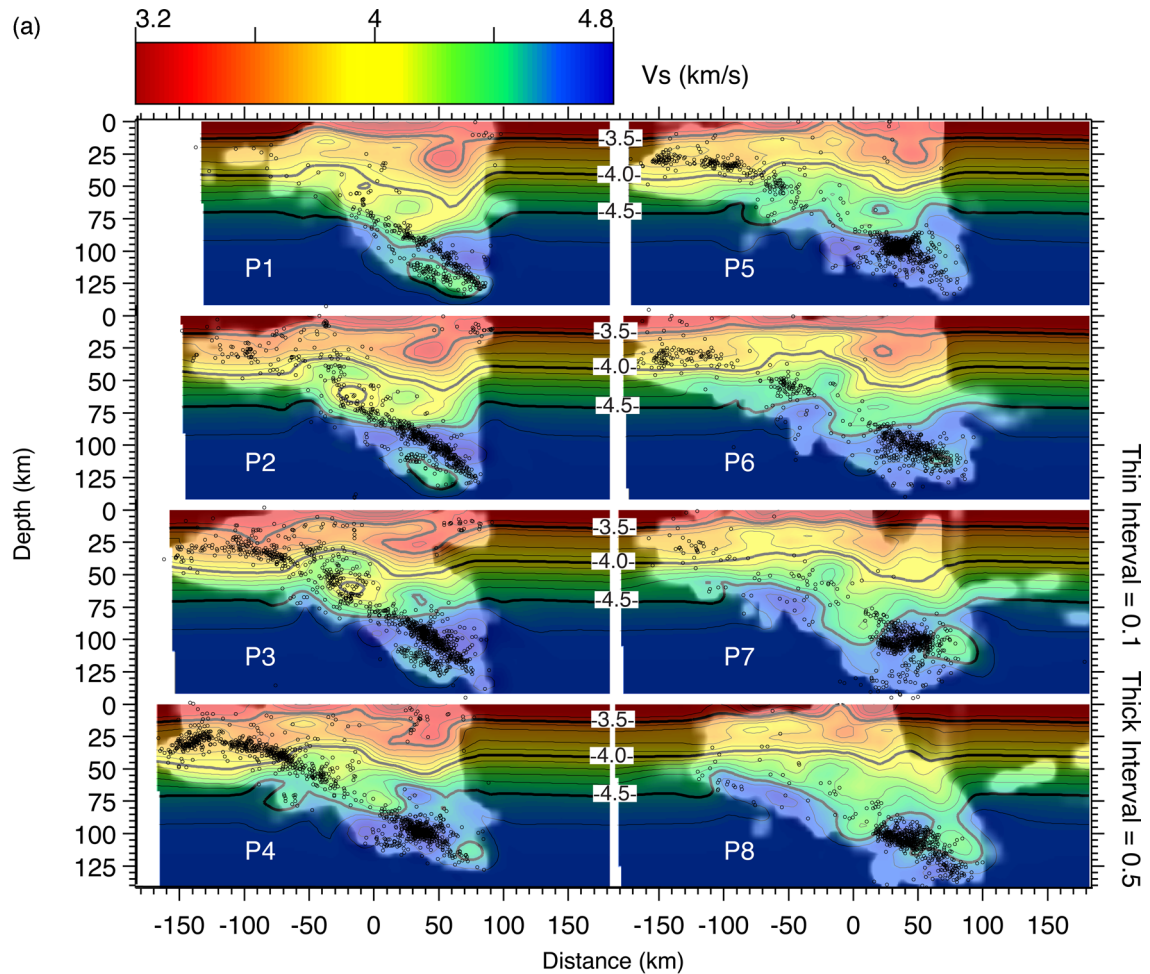


Figure 11. (a) Cross-sections P1–P8 of V_s for the preferred model. Meanings of symbols and colours are the same as in Fig. 10(a), except that the thin contour interval is now 0.5 km s^{-1} . (b) Cross-sections P9–P16 of V_s for the preferred model. Meanings of symbols and colours are the same as in Fig. 10(a), except that the thin contour interval is now 0.5 km s^{-1} .

data set is modified by random noise using a normal distribution with standard deviations that reflect the expected uncertainties in the actual data. Our main concerns are the extent to which the data can resolve the features we wish to interpret, and the dependence of the model on subjective choices made while carrying out the inversion (e.g. degree of regularization, weighting of observations, or starting model assumed).

4.1 Recovery of prismatic anomalies

A standard approach to estimating resolution in arrival time inversion is the ‘checkerboard’ test that attempts to recover alternating positive and negative perturbations in abutting prisms. We conducted versions of this test in which ± 5 per cent perturbations relative to a background 1-D model are applied to individual rectangular prisms that are $20 \times 20 \text{ km}$ in area and 10 km in depth. The perturbed elements are separated from one another by at least one prism with no perturbation so that the potential for smearing may be observed.

Results of these tests show that, in general, regions sampled with at least 10 ray paths are reasonably well recovered (Fig. 13). Moreover, despite recovered perturbations being smoothed at every iteration, the amount of smearing outside the anomaly is small over

most of the region. In the test shown here (Fig. 5), V_p and V_s are both perturbed by ± 5 per cent, with a zero V_p/V_s anomaly. The near identical recovery of V_p and V_s in this example shows that V_s can be resolved when solving for V_p/V_s rather than V_s directly, even when V_p/V_s itself is associated with a null signal.

4.2 Reconstruction of the model

While recovery of an isolated perturbation can be a fair representation of resolution of that variable, reconstruction of a prismatic pattern includes effects of coupling between perturbations that would be appropriate only if the Earth were indeed composed of alternately perturbed prisms. For example, such a representation requires 3-D ray paths to alternately focus and defocus around each perturbation.

An alternative way to demonstrate the ability of a data set to recover interpretable features at the scale and amplitude as those that appear in the model is to reconstruct the same distribution of imaged anomalies (e.g. Prevot *et al.* 1991). Hence, we generated a synthetic dataset using the same source–receiver distribution as the actual dataset and followed the same iterative procedure as with real data to attempt to recover the preferred model from a 1-D starting model. The results (Fig. 14) show that the recovered model generally

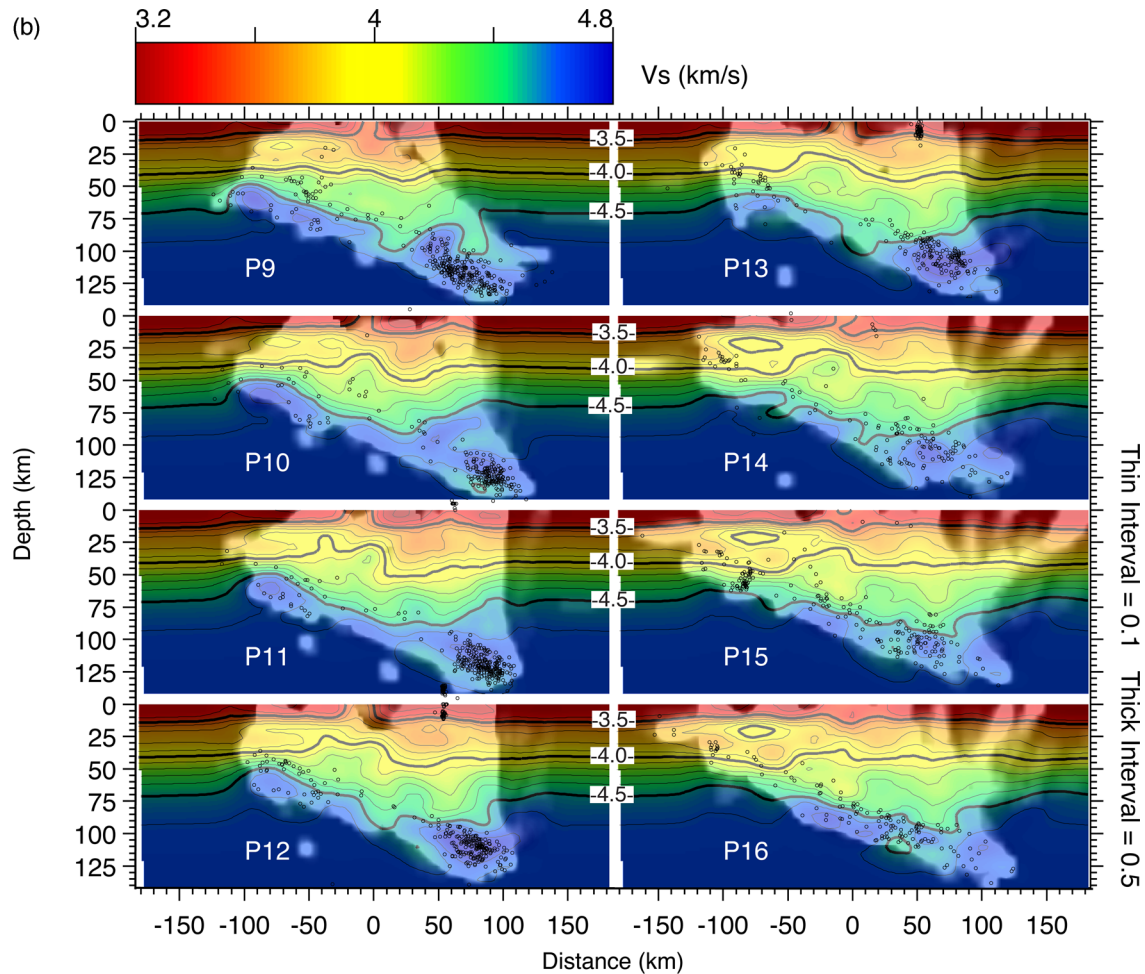


Figure 11 (Continued.)

looks very much like the true model both in pattern and amplitude, but there are some exceptions. First, while the recovered model manages to reproduce the absolute wave speeds rather well, it tends to slightly underestimate (by as much as a percent) the anomalies in the southern sections and overestimate them by a similar amount in the north. This is likely a result of the greater density of both earthquakes and stations in the north. Second, there is some lateral smearing of V_p in the northernmost sections at depths greater than about 90 km that prevents the appearance of the isolated low V_p/V_s in the true model. The reason for this lateral smearing is not obvious; indeed, one might expect that the relative abundance of seismicity in this part of the seismic zone would lead to better resolved features at depth. This smearing suggests that real earth structure in the north and at depths greater than 90 km is likely to be laterally smeared in the modelling of real data as well, and hence that the V_p and V_s anomalies are in reality smaller in lateral extent than they appear in the image.

4.3 Thin slab test

One of the main features we seek to interpret is the contrast between wave speeds in the slab and the supraslab mantle, and to test the robustness of this gradient we constructed hypothetical models by placing a thin (10 km thick) body with a relatively low V_p/V_s (1.67 versus 1.75) ratio representing that part of the slab just beneath the mantle seismicity. The purpose of this test is to investigate the

extent to which (1) localized anomalies within the slab spread across steep gradients into surrounding regions and (2) intraslab anomalies may be imaged by body waves. Several bodies with different lateral and vertical dimensions were tested; the salient results can be illustrated by models reconstructed from a V_p/V_s anomaly located in a thin (15 km thick), curved zone located along the underside of the (upper) seismic zone from about 50 km depth to the base of the model (Figs 15 and 16). We examine the resolution of lateral variations in the slab by restricting the lateral extent of one of the slab models to about 1° of latitude. As with all tests, we mimic the body wave arrival time data set used in the real inversion, but as only structure below 60 km is perturbed we do not include surface waves in a joint inversion. In this case, V_p remains at its 1-D value while V_s is perturbed to give an appropriate V_p/V_s contrast. In addition to V_p/V_s , this allows us to examine how well V_s can be recovered from estimates of V_p and V_p/V_s .

The V_p/V_s and V_s anomalies in the reconstruction (Figs 15 and 16) are both well recovered in both models at depths shallower than the deepest earthquakes (about 120 km depth) but, due to a lack of ray paths, no deeper. The thickness and location of the zone are well recovered, with very little contamination of the surrounding areas by the lower V_p/V_s in the slab, or of higher V_p/V_s from outside the slab. The upper termination of the slab at 50 km depth is also well constrained. Finally, the lateral variation in the extent of the slab is well reconstructed. At the same time, while the variations in V_p/V_s are evident in the reconstruction, the actual values are

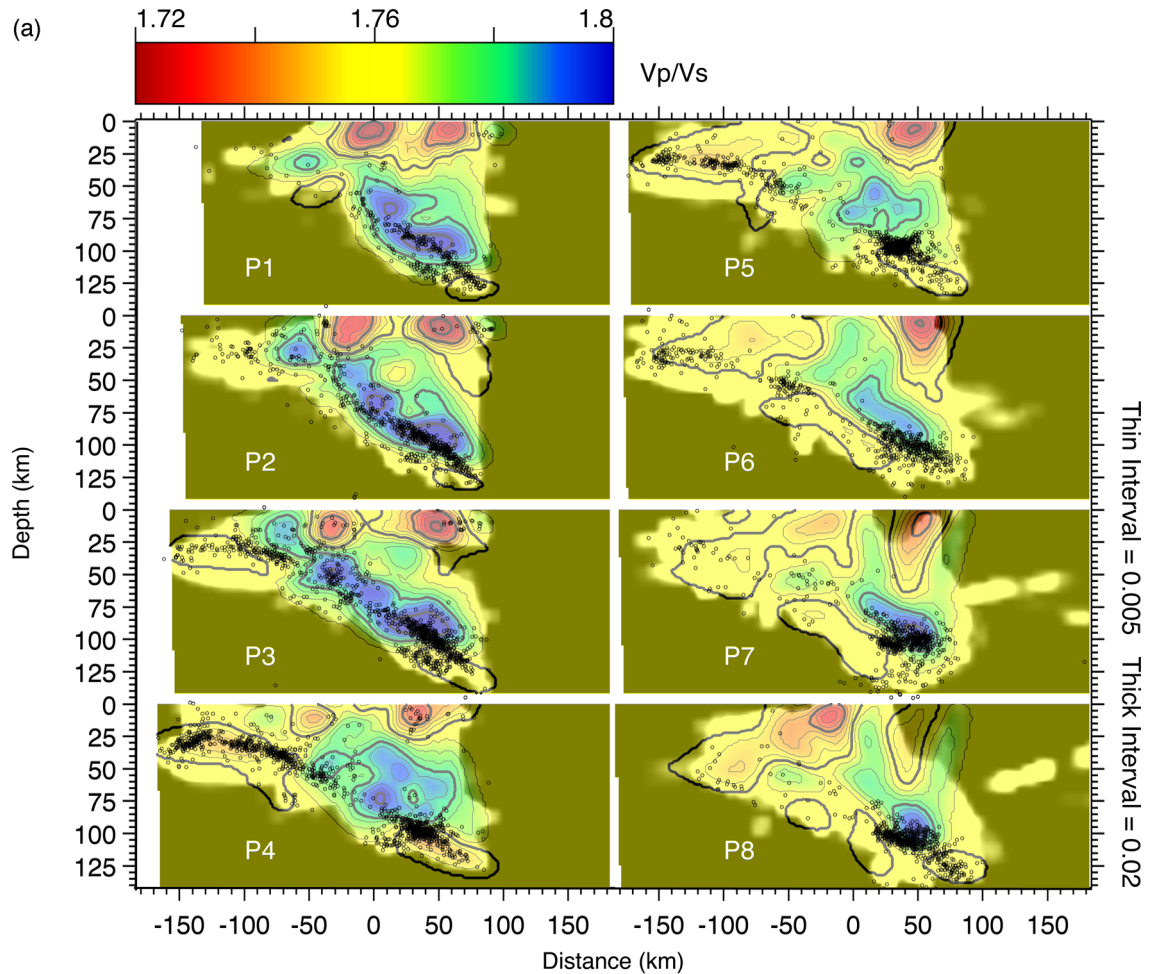


Figure 12. (a) Cross-sections P1–P8 of V_p/V_s for the preferred model. Meanings of symbols and colours are the same as in Fig. 10(a), except that the thin contour interval is now 0.005 and the thick contour interval is 0.02. Thick contour values start at 1.72. (b) Cross-sections P9–P16 of V_p/V_s for the preferred model. Meanings of symbols and colours are the same as in Fig. 10(a), except that the thin contour interval is now 0.005 and the thick contour interval is 0.02. Thick contour values start at 1.72.

underestimated in much of the slab and show intraslab heterogeneity on the order of 0.026 along its strike and dip.

4.4 Smoothing, weighting and starting models

Among the subjective assumptions made as part of the joint inversion are the extent to which the model is smoothed, the relative influence of different data types, and the starting model chosen. Several tests were performed varying each of these assumptions individually, and the general conclusions can be summarized in a few comparative tests. Specifically, the BWO inversions discussed above use a different set of data (no surface waves), a different starting model (the 1-D Antofagasta model of Husen *et al.* 1999), and/or a shorter smoothing window (± 1 node about the centre) than that used to generate the preferred model. A comparison of BWO models with different moving average window lengths (top and bottom panels in Fig. 17) shows that, as may be expected, the effects of smoothing are akin to passing the rough model through a low pass filter. All of the first order features that we see in the smoothed model can be identified in the rough one, but the fit to the data using the rough model is only marginally better (by about 5 per cent in variance). The difference between the BWO and joint models arises partly from the difference in starting model; in particular, the

Moho transition is more gradual in the joint model than the BWO models. Moreover, the inclusion of surface waves helps constrain the wave speeds in the upper few tens of km. These choices account for differences in the supraslab mantle wave speeds determined by the BWO inversion. For example, the lower wave speeds in the upper mantle in the BWO model are likely compensating for crustal thickening towards the central Andes. Indeed, the added constraint on crust and uppermost mantle structure provided by surface waves is a principle motivation for a joint inversion. Note that while the rough BWO model manages to fit the body waves better than the joint model by about 2 per cent, the joint model does a slightly better job (by 3 per cent) than the equally smoothed BWO model. Of course, neither of the BWO models manages to fit the surface wave data nearly as well as the joint model (surface wave variance in the joint model is reduced by about 70 per cent compared to that in either of the BWO models).

Creating a starting model for a joint inversion from the results of an SWO inversion requires a choice of V_p/V_s ratio. As discussed above, a V_p/V_s of 1.76 is consistent with the arrival times in the body wave data set. At the same time, tests with a range of values from 1.73 to 1.78 shows that while the patterns and gradients in V_p/V_s are virtually invariant, the average value of V_p/V_s remains close to its starting value. The fit to the entire data set is better with a V_p/V_s of

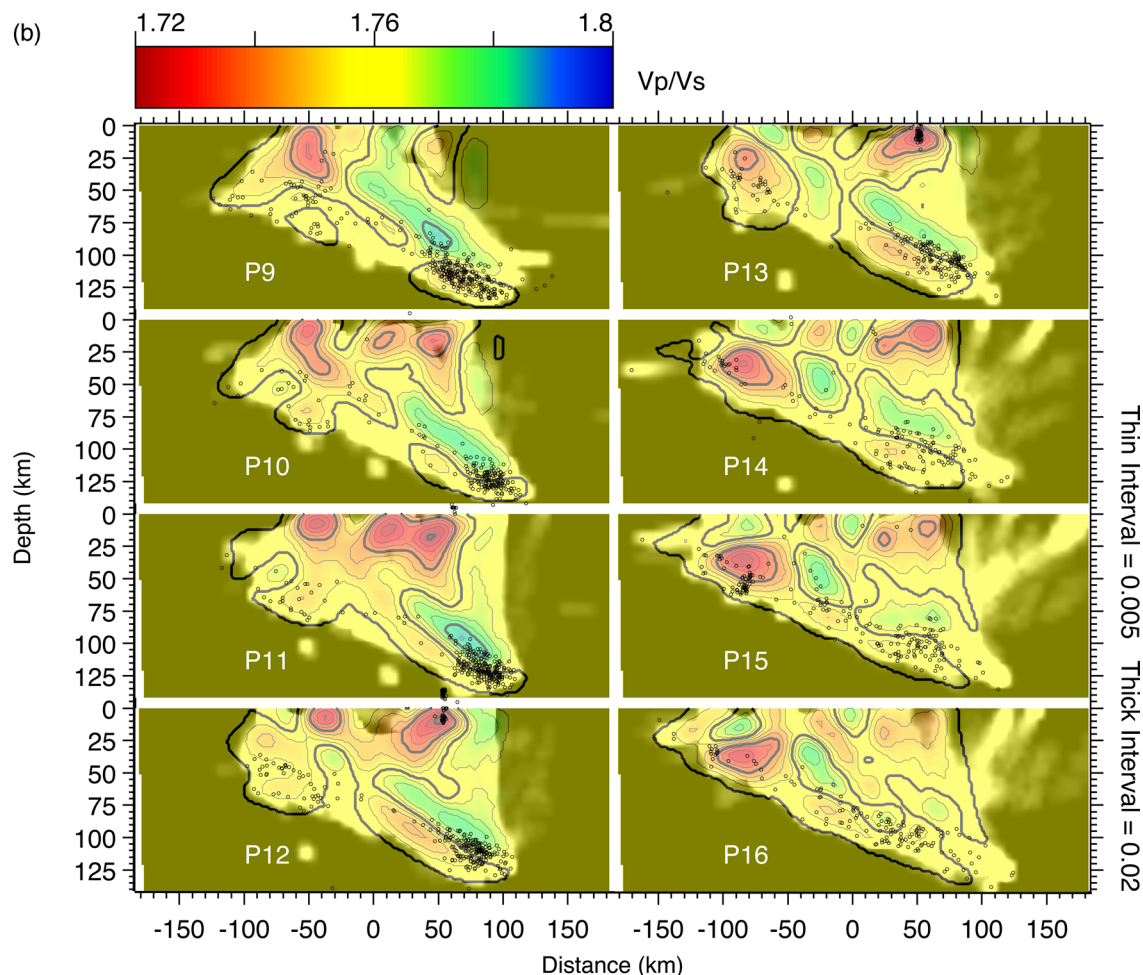


Figure 12 (Continued.)

1.76 than with either 1.73 or 1.78 (by about 3 per cent), and is nearly the same as 1.75. Moreover, there are about 1100 earthquakes (or roughly 10 per cent of the entire dataset) distributed throughout the study area, for which the fit to the data improves on an event by event basis with a V_p/V_s of 1.76 (Fig. 18). Since events are relocated prior to each iteration, the minimization of residuals on an event by event basis is a valid metric for judging the significance of a given model, and on this basis, as well as the improvement in overall variance, we take the model generated with a starting value of 1.76 as the preferred model.

4.5 Inferences from trial results

As a result of the trials described above, we conclude that the first order features in the preferred model are robust. Specifically, the increase in V_p/V_s , from the subducted slab into the supraslab mantle, as well as the size and location of the high V_p/V_s regions, appear well constrained. These features are reasonably independent of the starting model, but the actual values of V_p/V_s tend to stay close to the starting value. Nevertheless, we can appeal to a preference of the data for a certain range of V_p/V_s to argue for an optimal value. While large gradients in V_p , V_s and V_p/V_s are well constrained, localized regions with small changes (on the order of 1 per cent in velocity and 0.017 in V_p/V_s) are probably not significant. We are less confident in features in the model at depths greater than about 110 km. Although tests that recover specific features such as a low

V_p/V_s in the region between the deeper parts of the double seismic zone were successful, other tests suggest lateral smearing may blur the image.

5 DISCUSSION

5.1 Hydration of the supraslab mantle

The most conspicuous first order features in our preferred model are (1) the gradient from low to high V_p/V_s from the slab into the supraslab region, mostly at depths greater than about 40 km, along the entirety of the northern Chile margin, and (2) the extensive region, particularly north of about 21°S, of $V_p/V_s > 1.8$ located mostly above the interface between the slab and the supraslab mantle as represented by the Wadati-Benioff Zone (WBZ) earthquakes. This high V_p/V_s region is also characterized by relatively low values of V_p and V_s to depths of about 80 km. Because the introduction of fluids into the mantle can decrease both V_p and V_s and increase V_p/V_s by either partial melting (e.g. Hammond & Humphreys 2000; Karato 2012) or serpentinization (e.g. Christensen 1996, 2004; Ji *et al.* 2013), a viable explanation of these features is the dehydration of the subducted slab and the release of volatiles into the supraslab mantle. Variations on this scenario have been suggested in previous studies of subduction zones (e.g. Kamiya & Kobayashi 2000; Bostock *et al.* 2002; DeShon & Schwartz 2004; Eberhart-Phillips & Bannister 2010; Zhang *et al.* 2010) including northern Chile (e.g. ANCORP

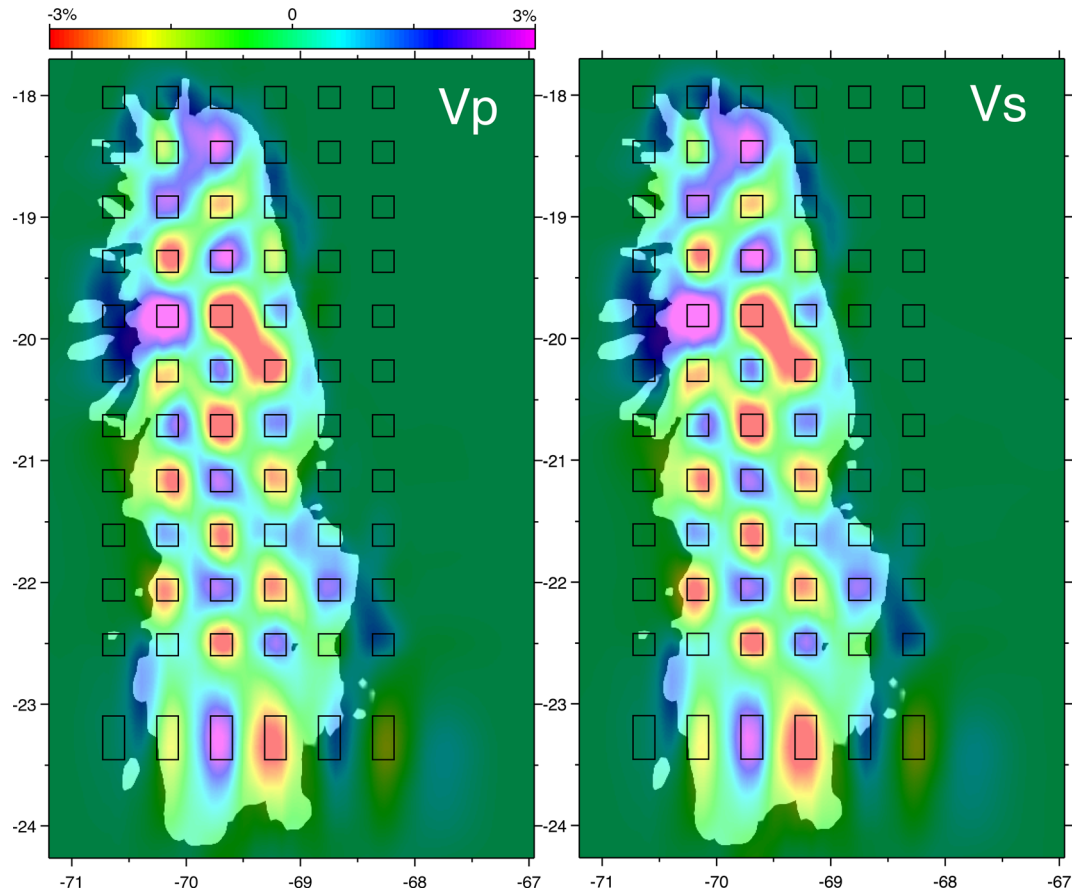


Figure 13. Map view of results of the prism reconstruction test at 50 km depth for V_p (left-hand panel) and V_s (right-hand panel). Values are indicated by the colour palette in the upper left-hand part of the figure. The plots are shaded to reflect density of sampling, with the brightest regions corresponding to regions sampled by at least 10 ray paths. The rectangles locate the bounds of the prisms that are perturbed from the background 1-D model. Note that the reconstructed images are nearly identical for V_p and V_s .

Working Group 2003). Our results suggest that the way in which the mantle is hydrated can depend not only on the type of convergent margin, but on variations in the subduction environment within a particular margin type.

Locating the supraslab mantle along the Andean margin requires an estimation of both the continental Moho and the top of the subducting Nazca Plate. The latter is assumed to coincide with the upper boundary of the WBZ earthquakes. The depth of the continental Moho is known to some extent from previous studies in this area (Beck *et al.* 1996; Yuan *et al.* 2000, 2002; McGlashan *et al.* 2008) that suggest that the thickness of the continental crust increases from about 40 km beneath the Coastal Cordillera and Central Depression to about 60 km under the Western Cordillera. Hence, the supraslab mantle ‘wedge’ at depths of 40–60 km is more like a channel with a width of perhaps a few 10 s of km. Most sections of our model (Figs 10 and 11) show a prominent east-dipping gradient in V_p and V_s between 40 and 60 km depth about 25 km above the top of the WBZ that we interpret as the crust to mantle transition.

V_p and V_s are both low (~ 7.2 – 7.6 km s $^{-1}$ and 4.1 – 4.3 km s $^{-1}$, respectively), and V_p/V_s is generally high (1.78–1.80), within the supramantle at depths between about 40 and 80 km depth, with the more extreme values found in the northern sections. These trends are consistent with serpentinization of this part of the mantle. Thermomechanical modelling of the subducting Nazca Plate (Dorbath *et al.* 2008) suggest that temperatures are cold enough at these

depths (< 700 °C) for serpentinite to be stable (Ulmer & Trommsdorff 1995).

In most cross sections, a gradient in V_p , V_s and V_p/V_s collocates with the upper part of the WBZ, and correlates quite well with the ‘Nazca Reflector’ seen in both receiver function (Yuan *et al.* 2000) and active source (ANCORP Working Group 2003) imaging. Note that while there is a positive gradient in V_p and V_s from the supraslab mantle into the interior of the slab, V_p and V_s within the slab are low. In the northern sections, V_p/V_s within this part of the slab is high, suggesting the presence of serpentinite within this part of the slab. These contrasts are greater north of 21°S, suggesting more significant hydration of the subducted slab in the north.

While estimates derived from the existing literature disagree on the extent to which this part of the mantle is serpentinized, the reduced V_p and V_s combined with increased V_p/V_s is consistent with higher levels of serpentinization in the north. For example, the high P-T model of Ji *et al.* (2013) would predict ~ 45 per cent serpentinite in the south and ~ 70 per cent in the north, while predictions from the dunite-antigorite model of Christensen (2004) are closer to 30 and 42 per cent (Fig. 19).

V_p and V_s both increase in the WBZ between 80 and 100 km and reach 8.2 and 4.6 km s $^{-1}$, respectively. V_p/V_s remains high below 80 km, and in fact is higher in the 80–120 km depth range than anywhere else in the model. For the most part the highest V_p/V_s is in a narrow zone that runs more or less parallel to the WBZ. As with the shallower parts of the model, V_p/V_s is in general much higher in the

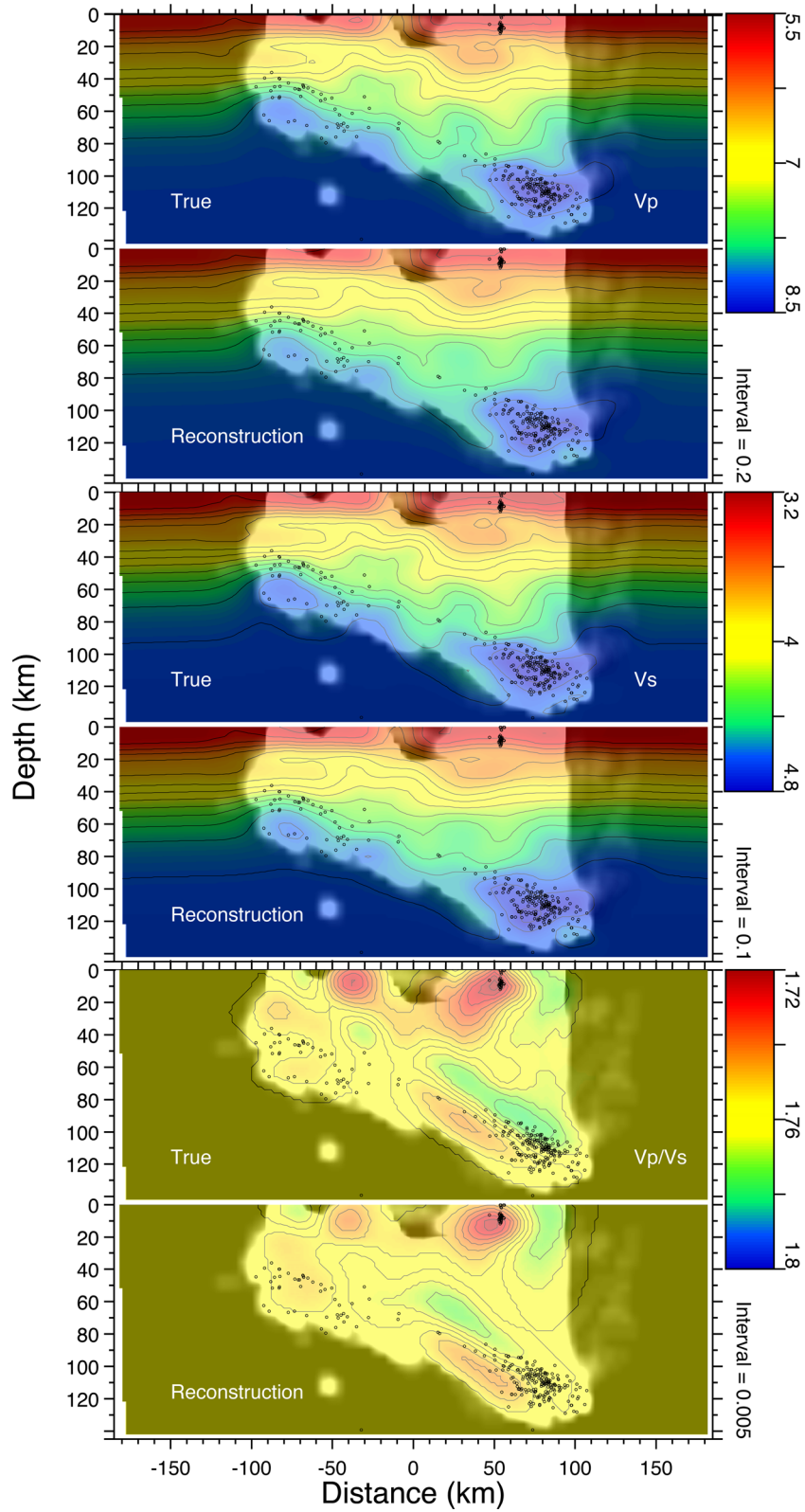


Figure 14. Results of the reconstruction tests for V_p (top two panels), V_s (middle two panels) and V_p/V_s (bottom two panels). In each case the ‘True’ model, taken from the preferred model, is shown at the top, and the reconstructed model directly beneath. These sections correspond to P12 in Figs 4 and 10–12.

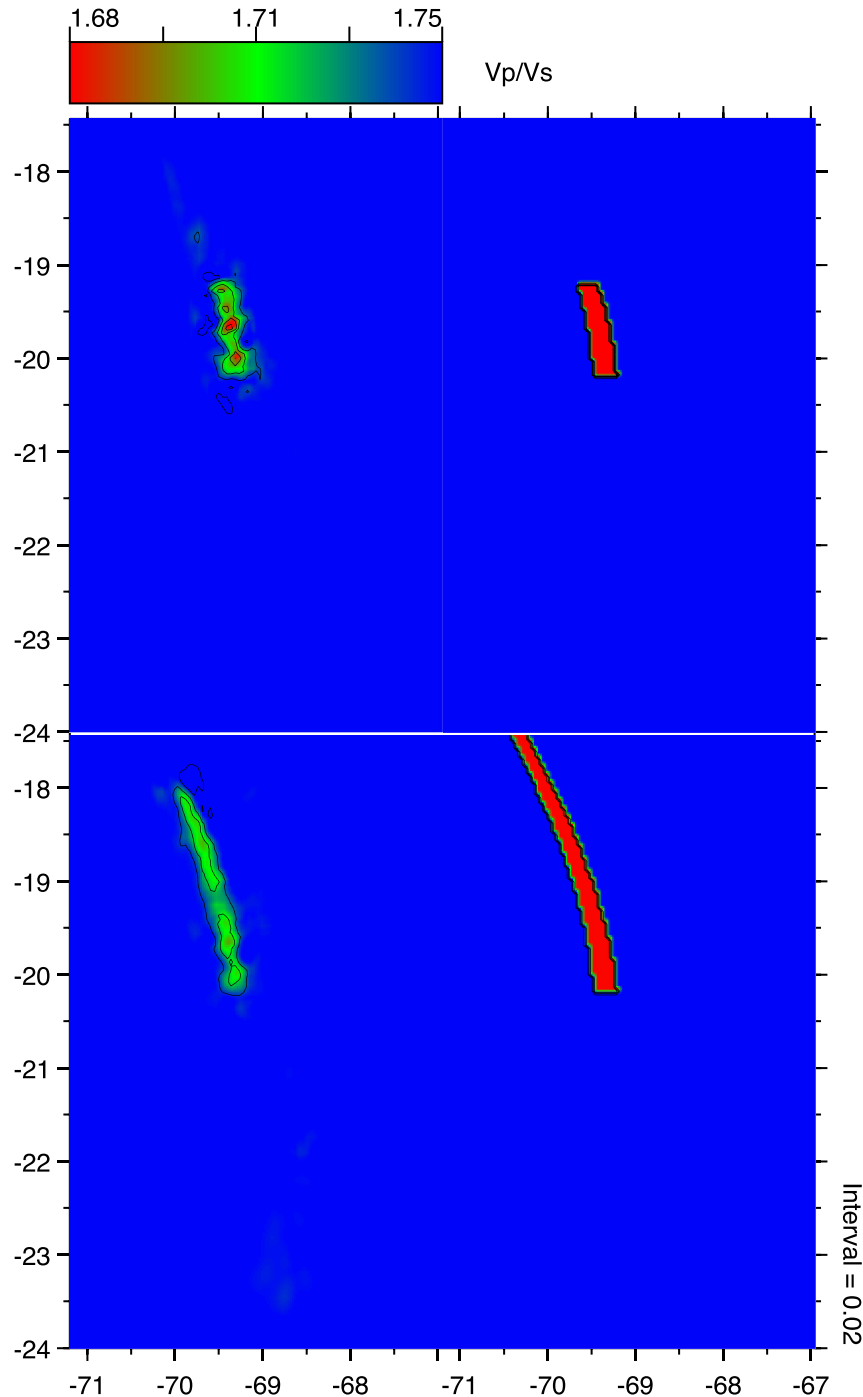


Figure 15. Map views of V_p/V_s for the short (top panel) and long (bottom panel) hypothetical slab models shown at 100 km depth. The true model is at the right, and the reconstructed model is at the left.

north (1.82) than in the south (1.78). Combined with the normal to high V_p and V_s in the supraslab mantle below 80 km depth, plus the instability of serpentinite at higher temperatures in this part of the mantle, we infer that this part of the supraslab mantle is partially melted. Based on the model of Hammond & Humphreys (2000), the observed increase in V_p/V_s could be achieved with a melt fraction of about 1 per cent in the north and less than half of that in the south.

We interpret the large, downdip positive gradient in V_p and V_s within the slab at depths between about 80 and 100 km to be a consequence of accelerated phase transitions from basalt to eclog-

ite in the crust and from serpentinite to peridotite in the mantle of the slab. The region of high V_p/V_s extends nearly the length of seismic zone but returns to average values at about 120 km depth, suggesting that phase transitions within the slab have ceased at this depth. The increased level of seismic activity between 100 and 130 km depth is indicative of higher rates of phase transition. Therefore, as similarly suggested by Yuan *et al.* (2000), the lessening of wave speed contrasts between the WBZ and the supraslab mantle at these depths could signify the completion of phase transitions in the slab.

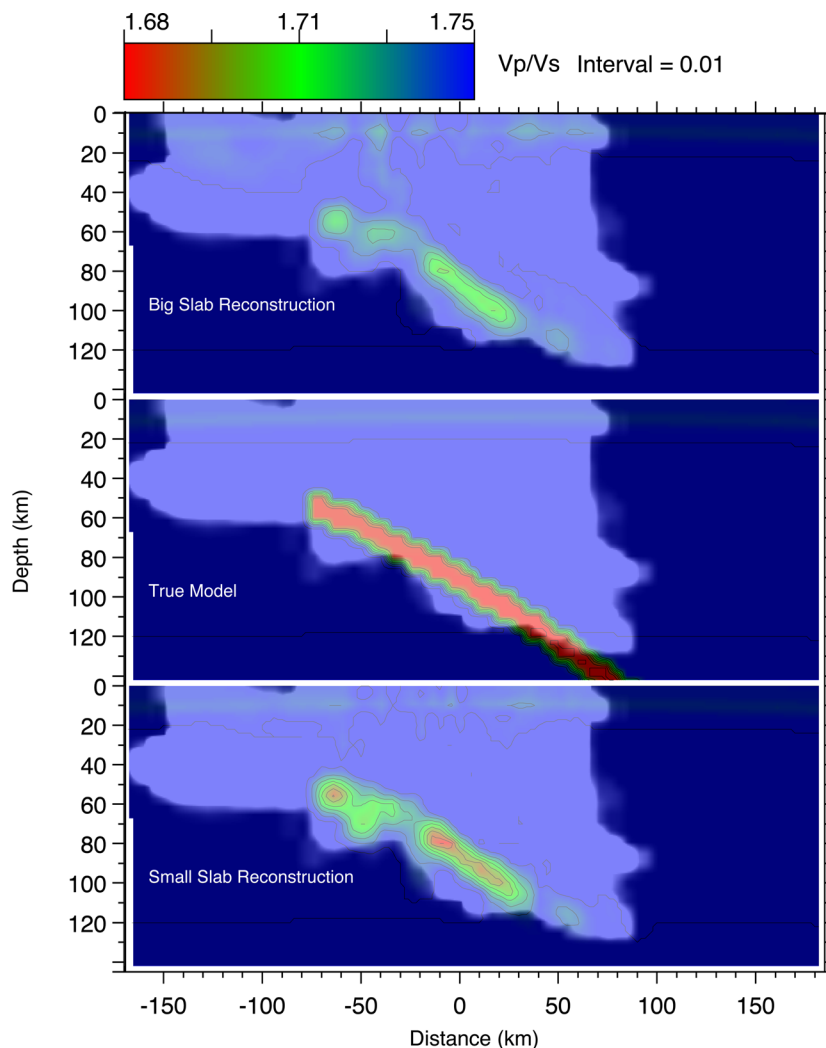


Figure 16. Cross-section views reconstruction of V_p/V_s for the long (top panel) and short (bottom panel) slab models shown at 20°S. The true model is shown in the middle. Bright areas are those sampled by 10 or more rays. This section corresponds to P5 in Fig. 4.

5.2 The north–south contrast and surface geology

As discussed above, while the influence of water in the slab and supraslab mantle can be seen all along the northern Chile subduction zone, there are some significant differences between the northern and southern parts of the model, mostly having to do with the size of the anomalies and the volumes over which they occur. These differences are gradational, but the largest gradients occur at about 21°S. The most significant of these is the extent of the region of high V_p/V_s , which, as discussed above, we associate with hydration resulting either in serpentinization of peridotite or the presence of partial melt. The difference in the size of this region (Fig. 21) north and south of 21°S suggests a more profound influence of water in the north.

We note that the oldest (>50 Ma) oceanic lithosphere subducted along the Nazca–South American plates boundary is located along this part of northern Chile (Fig. 2). Because the effective elastic thickness of oceanic lithosphere and the depth to the brittle–ductile transition increases with age, older oceanic lithosphere has a higher water reservoir capacity (Watts 2001; Contreras-Reyes & Osses 2010; Contreras-Reyes *et al.* 2011). Hence, the effects of dehydra-

tion are likely to be more apparent here than anywhere else along the Andean margin.

The northern region is much more seismically active in the 70–145 km depth range (prior to the 2104 Pisagua earthquake, the rate of activity was about twice as high in the north), consistent with earthquake activity being related to rates of dehydration reactions (Kirby *et al.* 1996; Omori *et al.* 2002, 2004). Moreover, there is a shift in the locations of the deeper hypocentres to the east south of 21°S (Fig. 4), meaning that the dip of the slab is less in the south. An explanation consistent with dehydration is that the greater loss of volatiles in the north leads to increased production of eclogite within the subducted slab (e.g. Hacker *et al.* 2003; Green *et al.* 2010), which in turn increases its negative buoyancy.

There is also a north–south difference in patterns of volcanic activity. In particular, the northern part is associated with an anomalous volume of Neogene ignimbrite deposits (Wörner *et al.* 1994; Wörner *et al.* 2002), which is consistent with a larger percentage of volatiles in the ascending magma. Interestingly, the southern boundary of the large hydrated region has an extended region of low V_p/V_s near the surface that corresponds to the location of the Pica gap in volcanism (Wörner *et al.* 1994; Figs 1 and 2). The northern part

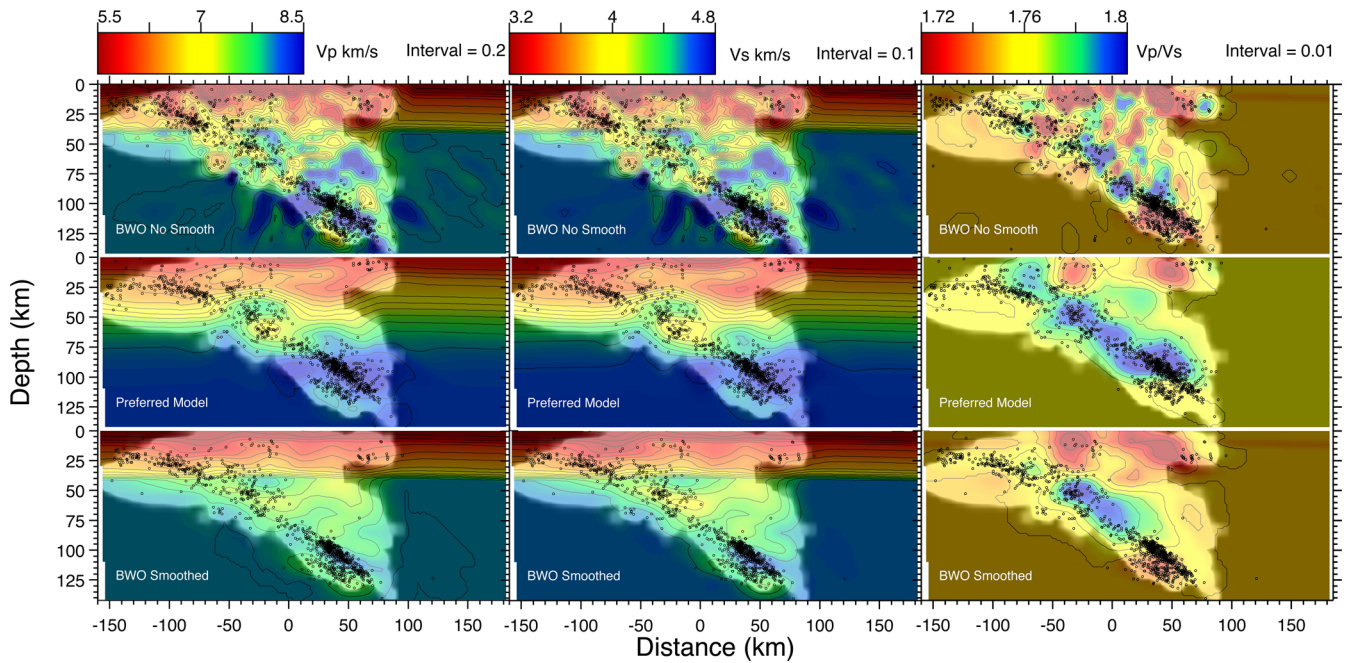


Figure 17. Comparison of models generated with body waves only (BWO) with minimal smoothing (top row), the preferred model (middle row), and BWO with the same smoothing as the preferred model (bottom row). Shown are V_p (left-hand column), V_s (middle column) and V_p/V_s (right-hand column). Bright areas correspond to regions sampled by at least 10 rays. Each cross section corresponds to P3 in Fig. 4.

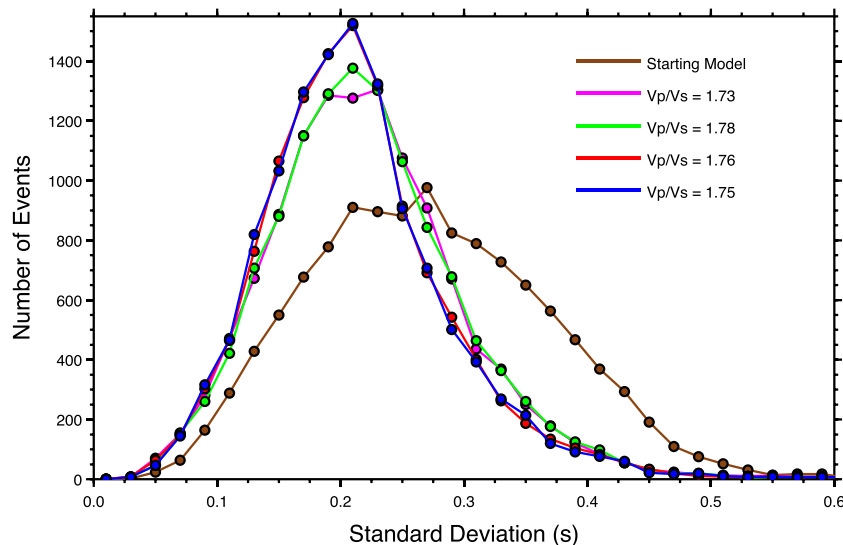


Figure 18. Histogram of the number of earthquakes with standard deviations within bins of 0.05 s for different choices of V_p/V_s in the starting model. Note that while results from V_p/V_s of 1.75 (blue) and 1.76 (red) are nearly the same, these choices reduce the standard deviation for more than 1100 events when compared to low (1.73) and high (1.78) values. The starting model refers to the 1-D SWO model shown in Fig. 8.

also has prominent linear topographic scarps that deform Neogene to Pleistocene deposits along the forearc, including portions that overlie the interplate zone and the Precordillera piedmont. While these are dramatic topographic features, their activation mechanism remains poorly understood (i.e. Armijo & Thiele 1990; González *et al.* 2003; Allmendinger *et al.* 2005; Fariás *et al.* 2005; Loveless *et al.* 2005; González *et al.* 2008).

The inferred regions of enhanced hydration correlate with the occurrence of megathrust earthquakes along this part of the margin. The high V_p/V_s at depths below 40 km is consistent with the downdip

extent of large megathrust events being limited by serpentinization (e.g. Hyndman & Peacock 2003). High V_p/V_s also extends up to 20 km depth between 19° and 19.8°S (sections P1–P3 in Fig. 12), suggesting the presence of significant amounts of water at shallower depths along the plate boundary. The importance of fluids for interplate coupling and hence for rupture mechanics is well known (e.g. Tsuji *et al.* 2008; Nakajima *et al.* 2009; Uchida *et al.* 2009; Abers *et al.* 2013), and appears here in a seismic gap capable of generating a $M_w \sim 9.0$ megathrust earthquake. Recent geodetic studies (Métois *et al.* 2013; Ortega-Culaciati *et al.* 2015, Fig. 2) show a

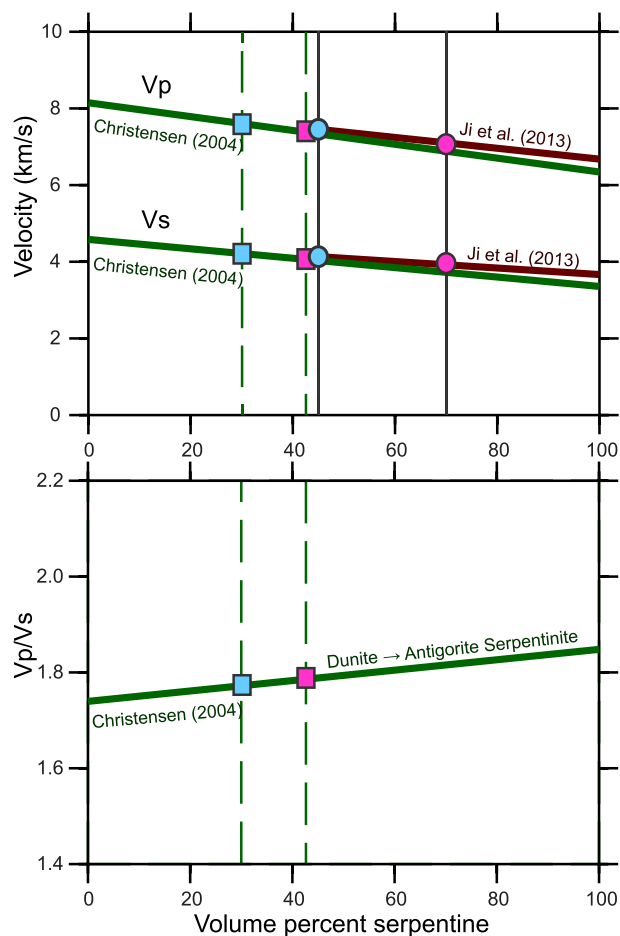


Figure 19. Values of V_p , V_s and V_p/V_s taken from the mantle wedge region of the preferred model for regions north (red symbols) and south (blue symbols) of 21°S, plotted on the Dunite-Antigorite model of Christensen (2004) (squares) and the high PT measurements of Ji *et al.* (2013) (circles). Note that while the estimates of serpentine per cent vary significantly, both correspond to a higher percentage north of 21°S.

heterogeneous distribution of interseismic coupling within this gap, with the north (18°–20.5°S) being significantly less coupled than the south (20.5°–23°S). This less coupled region correlates well with the shallow distribution of high V_p/V_s (Fig. 20), suggesting that hydration of the interface along the interplate contact controls the level of coupling.

These contrasts in the effects of hydration should be related to variations in the level of hydration of the Nazca plate. While it is difficult to know the initial conditions of the subducted plate, there presently is a succession of seamounts located on a larger swell on the Nazca plate, referred to as the Iquique ridge, that intersects the trench at about 21°S (Contreras-Reyes & Carrizo 2011; Figs 1 and 2). An extrapolation along the azimuth of this ridge into the subducted slab corresponds to the large region of high V_p/V_s that we see in the north. Because seamounts should be accompanied by enhanced hydrothermal circulation in the lithosphere, the subduction of the Iquique ridge could account for what we interpret as the elevated hydration of the supraslab mantle in this region. Note that this in turn suggests an additional role for subducted seamounts in the generation of megathrust earthquakes beyond the expected roughening of the plate boundary (e.g. Cloos & Shreve 1996; Scholz & Small 1997; Contreras-Reyes & Carrizo 2011; Geersen *et al.* 2015).

5.3 Comparison with other studies in northern Chile

A number of local seismic investigations of the crust and upper mantle beneath this part of the Andean margin have been published (e.g. Comte *et al.* 1994; Schmitz & Kley 1997; Graeber & Asch 1999; Patzwahl *et al.* 1999; Schmitz *et al.* 1999; Yuan *et al.* 2000, 2002; ANCORP Working Group 2003; Schurr *et al.* 2003; Rietbrock & Waldhauser 2004; Koulakov *et al.* 2006; Dorbath *et al.* 2008; Bloch *et al.* 2014). We note that the tomographic study of Graeber & Asch (1999) of the PISCO network deployed between 21°S and 25°S shows (1) a similar contrast of V_p/V_s from about 1.70 in the slab to 1.80 in the supraslab mantle, (2) extensive regions of low V_p/V_s (<1.70) in the crust, consistent with a largely felsic (i.e. granitic) lithology (Christensen 1999) and (3) a large increase in V_p from about 7.5 to >8.5 km s⁻¹ within the slab in the 80–100 km depth range. A similar change in V_p within the slab was determined as well by Comte *et al.* (1994).

As discussed above, the Nazca Reflector (NR) imaged by the Andean Continental Research Project (ANCORP) EW seismic reflection profile at 21°S (ANCORP Working Group 2003) aligns with the gradient in V_p and V_s found in our model. The high amplitude reflections of the NR terminate abruptly at 80 km depth, corresponding in our model to the increase in V_p and V_s to levels found in the surrounding mantle. Bloch *et al.* (2014) interpret the NR as an indicator of enhanced hydration, and suggest that a region of increased reflectivity above the NR to about 20 km depth corresponds to pathways for fluids within the crust and supraslab mantle, similar to those conjectured in previous studies (Springer 1999; Schurr *et al.* 2003; Koulakov *et al.* 2006). We note that this shallower region of enhanced reflectivity corresponds to a region of high V_p/V_s seen in sections P7 and P8 (Fig. 12a) that are closest to the ANCORP line.

The tomographic study of Dorbath *et al.* (2008) overlaps the northern section of our region (~18°–20°S). Their estimates of V_p and V_s in the upper WBZ show the same increases from low to high values at about 80 km depth as our model. In fact, V_p in their section P3 looks quite similar to section P3 in Fig. 10(a), including the decrease in V_p in the lower seismic zone at depths >90 km. At the same time, their estimates of V_s in the lower seismic zone, generally >5 km s⁻¹, are significantly higher than our estimate (~4.4 km s⁻¹). As a result, they deduce (by division) a low V_p/V_s (~1.68) in this part of the double seismic zone, in contrast to our value of 1.76. Our model does show a region of low V_p/V_s , but it appears in the region between the two zones. Dorbath *et al.* (2008) also do not find any coherent increase in V_p/V_s in the supraslab region, which is a dominant feature in our model. While the causes are not easily discerned, these differences in results are most likely due to differences in data and methodology.

6 CONCLUSIONS

Based on the results of this investigation and a comparison with results from previous studies in this and other subduction zones, we infer that the main features we observe are a consequence of dehydration of the subducting slab, phase transitions from basalt to eclogite and serpentinite to peridotite within the slab, and the hydration of the supraslab mantle. As summarized in Fig. 21, fluids from the subducting Nazca plate serpentinite the supraslab mantle between 40 and 80 km depth. At depths between 80 and 100 km, the phase transformations within the slab accelerate, resulting in higher wave speeds and more intense seismic activity. Water released into the supraslab mantle at these depths induces partial melt which

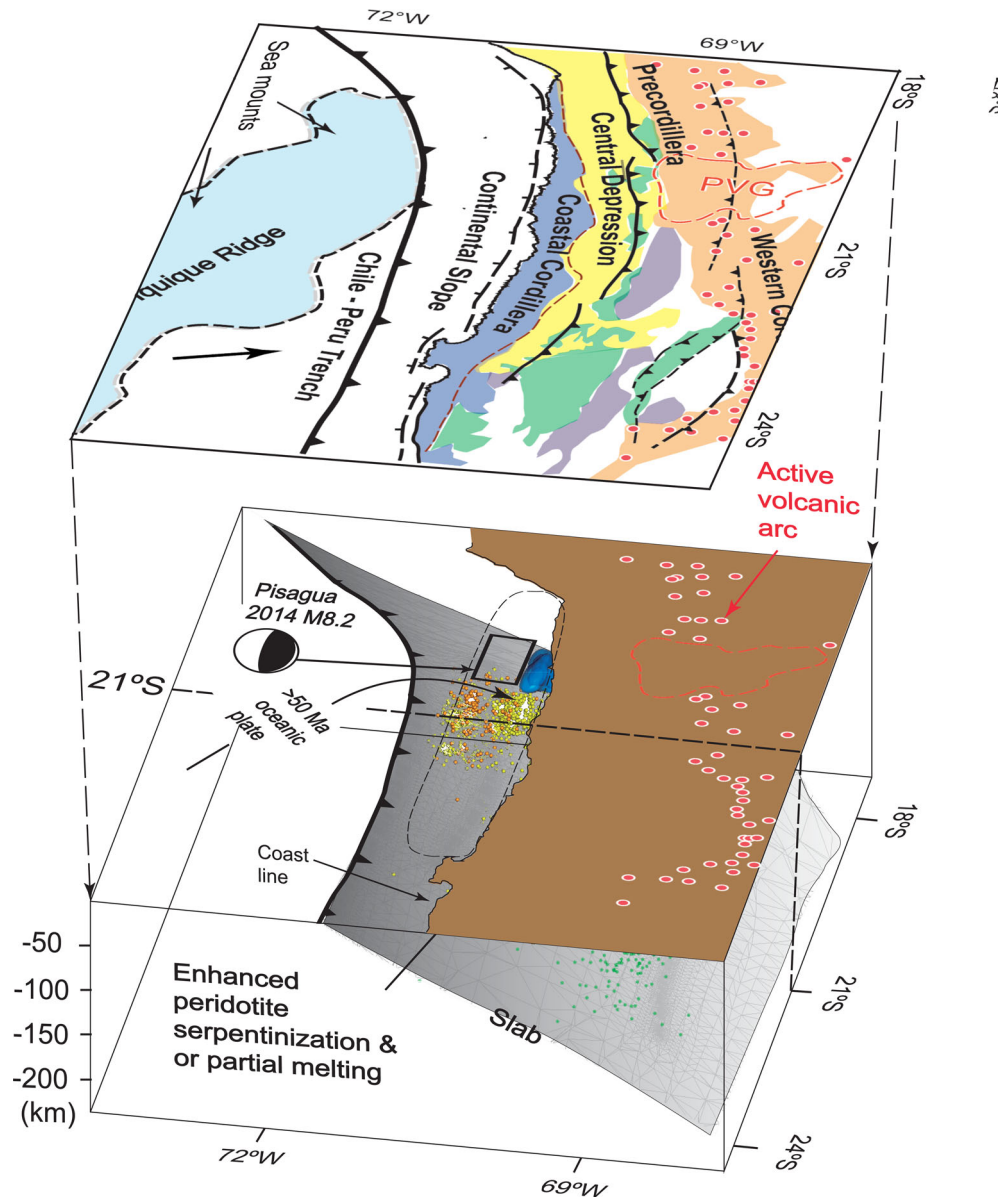


Figure 20. Tectonic context of the region of high V_p/V_s (>1.78) as shown by a blue surface that envelopes the volume. Most of this region is located in the supraslab mantle north of 21°S , and may extend close to the surface in the region where there 2014 Pisagua earthquake occurred. Seismicity is plotted as small circles filled with colours representing depth range as shown in Fig. 4. Active volcanoes are shown by red circles. The dashed red line is the Pica gap. The volume within the blue surface represents a region of enhanced hydration leading to supraslab hydration and partial melting, particularly north of 21°S .

makes its way up to the active arc in the Western Cordillera. At the end of the seismic zone at 140 km depth, the slab is dehydrated and the phase transformations are complete.

We note that this scenario is similar in many respects to that proposed by Oncken *et al.* (2003) for the ANCORP results at 21°S from an entirely different set of observations. The current study reveals a significant contrast in the effects of hydration north and south of this latitude. We attribute the more intense effects in the north to a gradient in the level of hydration in the subducted Nazca plate that eventually results in a release of larger volumes of water into the supraslab mantle. These larger quantities of water also appear to influence the nature of volcanism in the magmatic arc and the coupling of the plate boundary at depths of 20–40 km. We suggest that the cause of this greater in-

flux of water is the subduction of the Iquique ridge on the Nazca Plate.

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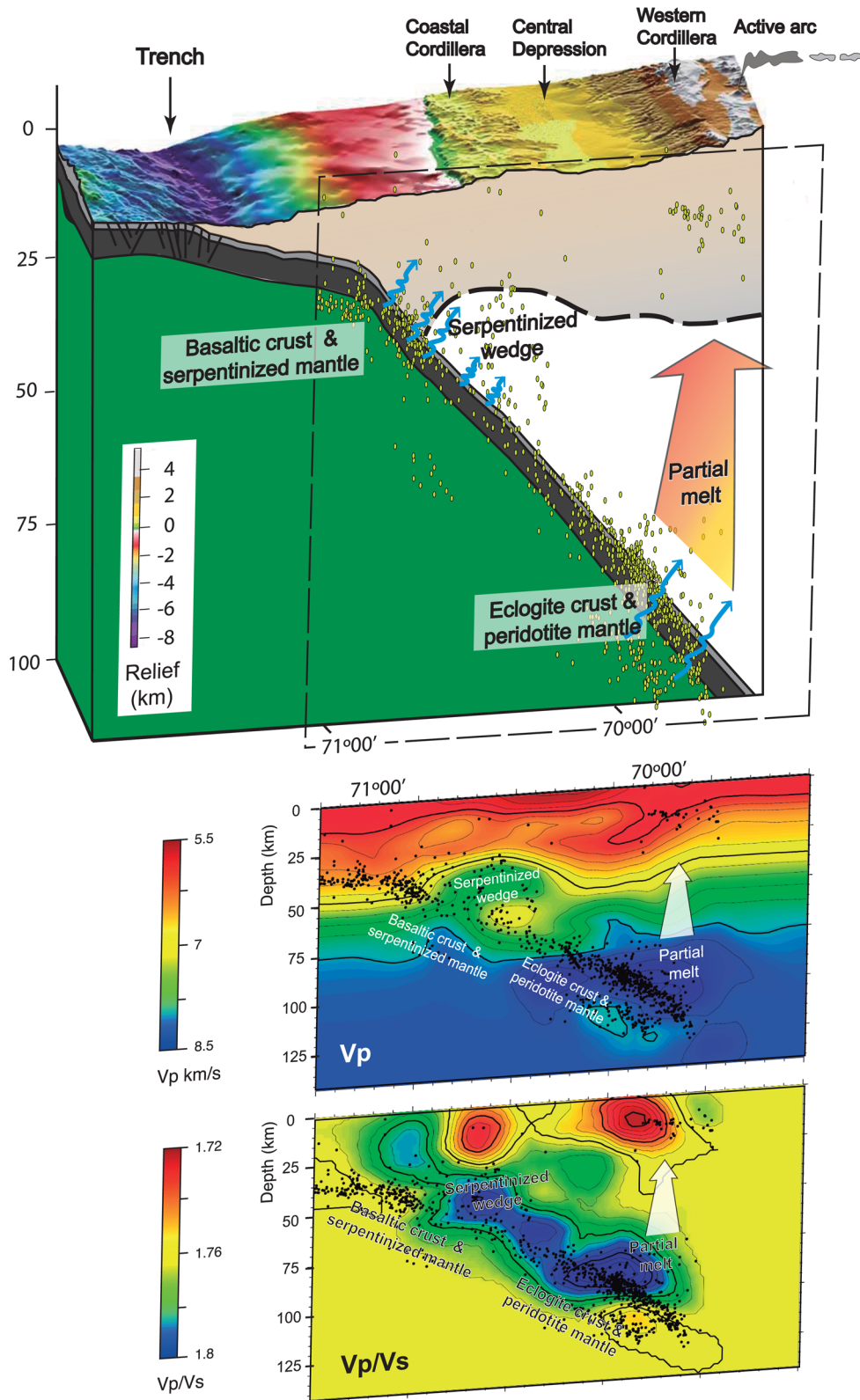


Figure 21. Summary of the principle inferences of this study as a simplified cartoon (top panel) and plotted on section P3 for V_p and V_p/V_s (bottom panel). Low V_p and high V_p/V_s within the supraslab mantle at depths between about 40 and 80 km correspond to serpentinization of the mantle wedge. The gradient to high V_p with high V_p/V_s between about 80 and 120 km transitions to partial melt that ascends (symbolized by the large arrow) to the volcanic arc in the Western Cordillera. Within the subducting Nazca Plate, a basaltic crust and serpentinized mantle at shallower depths transitions to an eclogitic crust and peridotitic mantle at greater depths.

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