# Minimal heteroclinics for a class of fourth order O.D.E. systems 

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## A R T I C L E I N F O

## Article history:

Received 11 December 2017
Accepted 4 April 2018
Communicated by Enzo Mitidieri

## Keywords:

Fourth order equations
Systems of O.D.E.
Heteroclinic orbit
Minimizer
Variational methods

## A B S T R A C T

We prove the existence of minimal heteroclinic orbits for a class of fourth order O.D.E. systems with variational structure. In our general set-up, the set of equilibria of these systems is a union of manifolds, and the heteroclinic orbits connect two disjoint components of this set.
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## 1. Introduction and main results

Given a smooth nonnegative function $W: \mathbb{R}^{m} \times \mathbb{R}^{m} \rightarrow[0, \infty)(m \geq 1)$, we define for every $(u, v):=\left(u_{1}, \ldots, u_{m}, v_{1}, \ldots, v_{m}\right) \in \mathbb{R}^{m} \times \mathbb{R}^{m}$, the vector $W_{u}(u, v):=\left(\frac{\partial W}{\partial u_{1}}(u, v), \ldots, \frac{\partial W}{\partial u_{m}}(u, v)\right) \in \mathbb{R}^{m}$, and the matrices $W_{u v}(u, v):=\left(\frac{\partial^{2} W}{\partial u_{j} \partial v_{i}}(u, v)\right)_{1 \leq i, j \leq m}, W_{v v}(u, v):=\left(\frac{\partial^{2} W}{\partial v_{j} \partial v_{i}}(u, v)\right)_{1 \leq i, j \leq m}$, where $i$ (respectively $j)$ stands for the row (resp. the column). Next, we consider the system:

$$
\begin{equation*}
\frac{\mathrm{d}^{4} u}{\mathrm{~d} x^{4}}+W_{u}\left(u, u^{\prime}\right)-W_{u v}\left(u, u^{\prime}\right) u^{\prime}-W_{v v}\left(u, u^{\prime}\right) u^{\prime \prime}=0, u: \mathbb{R} \rightarrow \mathbb{R}^{m} \tag{1}
\end{equation*}
$$

which is the Euler-Lagrange equation of the energy functional:

$$
\begin{equation*}
J_{\mathbb{R}}(u)=\int_{\mathbb{R}}\left(\frac{1}{2}\left|u^{\prime \prime}\right|^{2}+W\left(u, u^{\prime}\right)\right), u \in W_{\operatorname{loc}}^{2,2}\left(\mathbb{R} ; \mathbb{R}^{m}\right) \tag{2}
\end{equation*}
$$

In the scalar case $(m=1)$, setting $W(u, v)=\frac{1}{4}\left(u^{2}-1\right)^{2}+\frac{\beta}{2} v^{2}$, where $\beta>0,{ }^{1}$ we obtain the Extended Fisher-Kolmogorov equation

$$
\begin{equation*}
\frac{\mathrm{d}^{4} u}{\mathrm{~d} x^{4}}-\beta u^{\prime \prime}+u^{3}-u=0, u: \mathbb{R} \rightarrow \mathbb{R} \tag{3}
\end{equation*}
$$

[^0]which was proposed in 1988 by Dee and van Saarloos [5] as a higher-order model equation for bistable systems. Eq. (3) has been extensively studied by different methods: topological shooting methods, Hamiltonian methods, variational methods, and methods based on the maximum principle (cf. [3,13], and the references therein, in particular [9-11], and [12]). In recent years, it has become evident that the structure of solutions of (3) is considerably richer than the structure of solutions of the Allen-Cahn O.D.E.:
\[

$$
\begin{equation*}
u^{\prime \prime}=u^{3}-u, u: \mathbb{R} \rightarrow \mathbb{R} \tag{4}
\end{equation*}
$$

\]

or equivalently $u^{\prime \prime}=W^{\prime}(u)$, with $W(u)=\frac{1}{4}\left(u^{2}-1\right)^{2}$. Depending on the value of $\beta$, we mention below some properties of the heteroclinic orbits ${ }^{2}$ of (3), connecting at $\pm \infty$ the two equilibria $\pm 1$, in the sense that

$$
\begin{equation*}
\lim _{x \rightarrow \pm \infty}\left(u(x), u^{\prime}(x), u^{\prime \prime}(x), u^{\prime \prime \prime}(x)\right)=( \pm 1,0,0,0) \text { in the phase-space. } \tag{5}
\end{equation*}
$$

When $\beta \geq \sqrt{8},{ }^{3}$ the structure of bounded solutions of (3) exactly mirrors that of (4). In particular, (3) has (up to translations) a unique heteroclinic orbit connecting -1 to 1 , which is monotone. However, as soon as $\beta$ passes the critical value $\sqrt{8}$ from above, an infinity of heteroclinics appears immediately, and these orbits are no longer monotone. Actually, they oscillate around the equilibria $\pm 1$, and may jump from -1 to 1 and back a number of times. Also note that as $\beta$ decreases from $\sqrt{8}$, these orbits continue to exist up to $\beta=0$, and even somewhat beyond.

Another major difference between the second order model (3) and (4), lies in the existence of pulses for $\beta<\sqrt{8}$, i.e. nontrivial solutions $u: \mathbb{R} \rightarrow \mathbb{R}$ of (3) such that

$$
\begin{equation*}
\lim _{|x| \rightarrow \infty}\left(u(x), u^{\prime}(x), u^{\prime \prime}(x), u^{\prime \prime \prime}(x)\right)=(1,0,0,0) \text { or }(-1,0,0,0) . \tag{6}
\end{equation*}
$$

This situation which is excluded for the scalar equation (4), may occur if we consider the system $u^{\prime \prime}=\nabla W(u)$ with a multiple well potential $W: \mathbb{R}^{2} \rightarrow[0, \infty)(c f .[1$, Remark 2.6] and [15, Section 2]).

A more general version of the canonical equation (3) is given by

$$
\begin{equation*}
\frac{\mathrm{d}^{4} u}{\mathrm{~d} x^{4}}-g(u) u^{\prime \prime}-\frac{g^{\prime}(u)}{2}\left(u^{\prime}\right)^{2}+f^{\prime}(u)=0, u: \mathbb{R} \rightarrow \mathbb{R}, W(u, v)=\frac{g(u)}{2} v^{2}+f(u) \tag{7}
\end{equation*}
$$

where $f: \mathbb{R} \rightarrow \mathbb{R}$, and $g: \mathbb{R} \rightarrow \mathbb{R}$, are smooth functions (cf. [2,4]). For instance in [2], a double well potential $f \geq 0$ is considered, and $g$ is allowed to take negative values to an extent that is balanced by $f$. Provided that $\inf g$ is bigger than a negative constant depending on the nondegeneracy of the minima of $f$, the variational method can be applied to construct heteroclinics of (7).

The scope of this paper is to establish the existence of minimal heteroclinics for system (1) in a general set-up, similar to that considered in [1] for the Hamiltonian system $u^{\prime \prime}=\nabla W(u)$. In particular, we allow the function $W$ to vanish on submanifolds, and we are interested in connecting two disjoint subsets of minima of $W$.

We assume that $W \in C^{2}\left(\mathbb{R}^{m} \times \mathbb{R}^{m} ;[0, \infty)\right)$ is a nonnegative function such that
$\mathbf{H}_{1}$ : The set $A:=\left\{u \in \mathbb{R}^{m}: W(u, 0)=0\right\}$ is partitioned into two nonempty disjoint compact subsets $A^{-}$ and $A^{+}$.
$\mathbf{H}_{2}$ : There exists an open set $\Omega \subset \mathbb{R}^{m}$ such that $A^{-} \subset \Omega, A^{+} \cap \bar{\Omega}=\emptyset$, and $W(u, v)>0$ holds for every $u \in \partial \Omega$, and for every $v \in \mathbb{R}^{m}$.

[^1]$\mathbf{H}_{3}: \quad \liminf {\underset{|u| \rightarrow \infty}{ } W(u, v)>0 \text {, uniformly in } v \in \mathbb{R}^{m} .}$.
In $\mathbf{H}_{1}$, we define the sets $A^{-}$and $A^{+}$that we are going to connect. On the other hand, Hypothesis $\mathbf{H}_{2}$ ensures that the energy required to connect a neighborhood of $A^{-}$to a neighborhood of $A^{+}$cannot become arbitrarily small. As a consequence an orbit with finite energy may travel from $A^{-}$to $A^{+}$and back, only a finite number of times (cf. Lemma 2.4). Also note that $W$ is allowed to vanish if $u \notin \partial \Omega$, and $v \neq 0$. Finally, Hypothesis $\mathbf{H}_{3}$ is assumed to derive the boundedness of finite energy orbits (cf. Lemma 2.2).

Some typical examples of functions satisfying $\mathbf{H}_{i}, i=1,2,3$, are given by $W(u, v)=F(u), W(u, v)=$ $F(u)+\frac{\beta}{2}|v|^{2}($ vector analog of $(3)), W(u, v)=F(u)+\frac{G(u)}{2}|v|^{2}\left(\right.$ vector analog of (7)), where $F: \mathbb{R}^{m} \rightarrow[0, \infty)$ is a multiple well potential such that $\lim \inf _{|u| \rightarrow \infty} F(u)>0, G: \mathbb{R}^{m} \rightarrow[0, \infty)$, and $\beta>0$. In particular, our results apply to the system

$$
\begin{equation*}
\frac{\mathrm{d}^{4} u}{\mathrm{~d} x^{4}}+\nabla F(u)=0, u: \mathbb{R} \rightarrow \mathbb{R}^{m} \tag{8}
\end{equation*}
$$

to the vector Extended Fisher-Kolmogorov equation

$$
\begin{equation*}
\frac{\mathrm{d}^{4} u}{\mathrm{~d} x^{4}}-\beta u^{\prime \prime}+\nabla F(u)=0, u: \mathbb{R} \rightarrow \mathbb{R}^{m}, \beta>0 \tag{9}
\end{equation*}
$$

or to

$$
\begin{equation*}
\frac{\mathrm{d}^{4} u}{\mathrm{~d} x^{4}}-G(u) u^{\prime \prime}+\frac{\nabla G(u)}{2}\left|u^{\prime}\right|^{2}+\nabla F(u)-\left(\nabla G(u) \cdot u^{\prime}\right) u^{\prime}=0, u: \mathbb{R} \rightarrow \mathbb{R}^{m} \tag{10}
\end{equation*}
$$

Let $q \in\left(0, \frac{d\left(A^{-}, A^{+}\right)}{2}\right)$, be such that

$$
\left\{u \in \mathbb{R}^{m}: d\left(u, A^{-}\right) \leq q\right\} \subset \Omega, \text { and }\left\{u \in \mathbb{R}^{m}: d\left(u, A^{+}\right) \leq q\right\} \cap \bar{\Omega}=\emptyset .
$$

We define the class $\mathcal{A}$ by:

$$
\mathcal{A}=\left\{u \in W_{\text {loc }}^{2,2}\left(\mathbb{R} ; \mathbb{R}^{m}\right): \begin{array}{l}
d\left(u(x), A^{-}\right) \leq q, \text { for } x \leq x_{u}^{-}, \\
d\left(u(x), A^{+}\right) \leq q, \text { for } x \geq x_{u}^{+},
\end{array} \text {for some } x_{u}^{-}<x_{u}^{+}\right\},
$$

where $d$ stands for the Euclidean distance. Note that no limitation is imposed on the numbers $x_{u}^{-}<x_{u}^{+}$ that may largely depend on $u$. Our main theorem establishes the existence of a connecting minimizer in the class $\mathcal{A}$ :

Theorem 1.1. Assume $W$ satisfies $\mathbf{H}_{i}, i=1,2,3$. Then $J_{\mathbb{R}}(u)$ admits a minimizer $\bar{u} \in \mathcal{A}$ :

$$
J_{\mathbb{R}}(\bar{u})=\min _{u \in \mathcal{A}} J_{\mathbb{R}}(u)<+\infty .
$$

Moreover it results that ${ }^{4}$
(i) $\bar{u} \in C^{4}\left(\mathbb{R} ; \mathbb{R}^{m}\right)$ solves $(1)$
(ii) $\lim _{x \rightarrow \pm \infty} d\left(\bar{u}(x), A^{ \pm}\right)=0$,
(iii) $\lim _{x \rightarrow \pm \infty}\left(\bar{u}^{\prime}(x), \bar{u}^{\prime \prime}(x), \bar{u}^{\prime \prime \prime}(x)\right)=(0,0,0)$,
(iv) $H:=\frac{1}{2}\left|\bar{u}^{\prime \prime}\right|^{2}-W\left(\bar{u}, \bar{u}^{\prime}\right)+W_{v}\left(\bar{u}, \bar{u}^{\prime}\right) \cdot \bar{u}^{\prime}-\bar{u}^{\prime \prime \prime} \cdot \bar{u}^{\prime} \equiv 0, \forall x \in \mathbb{R}$.

An immediate consequence of Theorem 1.1 is

[^2]Corollary 1.2. Assume that $A=\left\{a_{1}, \ldots, a_{N}\right\}$ for some $N \geq 2$, and given $a^{-} \in A$, set $A^{-}=\left\{a^{-}\right\}$and $A^{+}=A \backslash\left\{a^{-}\right\}$. Then under the assumptions of Theorem 1.1, there exists $a^{+} \in A^{+}$such that the minimizer $\bar{u}$ satisfies $\lim _{x \rightarrow \pm \infty} \bar{u}(x)=a^{ \pm}$.

By construction, the minimizer $\bar{u}$ of Theorem 1.1 is a minimal solution of (1), in the sense that

$$
J_{\operatorname{supp} \phi}(\bar{u}) \leq J_{\operatorname{supp} \phi}(\bar{u}+\phi)
$$

for all $\phi \in C_{0}^{\infty}\left(\mathbb{R} ; \mathbb{R}^{m}\right)$. This notion of minimality is standard for many problems in which the energy of a localized solution is actually infinite due to non compactness of the domain. The Hamiltonian H introduced in property (iv) of Theorem 1.1, is a constant function for every solution of (1). In the case of system $u^{\prime \prime}=\nabla W(u)$, we have $H=\frac{1}{2}\left|u^{\prime}\right|^{2}-W(u)$, and every heteroclinic orbit satisfies the equipartition relation $H=0 \Leftrightarrow \frac{1}{2}\left|u^{\prime}\right|^{2}=W(u)$. We also point out that in the general set-up of Theorem 1.1, the minimizer $\bar{u}$ is a heteroclinic orbit only in a weak sense, since $\bar{u}$ approaches the sets $A^{ \pm}$at $\pm \infty$, but the limits of $\bar{u}$ at $\pm \infty$ may not exist. In Section 3, we will study the asymptotic convergence of $\bar{u}$, and establish an exponential estimate under a convexity assumption on $W$ in a neighborhood of the smooth orientable surfaces $A^{ \pm}$. From this estimate, it follows that the limits of $\bar{u}$ exist at $\pm \infty$. As a consequence, in many standard situations, the orbit of $\bar{u}$ actually connects two points $a^{ \pm} \in A^{ \pm}$.

The next Section contains the proof of Theorem 1.1. In contrast with [1], we avoid utilizing comparison arguments, since this method applied to higher order problems requires a lot of calculation. Indeed, to modify $W^{2,2}$ Sobolev maps, we also have to ensure the continuity of the first derivatives. Two ideas in Lemma 2.4 are crucial in the proof of Theorem 1.1. Firstly, the fact that a finite energy orbit may travel from $A^{-}$to $A^{+}$and back, only a finite number of times in view of $\mathbf{H}_{2}$. Secondly, an inductive argument to consider appropriate translations of the minimizing sequence, and fix the loss of compactness issue due to the translation invariance of (1).

## 2. Proof of Theorem 1.1

We first establish the following Lemmas:

Lemma 2.1. There exists $u_{0} \in \mathcal{A}$ satisfying

$$
\begin{equation*}
J_{\mathbb{R}}\left(u_{0}\right)<+\infty \tag{11}
\end{equation*}
$$

Proof. Indeed, let $a^{ \pm} \in A^{ \pm}$be such that $d\left(a^{-}, a^{+}\right)=d\left(A^{-}, A^{+}\right)$. We define

$$
u_{0}(x)= \begin{cases}a^{-}, & \text {for } x \leq 0 \\ a^{-}+\left(2 x^{2}-x^{4}\right)\left(a^{+}-a^{-}\right), & \text {for } 0 \leq x \leq 1 \\ a^{+}, & \text {for } x \geq 1\end{cases}
$$

which clearly belongs to $\mathcal{A}$ and satisfies (11).

From (11) it follows that

$$
\inf _{u \in \mathcal{A}} J_{\mathbb{R}}(u)=\inf _{u \in \mathcal{A}_{b}} J_{\mathbb{R}}(u)<+\infty
$$

where

$$
\mathcal{A}_{b}=\left\{u \in \mathcal{A}: J_{\mathbb{R}}(u) \leq J_{\mathbb{R}}\left(u_{0}\right)\right\}
$$

Lemma 2.2. The maps $u \in \mathcal{A}_{b}$ and their first derivatives are uniformly bounded. In addition, the derivatives $u^{\prime}$ of the maps $u \in \mathcal{A}_{b}$ are equicontinuous.

Proof. We first notice that the first derivative of a map $u \in \mathcal{A}_{b}$ is Hölder continuous, since by the Cauchy-Schwarz inequality we have

$$
\begin{equation*}
\left|u^{\prime}(y)-u^{\prime}(x)\right| \leq\left(\int_{x}^{y}\left|u^{\prime \prime}\right|^{2}\right)^{1 / 2} \sqrt{y-x} \leq \sqrt{2 J_{\mathbb{R}}\left(u_{0}\right)} \sqrt{y-x}, \forall x<y \tag{12}
\end{equation*}
$$

This proves that the derivatives $u^{\prime}$ of the maps $u \in \mathcal{A}_{b}$ are equicontinuous.
Next, we establish the uniform boundedness of the maps $u \in \mathcal{A}_{b}$. Let $R>0$ be large enough and such that $d\left(u, A^{-} \cup A^{+}\right) \leq q$ implies that $|u|<R$. According to Hypothesis $\mathbf{H}_{3}$, we can find a constant $w_{R}>0$ such that $W(u, v) \geq w_{R}$, for every $u \in \mathbb{R}^{m}$ such that $|u| \geq R$, and for every $v \in \mathbb{R}^{m}$. It follows that for every map $u \in \mathcal{A}_{b}$ we have $w_{R} \mathcal{L}^{1}(\{x \in \mathbb{R}:|u(x)| \geq R\}) \leq \int_{\mathbb{R}} W(u) \leq J_{\mathbb{R}}\left(u_{0}\right)$, where $\mathcal{L}^{1}$ denotes the one dimensional Lebesgue measure. As a consequence, if $u$ takes a value $u\left(x_{2}\right)=L \nu$ with $L>R$ and $\nu$ a unit vector, we can find an interval $x_{1}<x_{2}$ such that $\left|u\left(x_{1}\right)\right|=R$ and $|u(x)| \geq R, \forall t \in\left[x_{1}, x_{2}\right]$. Then, we have $L-R \leq \int_{x_{1}}^{x_{2}} u^{\prime}(x) \cdot \nu \mathrm{d} x$, and this implies the existence of $y_{1} \in\left[x_{1}, x_{2}\right]$ such that $u^{\prime}\left(y_{1}\right) \cdot \nu \geq \frac{(L-R)}{x_{2}-x_{1}} \geq \frac{(L-R) w_{R}}{J_{\mathbb{R}}\left(u_{0}\right)}$. Similarly, we can find $x_{3}>x_{2}$ such that $\left|u\left(x_{3}\right)\right|=R$ and $|u(x)| \geq R, \forall t \in\left[x_{2}, x_{3}\right]$. As previously, there exists $y_{3} \in\left[x_{2}, x_{3}\right]$ such that $u^{\prime}\left(y_{3}\right) \cdot \nu \leq-\frac{(L-R) w_{R}}{J_{\mathbb{R}}\left(u_{0}\right)}$, and by construction $y_{3}-y_{1} \leq \frac{J_{\mathbb{R}}\left(u_{0}\right)}{w_{R}}$. Finally in view of (12) we obtain

$$
\frac{2(L-R) w_{R}}{J_{\mathbb{R}}\left(u_{0}\right)} \leq\left|u^{\prime}\left(y_{3}\right)-u^{\prime}\left(y_{1}\right)\right| \leq \sqrt{2 J_{\mathbb{R}}\left(u_{0}\right)} \sqrt{y_{3}-y_{1}} \leq J_{\mathbb{R}}\left(u_{0}\right) \sqrt{\frac{2}{w_{R}}},
$$

and deduce that $L \leq M:=R+\frac{1}{\sqrt{2}} \frac{\left(J_{\mathbb{R}}\left(u_{0}\right)\right)^{2}}{w_{R}^{3 / 2}}$, which proves the uniform bound for $u \in \mathcal{A}_{b}$.
Now, suppose that $u^{\prime}\left(x_{0}\right)=\Lambda \nu$ with $\Lambda>\sqrt{2 J_{\mathbb{R}}\left(u_{0}\right)}$ and $\nu$ a unit vector. Utilizing again (12) we have $u^{\prime}(x) \cdot \nu \geq \Lambda-\sqrt{2 J_{\mathbb{R}}\left(u_{0}\right)}$ for $x \in\left[x_{0}-1, x_{0}+1\right]$. In particular since $\|u\|_{L^{\infty}} \leq M$, we conclude that $2 M \geq \int_{x_{0}-1}^{x_{0}+1}\left(u^{\prime}(x) \cdot \nu\right) \mathrm{d} x \geq 2\left(\Lambda-\sqrt{2 J_{\mathbb{R}}\left(u_{0}\right)}\right)$ which implies that $\Lambda \leq M+\sqrt{2 J_{\mathbb{R}}\left(u_{0}\right)}$. This completes the proof of Lemma 2.2.

Lemma 2.3. Let $u \in W_{\mathrm{loc}}^{2,2}\left(\mathbb{R} ; \mathbb{R}^{m}\right)$ be such that $J_{\mathbb{R}}(u) \leq J_{\mathbb{R}}\left(u_{0}\right)$, and $u$ as well as $u^{\prime}$ are bounded, and uniformly continuous. Then,

$$
\begin{equation*}
\lim _{x \rightarrow \pm \infty} d\left(u(x), A^{-} \cup A^{+}\right)=0, \text { and } \lim _{x \rightarrow \pm \infty} u^{\prime}(x)=0 \tag{13}
\end{equation*}
$$

Proof. We first assume by contradiction that $\lim _{x \rightarrow \pm \infty} u^{\prime}(x)=0$ does not hold. Without loss of generality, we consider a sequence $\left\{x_{k}\right\}$ such that $\lim _{k \rightarrow \infty} x_{k}=+\infty$, and $\lim _{k \rightarrow \infty} u^{\prime}\left(x_{k}\right)=\lambda \nu$, with $\lambda \neq 0$, and $\nu$ a unit vector. Let $k_{0}$ be large enough, such that $u^{\prime}\left(x_{k}\right) \cdot \nu \geq \frac{3 \lambda}{4}$ for every $k \geq k_{0}$, and let $I_{k}=\left[a_{k}, b_{k}\right]$ be the largest interval containing $x_{k}$ and such that $u^{\prime} \cdot \nu \geq \lambda / 2$ holds on $I_{k}$. Since $\|u\|_{L^{\infty}} \leq M$, it is clear that $\mathcal{L}^{1}\left(I_{k}\right) \leq \frac{4 M}{\lambda}$, where $\mathcal{L}^{1}$ denotes the one dimensional Lebesgue measure. Moreover, we have $u^{\prime}\left(a_{k}\right) \cdot \nu=\lambda / 2$. Applying (12) in the interval $\left[a_{k}, x_{k}\right]$, it follows that $\frac{\lambda^{3}}{4^{3} M} \leq \int_{I_{k}}\left|u^{\prime \prime}\right|^{2}$. Since, by passing to a subsequence if necessary, we can assume that the intervals $I_{k}$ are disjoint, this contradicts $J_{\mathbb{R}}(u) \leq J_{\mathbb{R}}\left(u_{0}\right)$.

Next, we assume by contradiction that $\lim _{x \rightarrow \pm \infty} d\left(u(x), A^{-} \cup A^{+}\right)=0$ does not hold. Without loss of generality, we consider a sequence $\left\{x_{k}\right\}$ such that $\lim _{k \rightarrow \infty} x_{k}=+\infty, \lim _{k \rightarrow \infty} u\left(x_{k}\right)=l \notin A^{-} \cup A^{+}$, and $\lim _{k \rightarrow \infty} u^{\prime}\left(x_{k}\right)=0$. Since $u$ as well as $u^{\prime}$ are bounded and uniformly continuous, the function $x \rightarrow W\left(u(x), u^{\prime}(x)\right)$ is also uniformly continuous. In view of $\mathbf{H}_{1}$, there exists $\delta>0$ independent of $k$ such that $W\left(u(x), u^{\prime}(x)\right) \geq W(l, 0) / 2>0$, for every $x \in\left[x_{k}-\delta, x_{k}+\delta\right]$, and $k \geq k_{0}$ large enough. In particular we have $J_{\left[x_{k}-\delta, x_{k}+\delta\right]}(u) \geq \delta W(l, 0)$, for $k=k_{0}, k_{0}+1, \ldots$ Since, by passing to a subsequence if necessary, we can assume that the intervals $\left[x_{k}-\delta, x_{k}+\delta\right]$ are disjoint, we reach again a contradiction.


Fig. 1. The sequence $-\infty=x_{0}<y_{1}<x_{1}<y_{2}<x_{2}<\cdots<x_{2 N}=\infty,(N=2)$.

Lemma 2.4. There exists $\bar{u} \in \mathcal{A}_{b}$ satisfying $J_{\mathbb{R}}(\bar{u})=\min _{u \in \mathcal{A}_{b}} J_{\mathbb{R}}(u)<+\infty$, and property (ii) of Theorem 1.1.

Proof. We consider a sequence $u_{k} \in \mathcal{A}_{b}$ such that $\lim _{k \rightarrow \infty} J\left(u_{k}\right)=\inf _{u \in \mathcal{A}_{b}} J_{\mathbb{R}}(u)$. For every $k$ we define the sequence

$$
-\infty<x_{1}(k)<x_{2}(k)<\cdots<x_{2 N_{k}-1}(k)<x_{2 N_{k}}(k)=\infty
$$

by induction:

- $x_{1}(k)=\sup \left\{t \in \mathbb{R}: d\left(u_{k}(s), A^{+}\right) \geq q, \forall s \leq t\right\}<\infty$,
- $x_{2 i}(k)=\sup \left\{t \in \mathbb{R}: d\left(u_{k}(s), A^{-}\right) \geq q, \forall s \in\left[x_{2 i-1}(k), t\right]\right\} \leq \infty$,
- $x_{2 i+1}(k)=\sup \left\{t \in \mathbb{R}: d\left(u_{k}(s), A^{+}\right) \geq q, \forall s \in\left[x_{2 i}(k), t\right]\right\}<\infty$, if $x_{2 i}(k)<\infty$,
where $i=1, \ldots$. In addition, we set
- $y_{2 i-1}(k)=\sup \left\{t \leq x_{2 i-1}(k): d\left(u_{k}(t), A^{-}\right) \leq q\right\}$,
- $y_{2 i}(k)=\sup \left\{t \leq x_{2 i}(k): d\left(u_{k}(t), A^{+}\right) \leq q\right\}$, if $x_{2 i}(k)<\infty$ (see Fig. 1).

By Lemma 2.2, we have the uniform bounds $M:=\sup _{k}\left\|u_{k}\right\|_{L^{\infty}}<\infty$, and $\Lambda:=\sup _{k}\left\|u_{k}^{\prime}\right\|_{L^{\infty}}<\infty$. Let $\delta>0$ be such that

- $B_{\delta}(z) \cap\left\{u \in \mathbb{R}^{m}: d\left(u, A^{-}\right) \leq q\right\}=\emptyset$, and $B_{\delta}(z) \cap\left\{u \in \mathbb{R}^{m}: d\left(u, A^{+}\right) \leq q\right\}=\emptyset, \forall z \in \partial \Omega \cap B_{M}$,
- $W(u, v)>0$ holds on $\left\{(u, v) \in B_{M} \times B_{\Lambda}: d\left(u, \partial \Omega \cap B_{M}\right) \leq \delta\right\}\left(c f\right.$. Hypothesis $\left.\mathbf{H}_{2}\right)$,
where $B_{R}(z) \subset \mathbb{R}^{m}$ denotes the closed ball of radius $R$ centered at $z \in \mathbb{R}^{m}$, and $B_{R}$ the closed ball of radius $R$ centered at the origin.

Next, we notice that in every interval $\left[y_{j}(k), x_{j}(k)\right]\left(j=1, \ldots, 2 N_{k}-1\right)$, there exists $z_{j}(k) \in\left[y_{j}(k), x_{j}(k)\right]$ such that $u_{k}\left(z_{j}(k)\right) \in \partial \Omega$. Let $I_{j}(k)=\left[a_{j}(k), b_{j}(k)\right]$ be the largest interval containing $z_{j}(k)$, and such that $\left|u_{k}(x)-u_{k}\left(z_{j}(k)\right)\right| \leq \delta, \forall x \in I_{j}(k)$. Since $\left|u_{k}\left(a_{j}(k)\right)-u_{k}\left(z_{j}(k)\right)\right|=\delta$, and $\left|u_{k}\left(b_{j}(k)\right)-u_{k}\left(z_{j}(k)\right)\right|=\delta$, it is clear that

$$
2 \delta \leq \int_{a_{j}(k)}^{b_{j}(k)}\left|u_{k}^{\prime}\right| \leq \Lambda\left(b_{j}(k)-a_{j}(k)\right)
$$

and

$$
\int_{a_{j}(k)}^{b_{j}(k)} W\left(u_{k}, u_{k}^{\prime}\right) \geq w_{\delta}\left(b_{j}(k)-a_{j}(k)\right) \geq w_{\delta} \frac{2 \delta}{\Lambda},
$$

where $w_{\delta}:=\inf \left\{W(u, v): d\left(u, \partial \Omega \cap B_{M}\right) \leq \delta,|u| \leq M,|v| \leq \Lambda\right\}>0$. Since the intervals $\left[a_{j}(k), b_{j}(k)\right] \subset$ $\left[y_{j}(k), x_{j}(k)\right]$ are disjoint for every $j=1, \ldots, 2 N_{k}-1$, it follows that

$$
\left(2 N_{k}-1\right) w_{\delta} \frac{2 \delta}{\Lambda} \leq \int_{\mathbb{R}} W\left(u_{k}, u_{k}^{\prime}\right) \leq J_{\mathbb{R}}\left(u_{0}\right)
$$

and thus the integers $N_{k}$ are uniformly bounded. By passing to a subsequence, we may assume that $N_{k}$ is a constant integer $N \geq 1$.

Our next claim is that up to subsequence, there exist an integer $i_{0}\left(1 \leq i_{0} \leq N\right)$ and an integer $j_{0}$ $\left(i_{0} \leq j_{0} \leq N\right)$ such that

- (a) the sequence $x_{2 j_{0}-1}(k)-x_{2 i_{0}-1}(k)$ is bounded,
- (b) $\lim _{k \rightarrow \infty}\left(x_{2 i_{0}-1}(k)-x_{2 i_{0}-2}(k)\right)=\infty$,
- (c) $\lim _{k \rightarrow \infty}\left(x_{2 j_{0}}(k)-x_{2 j_{0}-1}(k)\right)=\infty$,
where for convenience we have set $x_{0}(k):=-\infty$.
Indeed, we are going to prove by induction on $N \geq 1$, that given $2 N+1$ sequences $-\infty \leq x_{0}(k)<$ $x_{1}(k)<\cdots<x_{2 N}(k) \leq \infty$, such that $\lim _{k \rightarrow \infty}\left(x_{1}(k)-x_{0}(k)\right)=\infty$, and $\lim _{k \rightarrow \infty}\left(x_{2 N}(k)-x_{2 N-1}(k)\right)=\infty$, then up to subsequence the properties (a), (b), and (c) above hold, for two fixed indices $1 \leq i_{0} \leq j_{0} \leq N$. When $N=1$, the assumption holds by taking $i_{0}=j_{0}=1$. Assume now that $N>1$, and let $l \geq 1$ be the largest integer such that the sequence $x_{l}(k)-x_{1}(k)$ is bounded. Note that $l<2 N$. If $l$ is odd, we are done, since the sequence $x_{l+1}(k)-x_{l}(k)$ is unbounded, and thus we can extract a subsequence $\left\{n_{k}\right\}$ such that $\lim _{k \rightarrow \infty}\left(x_{l+1}\left(n_{k}\right)-x_{l}\left(n_{k}\right)\right)=\infty$. Otherwise $l=2 m($ with $1 \leq m<N)$, and the sequence $x_{2 m+1}(k)-x_{2 m}(k)$ is unbounded. We extract a subsequence $\left\{n_{k}\right\}$ such that $\lim _{k \rightarrow \infty}\left(x_{2 m+1}\left(n_{k}\right)-x_{2 m}\left(n_{k}\right)\right)=\infty$. Then, we apply the inductive statement with $N^{\prime}=N-m$, to the $2 N^{\prime}+1$ sequences $x_{2 m}\left(n_{k}\right)<x_{2 m+1}\left(n_{k}\right)<\cdots<x_{2 N}\left(n_{k}\right)$.

At this stage, we consider appropriate translations of the sequence $\left\{u_{k}\right\}$, by setting $\bar{u}_{k}(x)=u_{k}(x-$ $\left.x_{2 i_{0}-1}(k)\right)$. It is obvious that $\left\{\bar{u}_{k}\right\}$ is still a minimizing sequence. In view of Lemma 2.2 we obtain by the theorem of Ascoli via a diagonal argument that $\lim _{k \rightarrow \infty} \bar{u}_{k}=\bar{u}$ in $C_{\text {loc }}^{1}$ (up to subsequence). On the other hand, since $\int_{\mathbb{R}}\left|\bar{u}_{k}^{\prime \prime}\right|^{2} \leq 2 J_{\mathbb{R}}\left(u_{0}\right)$ we deduce that $\bar{u}_{k}^{\prime \prime} \rightharpoonup \bar{v}$ weakly in $L^{2}\left(\mathbb{R} ; \mathbb{R}^{m}\right)$ (up to subsequence). One can check that actually $\bar{u} \in W_{\text {loc }}^{2,2}\left(\mathbb{R} ; \mathbb{R}^{m}\right)$, and $\bar{u}^{\prime \prime}=\bar{v}$. Finally, we have by lower semicontinuity

$$
\begin{equation*}
\int_{\mathbb{R}}\left|\bar{u}^{\prime \prime}\right|^{2} \leq \liminf _{k \rightarrow \infty} \int_{\mathbb{R}}\left|\bar{u}_{k}^{\prime \prime}\right|^{2}, \tag{14}
\end{equation*}
$$

and by Fatou's Lemma

$$
\begin{equation*}
\int_{\mathbb{R}} W\left(\bar{u}, \bar{u}^{\prime}\right) \leq \liminf _{k \rightarrow \infty} \int_{\mathbb{R}} W\left(\bar{u}_{k}, \bar{u}_{k}^{\prime}\right) \tag{15}
\end{equation*}
$$

It follows from (14) and (15) that $J_{\mathbb{R}}(\bar{u}) \leq \inf _{u \in \mathcal{A}_{b}} J_{\mathbb{R}}(u)<+\infty$. To complete the proof it remains to show that $\bar{u} \in \mathcal{A}$. Indeed, in the interval $\left[x_{2 i_{0}-2}(k), x_{2 i_{0}-1}(k)\right]$ we have $d\left(u_{k}(x), A^{+}\right) \geq q$, thus since $\lim _{k \rightarrow \infty}\left(x_{2 i_{0}-1}(k)-x_{2 i_{0}-2}(k)\right)=\infty$, we deduce that $d\left(\bar{u}(x), A^{+}\right) \geq q$, for $x \leq 0$. Similarly, in the interval $\left[x_{2 j_{0}-1}(k), x_{2 j_{0}}(k)\right]$ we have $d\left(u_{k}(x), A^{-}\right) \geq q$, thus since $\lim _{k \rightarrow \infty}\left(x_{2 j_{0}}(k)-x_{2 j_{0}-1}(k)\right)=\infty$, while the sequence $x_{2 j_{0}-1}(k)-x_{2 i_{0}-1}(k)$ is bounded, it follows that $d\left(\bar{u}(x), A^{-}\right) \geq q$, in a neighborhood of $+\infty$. To conclude, Lemma 2.3 applied to $\bar{u}$, implies that $\lim _{x \rightarrow \pm \infty} d\left(\bar{u}(x), A^{ \pm}\right)=0$, and thus $\bar{u} \in \mathcal{A}$.

Now, we complete the proof of Theorem 1.1. By definition of the class $\mathcal{A}$, for every $\phi \in C_{0}^{\infty}\left(\mathbb{R} ; \mathbb{R}^{m}\right)$, we have $\bar{u}+\phi \in \mathcal{A}$. Thus, the minimizer $\bar{u}$ satisfies the Euler-Lagrange equation:

$$
\begin{equation*}
\int_{\mathbb{R}}\left(\bar{u}^{\prime \prime} \cdot \phi^{\prime \prime}+W_{u}\left(\bar{u}, \bar{u}^{\prime}\right) \cdot \phi+W_{v}\left(\bar{u}, \bar{u}^{\prime}\right) \cdot \phi^{\prime}\right)=0, \quad \forall \phi \in C_{0}^{\infty}\left(\mathbb{R} ; \mathbb{R}^{m}\right) . \tag{16}
\end{equation*}
$$

This is the weak formulation of (1). Since $W \in C^{2}\left(\mathbb{R}^{m} \times \mathbb{R}^{m} ; \mathbb{R}\right)$, it follows that $\bar{u} \in C^{4}\left(\mathbb{R} ; \mathbb{R}^{m}\right)$, and $\bar{u}$ is a classical solution of system (1).

Next we establish property (iii). The limit $\lim _{x \rightarrow \pm \infty} \bar{u}^{\prime}(x)=0$, is a consequence of Lemma 2.3. To see that $\lim _{x \rightarrow \pm \infty} \bar{u}^{\prime \prime}(x)=0$, we recall the interpolation inequality

$$
\begin{equation*}
\int_{a}^{a+h}\left|v^{\prime}\right|^{2} \leq C\left(\int_{a}^{a+h}|v|^{2}+\int_{a}^{a+h}\left|v^{\prime \prime}\right|^{2}\right), \forall v \in W^{2,2}\left([a, a+h] ; \mathbb{R}^{m}\right), \tag{17}
\end{equation*}
$$

that holds for a constant $C$ independent of $a \in \mathbb{R}$, and $h \in[1, \infty)$. In view of (1), it is clear that

$$
\begin{equation*}
\int_{a}^{a+1}\left|\frac{\mathrm{~d}^{4} \bar{u}}{\mathrm{~d} x^{4}}\right|^{2} \leq C_{1}+C_{2} \int_{a}^{a+1}\left|\bar{u}^{\prime \prime}\right|^{2} \leq C_{1}+2 C_{2} J_{\mathbb{R}}(\bar{u}) \leq C_{3} \tag{18}
\end{equation*}
$$

where $C_{i}$ are constants independent of $a$. Moreover, applying (17) to $v=\bar{u}^{\prime \prime}$, we can find another constant $C_{4}$ independent of $a$, such that

$$
\begin{equation*}
\int_{a}^{a+1}\left|\bar{u}^{\prime \prime \prime}\right|^{2} \leq C_{4} \tag{19}
\end{equation*}
$$

and as a consequence $\bar{u}^{\prime \prime}$ is uniformly continuous (see the proof of Lemma 2.2). Since $\int_{\mathbb{R}}\left|\bar{u}^{\prime \prime}\right|^{2}<\infty$ it follows that $\lim _{x \rightarrow \pm \infty} \bar{u}^{\prime \prime}(x)=0$. Finally, $\mathbf{H}_{1}$ and (1) imply that $\lim _{x \rightarrow \pm \infty} \frac{\mathrm{d}^{4} \bar{u}}{\mathrm{~d} x^{4}}(x)=0$. thus, we also have $\lim _{x \rightarrow \pm \infty} \bar{u}^{\prime \prime \prime}(x)=0$ (cf. [7, §3.4 p. 37]).

To prove property (iv), consider an arbitrary solution $u$ of (1). By integrating the inner product of (1) by $u^{\prime}$, one can see that the Hamiltonian $H:=\frac{1}{2}\left|u^{\prime \prime}\right|^{2}-W\left(u, u^{\prime}\right)+W_{v}\left(u, u^{\prime}\right) \cdot u^{\prime}-u^{\prime \prime \prime} \cdot u^{\prime}$ is constant along solutions. In the case of the minimizer $\bar{u}$, the Hamiltonian is zero by properties (ii) and (iii), and by Hypothesis $\mathbf{H}_{1}$.

## 3. Asymptotic convergence of the minimizer $\bar{u}$

A natural question arises in the case where the set $A^{ \pm}$defined in $\mathbf{H}_{1}$ are manifolds or union of manifolds: does the minimizer $\bar{u}$ converge to a point of $A^{+}$(respectively $A^{-}$) at $\pm \infty$ ? Before answering this question, we are going to establish by a variational method the following exponential estimate:

Proposition 3.1. Assume that $A^{-} \subset \mathbb{R}^{m}$ is a $C^{2}$ compact orientable surface with unit normal $\mathbf{n}$, and that $W$ satisfies

$$
\begin{equation*}
\left.\frac{\mathrm{d}^{2} W}{\mathrm{~d} s^{2}}(a+s \mathbf{n}, s \nu)\right|_{s=0}>0, \forall a \in A^{-}, \forall \nu \in \mathbb{R}^{m} \text { such that }|\nu|=1 . \tag{20}
\end{equation*}
$$

Then, the minimizer $\bar{u}$ constructed in Theorem 1.1 satisfies $d\left(\bar{u}(x), A^{-}\right) \leq K e^{k x}$, and $\left|\bar{u}^{\prime}(x)\right| \leq K e^{k x}$, $\forall x \leq 0$, for some constants $K, k>0$.

Proof. In view of (20), there exists $\lambda>0$ small enough, such that $\mathcal{U}:=\left\{u \in \mathbb{R}^{m}: d\left(u, A^{-}\right)<\lambda\right\}$ is a tubular neighborhood of $A^{-}$(cf [6]), and moreover

$$
\begin{equation*}
m\left(d^{2}\left(u, A^{-}\right)+|v|^{2}\right) \leq W(u, v) \leq M\left(d^{2}\left(u, A^{-}\right)+|v|^{2}\right), \forall u \in \mathcal{U}, \forall v \in \mathbb{R}^{m}:|v|<\lambda, \tag{21}
\end{equation*}
$$

for some constants $0<m<M$. Let $x_{0}$ be such that $d\left(\bar{u}(x), A^{-}\right)<\lambda / 8$, and $\left|\bar{u}^{\prime}(x)\right|<\lambda / 4, \forall x \leq x_{0}$. For fixed $x \leq x_{0}$, we set $\phi(x):=\bar{u}(x)-\frac{1}{2} \bar{u}^{\prime}(x)$. One can see that $\phi(x) \in \mathcal{U}$, since actually $d\left(\phi(x), A^{-}\right) \leq$ $d\left(\bar{u}(x), A^{-}\right)+\frac{1}{2}\left|\bar{u}^{\prime}(x)\right|<\lambda / 4$. We also introduce the point $a(x) \in A^{-}$such that $d(\phi(x), a(x))=d\left(\phi(x), A^{-}\right)$. Next we define the comparison map

$$
z(t)= \begin{cases}\bar{u}(x)+\left((t-x)+\frac{(t-x)^{2}}{2}\right) \bar{u}^{\prime}(x) & \text { for } x-1 \leq t \leq x  \tag{22}\\ \phi(x)+\left(2(t-x+1)^{2}-(t-x+1)^{4}\right)(a(x)-\phi(x)) & \text { for } x-2 \leq t \leq x-1, \\ a(x) & \text { for } t \leq x-2\end{cases}
$$

An easy computation shows that
(a) $z \in W_{\text {loc }}^{2,2}\left((-\infty, x] ; \mathbb{R}^{m}\right)$,
(b) $z(x)=\bar{u}(x)$, and $z^{\prime}(x)=\bar{u}^{\prime}(x)$,
(c) $d\left(z(t), A^{-}\right) \leq d\left(\bar{u}(x), A^{-}\right)+\frac{1}{2}\left|\bar{u}^{\prime}(x)\right|<\lambda / 4, \forall t \leq x$,
(d) $\left|z^{\prime}(t)\right| \leq 4 d\left(\bar{u}(x), A^{-}\right)+2\left|\bar{u}^{\prime}(x)\right|<\lambda, \forall t \leq x$,
(e) $J_{(-\infty, x]}(z) \leq C\left(d^{2}\left(\bar{u}(x), A^{-}\right)+\left|\bar{u}^{\prime}(x)\right|^{2}\right)$, for a constant $C>0$ independent of $x$.

At this stage, we set $\theta(x):=\int_{-\infty}^{x}\left(d^{2}\left(\bar{u}(t), A^{-}\right)+\left|\bar{u}^{\prime}(t)\right|^{2}\right) \mathrm{d} t$, and it is clear that $\theta^{\prime}(x)=d^{2}\left(\bar{u}(x), A^{-}\right)+\left|\bar{u}^{\prime}(x)\right|^{2}$. The variational characterization of $\bar{u},(21)$, and (e) above, imply that

$$
\begin{equation*}
m \theta(x) \leq \int_{-\infty}^{x} W\left(\bar{u}(t), \bar{u}^{\prime}(t)\right) \mathrm{d} t \leq J_{(-\infty, x]}(\bar{u}) \leq J_{(-\infty, x]}(z) \leq C \theta^{\prime}(x) . \tag{23}
\end{equation*}
$$

After an integration of inequality (23), we obtain that $\theta(x) \leq \theta\left(x_{0}\right) e^{c\left(x-x_{0}\right)}$, for every $x \leq x_{0}$, and for some constant $c>0$. Since the functions $x \rightarrow d^{2}\left(\bar{u}(x), A^{-}\right)$, and $x \rightarrow\left|\bar{u}^{\prime}(x)\right|^{2}$ are Lipschitz continuous (cf. Theorem 1.1), the statement of Proposition 3.1 follows from

Lemma 3.2. Let $f:\left(-\infty, x_{0}\right] \rightarrow[0, \infty)$ be a function such that

- $|f(x)-f(y)| \leq M|x-y|, \forall x, y \leq x_{0}$,
- $\int_{-\infty}^{x} f(t) \mathrm{d} t \leq C e^{c x}, \forall x \leq x_{0}$,
where $M, c$ and $C$ are positive constants. Then, $f(x) \leq 2 \sqrt{M C} e^{\frac{c}{2} x}, \forall x \leq x_{0}$.
Proof. Let $x \leq x_{0}$ be fixed and let $\lambda:=f(x)$. For $t \in\left[x-\frac{\lambda}{2 M}\right.$, $\left.x\right]$, we have $f(t) \geq f(x)-M|t-x| \geq \frac{\lambda}{2}$. Thus,

$$
\frac{\lambda^{2}}{4 M} \leq \int_{x-\frac{\lambda}{2 M}}^{x} f(t) \mathrm{d} t \leq C e^{c x} \Rightarrow \lambda=f(x) \leq 2 \sqrt{M C} e^{\frac{c}{2} x}
$$

Corollary 3.3. Under the assumptions of Proposition 3.1, there exists $l \in A^{-}$such that $\bar{u}(x) \rightarrow l$, as $x \rightarrow-\infty$.

Proof. The exponential estimates provided by Proposition 3.1 imply that $x \rightarrow\left|\bar{u}\left({ }^{\prime} x\right)\right|$ is integrable in a neighborhood of $-\infty$. As a consequence, it is easy to see that the limit of $\bar{u}$ at $-\infty$ exists and belongs to $A^{-}$.

Proposition 3.4. Assume that $A^{-}=\left\{a^{-}\right\}$, and that $W$ satisfies

$$
\begin{equation*}
m|u|^{2} \leq W(u, v) \text { in a neighborhood of }\left(a^{-}, 0\right), \text { for a constant } m>0, \tag{24}
\end{equation*}
$$

Then, the minimizer $\bar{u}$ constructed in Theorem 1.1 satisfies $\left|\bar{u}(x)-a^{-}\right| \leq K e^{k x}$, and $\left|\bar{u}^{\prime}(x)\right| \leq K e^{k x}, \forall x \leq 0$, for some constants $K, k>0$.

Proof. We proceed as in the proof of Proposition 3.1. For $\lambda>0$ small enough, we have

$$
\begin{equation*}
m|u|^{2} \leq W(u, v) \leq M\left(\left|u-a^{-}\right|^{2}+|v|^{2}\right), \forall u \in \mathbb{R}^{m}:\left|u-a^{-}\right|<\lambda, \forall v \in \mathbb{R}^{m}:|v|<\lambda . \tag{25}
\end{equation*}
$$

Let $x_{0}$ be such that $\left|\bar{u}(x)-a^{-}\right|<\lambda / 8$, and $\left|\bar{u}^{\prime}(x)\right|<\lambda / 4, \forall x \leq x_{0}$. For fixed $x \leq x_{0}$, we set again $\phi(x):=\bar{u}(x)-\frac{1}{2} \bar{u}^{\prime}(x)$. Next we consider the comparison map (22), where $a(x)$ is now replaced by $a^{-}$. This map $z$ still satisfies properties (a)-(e) in Proposition 3.1. Setting $\theta(x):=\int_{-\infty}^{x}\left(\left|\bar{u}(t)-a^{-}\right|^{2}+\left|\bar{u}^{\prime}(t)\right|^{2}\right) \mathrm{d} t$, we obtain

$$
\begin{equation*}
m \int_{-\infty}^{x}\left|\bar{u}(t)-a^{-}\right|^{2} \mathrm{~d} t+\frac{1}{2} \int_{-\infty}^{x}\left|\bar{u}^{\prime \prime}(t)\right|^{2} \mathrm{~d} t \leq J_{(-\infty, x]}(\bar{u}) \leq J_{(-\infty, x]}(z) \leq C \theta^{\prime}(x) . \tag{26}
\end{equation*}
$$

Finally, we utilize the interpolation inequality (17), to bound $\int_{-\infty}^{x}\left|\bar{u}^{\prime}(t)\right|^{2} \mathrm{~d} t$ by a constant multiplied by the left hand-side of (26). Hence, $\theta(x) \leq c \theta^{\prime}(x), \forall x \leq x_{0}$, and for a constant $c>0$. Then we conclude as in Proposition 3.1.

## Acknowledgment

P. Smyrnelis was partially supported by Fondo Basal CMM-Chile and Fondecyt postdoctoral grant 3160055.

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    ${ }^{1}$ In the case where $\beta<0$, the corresponding equation is known as the Swift-Hohenberg equation.

[^1]:    ${ }^{2}$ The existence of heteroclinic solutions of (3) via variational arguments was investigated for the first time by L. A. Peletier, W. C. Troy and R. C. A. M. VanderVorst [14], and W. D. Kalies, R. C. A. M. VanderVorst [8].
    ${ }^{3}$ The linearization of (3) at $\pm 1$ reads $\frac{\mathrm{d}^{4} v}{\mathrm{~d} x^{4}}-\beta v^{\prime \prime}+2 v=0$. The four roots of the associated characteristic equation $\lambda^{4}-\beta \lambda^{2}+2=0$ are all real if and only if $\beta \geq \sqrt{8}$.

[^2]:    ${ }^{4}$ The existence of a minimizer $\bar{u}$ satisfying (ii) is ensured provided that $W$ is continuous (cf. the proof in Section 2). On the other hand, the $C^{1}$ smoothness of $W$ and $W_{u}$ is required to establish properties (i), (iii) and (iv).

