



# Mate selection provides similar genetic progress and average inbreeding than optimum contribution selection in the long-term

Grazyella Massako Yoshida<sup>a,b</sup>, José Manuel Yáñez<sup>b,c</sup>, Sandra Aidar de Queiroz<sup>a</sup>, Roberto Carvalheiro<sup>a,d,\*</sup>

<sup>a</sup> Department of Animal Science, School of Agricultural and Veterinarian Sciences, Sao Paulo State University (UNESP), Via de Acesso Prof. Paulo Donato Castellane, 14884-900 Jaboticabal, SP, Brazil

<sup>b</sup> Facultad de Ciencias Veterinarias y Pecuarias, Universidad de Chile, Av Santa Rosa 11735, La Pintana, Santiago 8820808, Chile

<sup>c</sup> Núcleo Milenio de Salmónidos Invasores, Concepción, Chile

<sup>d</sup> National Council for Scientific and Technological Development (CNPq), Brasília, DF, Brazil

## ARTICLE INFO

### Keywords:

Aquaculture breeding  
Coancestry  
Differential evolution  
Mating strategy

## ABSTRACT

Optimum contribution selection (OCS) and mate selection (MS) are alternative strategies to maximize genetic gain under controlled rates of inbreeding. There is evidence in the literature that MS outperforms OCS in controlling inbreeding under the same expected genetic gain in the short-term. It is unclear, however, if the same would occur in the long-term. This study aimed to compare OCS and MS regarding short- and long-term genetic progress and inbreeding, using simulated data. The structure of the simulated population aimed to mimic an aquaculture breeding program. Twenty discrete generations were simulated, considering 50 families and 2000 offspring per generation, and a trait with a heritability of 0.3. OCS and MS were applied using a differential evolution (DE) algorithm, under an objective function that accounted for genetic merit, coancestry among selection candidates and inbreeding of the future progeny. For OCS, the optimization process consisted of selection based on optimum contribution followed by minimum inbreeding mating. Objective functions using different weights on coancestry were tested. For each application, 20 replicates were simulated and the results were compared based on their average. Both strategies, OCS and MS, were very effective in controlling inbreeding over the generations. In the short-term, MS was more efficient than OCS in controlling inbreeding under the same genetic gain. In the long-term, OCS and MS resulted in similar genetic progress and average inbreeding, under the same penalty on coancestry.

## 1. Introduction

Selective breeding schemes for animals involve selection and mating decisions, i.e. the definition of the animals to be used as parents of the next generation and the decision regarding the matings to be performed among the selected parents. Both decisions have a high impact on the outcome of the breeding program because they determine genetic gain and inbreeding level of subsequent generations (Falconer and Mackay, 1996).

Aquaculture breeding is usually characterized by having populations with limited number of controlled families and high fecundity. The latter allows applying high selection intensity, which enables relatively high annual genetic gain in the short-term. However, this can also potentially lead to very few families dominating the genetic

contributions to the next generation and, consequently, the rate of inbreeding can easily increase to undesirable levels (Caballero et al., 1996). High rates of inbreeding may have an important effect on medium- and long-term response to selection, increase the manifestation of deleterious alleles, cause inbreeding depression, reduce genetic variation and genetic progress of subsequent generations (Falconer and Mackay, 1996).

Different strategies have been proposed to control inbreeding, including optimum contribution selection (OCS) (Meuwissen, 1997; Woolliams and Thompson, 1994), which maximizes genetic response while constraining the rate of inbreeding by restricting coancestry among selected parents. The usefulness of restricting coancestry has been shown to be effective not only to control future inbreeding, but also to the maintenance of genetic diversity (Caballero and Toro, 2000;

\* Corresponding author at: Department of Animal Science, School of Agricultural and Veterinarian Sciences, Sao Paulo State University (UNESP), Via de Acesso Prof. Paulo Donato Castellane, 14884-900 Jaboticabal, SP, Brazil.

E-mail address: [roberto.carvalheiro@unesp.br](mailto:roberto.carvalheiro@unesp.br) (R. Carvalheiro).

<https://doi.org/10.1016/j.aquaculture.2020.735376>

Received 13 January 2020; Received in revised form 13 April 2020

Available online 14 April 2020

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Gómez-Romano et al., 2013).

In fish breeding programs, several studies have shown the benefits of implementing OCS in terms of maximizing genetic response with constrained rate of inbreeding (Agaro et al., 2007; Hinrichs et al., 2006; Holtmark et al., 2008; Kause et al., 2005; Nielsen et al., 2011; Skaarud et al., 2011, 2014; Sonesson et al., 2005). Skaarud et al. (2011), in a simulation study, observed that, under the same rate of inbreeding, the genetic gain obtained with OCS methods were up to 13% higher than for the commonly used practical method that restricts the maximum number of offspring that can be selected from the same family for use as parents in the next generation.

Optimum contribution selection is usually applied in combination with mating strategies as minimum inbreeding and compensatory mating (Sonesson and Meuwissen, 2000, 2002; Grundy et al., 1998; Meuwissen, 1997; Sonesson and Meuwissen, 2000). An alternative strategy is to perform selection and mate allocations simultaneously by using mate selection (MS) (Kinghorn and Shepherd, 1999; Shepherd and Kinghorn, 1999). In this approach, different components related to the breeding objective can be accommodated in an objective function (OF) that, when optimized, results in a mating list that indirectly determines the contribution of each selection candidate (Kinghorn, 2011). The main challenge is to determine a proper OF and a method to optimize it (Kinghorn and Shepherd, 1999). MS has also been shown to be effective in controlling the rate of inbreeding while maximizing genetic gain, and other components of the objective function when present (Carvalho et al., 2010a; Hayes et al., 2002; Kinghorn and Shepherd, 1999; Kinghorn, 1998, 2011; Li et al., 2006; Shepherd and Kinghorn, 1999).

Using real Nile tilapia and coho salmon datasets, Yoshida et al. (2017) observed that, under the same expected genetic gain, MS outperformed OCS in controlling inbreeding in the short-term. However, their data did not allow contrasting both strategies in the long-term and a simulation study was recommended. The objective of the present study was to compare OCS and MS in aquaculture breeding, regarding short- (generation 5) and long-term (generation 20) genetic progress and inbreeding, using simulated data. Partial results of this study were presented by Yoshida et al. (2018a).

## 2. Material and methods

### 2.1. Simulated data

The simulation process aimed to mimic the structure of a fish population. The animals from the base population (G0) comprised 25 males and 50 females. Their additive genetic values ( $g_i$ ) were sampled from a Gaussian distribution  $N(0, \sigma_a^2)$ , where  $\sigma_a^2$  is the additive genetic variance ( $\sigma_a^2 = 0.3$ ) in G0. Phenotypes in the base population were then calculated as:

$$y_i = g_i + e_i$$

where  $e_i$  is the environmental effect sampled from  $N(0, \sigma_e^2)$ , with  $\sigma_e^2 = 1 - \sigma_a^2$ . Thus, in the base generation, the phenotypic variance was equal to 1 and the heritability equal to 0.3. Phenotypic values of the offspring in later generations were simulated as:

$$y_i = 0.5g_s + 0.5g_d + m_i + e_i$$

where  $g_s$  and  $g_d$  are the additive genetic values of the sire and dam, respectively;  $m_i$  is the Mendelian sampling effect with the distribution  $N(0, 0.5(1 - (F_s + F_d)/2)\sigma_a^2)$ , with  $F_s$  and  $F_d$  being the inbreeding coefficients of the sire and dam, respectively; and  $e_i$  was defined as above. Each female produced 40 offspring with equal probability of being a male or a female, totaling 2000 progenies per generation. For each scenario encompassing a selection and mating strategy, 20 discrete generations were simulated (G1-G20).

### 2.2. Objective function

An algorithm based on Differential Evolution (DE) (Storn and Price, 1997) was developed in FORTRAN by Carvalho et al. (2010b), which allows applying either OCS or MS depending on the weights used for the different components of the objective function (OF) to be optimized. The OF used was:

$$OF = w_1x'EBV + w_2x'Ax + w_3\bar{F}$$

where,  $x'EBV$  is the expected merit of the future progeny;  $x'Ax$  is the weighted mean coancestry of selected parents;  $\bar{F}$  is the expected average inbreeding coefficient of future progeny;  $w_1$  to  $w_3$  are the corresponding weighting factors and  $x$  is the vector of genetic contributions to be optimized for each candidate (the symbol ' denotes a transposed vector). The optimization of OF ignoring  $\bar{F}$  ( $w_3 = 0$ ) corresponds to OCS followed by random mating, and using a relatively very low value for  $w_3$  corresponds to OCS followed by minimum inbreeding mating as, in this case, the value of OF would primarily be determined by the expected merit and coancestry and secondary by  $\bar{F}$ , i.e.  $\bar{F}$  would only drive mate and not selection.

Although not explicitly described in the OF, the mate allocations were determined by  $\bar{F}$ , following the problem representation suggested by Gondro and Kinghorn (2008). In this representation, an auxiliary vector is used internally in the mate selection algorithm with the number of elements equal to the number of mates (in our case, equal to the number of dams). Each element of the auxiliary vector is a real number used to indirectly determine the mates. These real numbers are ranked, and the resultant rankings ultimately define the matings to be performed (Yoshida et al., 2017). As an illustrative example, suppose that five mates need to be performed and the optimized  $x$  vector determines the contribution of three candidate sires as 3, 0 and 2 respectively. Let us also suppose that the ranking of the five elements of the auxiliary vector are (in order) equal to second, fifth, first, fourth and third, which determines that the first candidate sire would be mated with the second, fifth and first available dams, and the third candidate sire would be mated with the fourth and third available dams. This model representation was chosen because it is computationally much more efficient than optimizing the number of offspring from every possible mate. More information about this mate representation and its reasoning can be found in Gondro and Kinghorn (2008).

For every discrete generation, the best female and the best five male offspring per family were considered as selection candidates to produce the next generation, resulting in 50 female and 250 male selection candidates. The males were allowed to be mated to a maximum of four females and each female was mated once, i.e. the contribution of each female was not optimized. We have not considered all offspring as selection candidates because the optimization process would be much slower and the results in terms of genetic gain and inbreeding rate would be similar based on prior assessments (results not shown). Pre-selection of candidates was based on their estimated breeding values.

The operational parameters of the DE algorithm to optimize the OF were: population size = 2 times the number of candidates; crossover rate = 0.5; mutation factor = 0.2 (or 0.9 every 4 generations); and maximum number of generations of the evolutionary process (maxgen = 100,000). Convergence was assumed when the range and the mean absolute deviation of the OF, considering all the possible solutions per generation, were lower than  $1 \times 10^{-6}$ . The best solution from the maxgen generation was considered as the optimum solution when the convergence criterion was not attained.

The approach proposed by Lampinen and Zelinka (1999) was adopted to provide integer solutions for number of mates per candidate. To increase computational efficiency, the Colleau (2002) indirect approach was adopted to calculate coancestry, and linked lists (Knuth, 1975) were used for storage and calculations involving sparse matrices. The mate selection algorithm is freely available for research purpose and can be obtained under request to the corresponding author.

### 2.3. Scenarios

Initially, four different OF were optimized, characterizing two applications of OCS (OCS1 and OCS2) and two of MS (MS1 and MS2). They differed according to the weights used for coancestry ( $w_2$ ) and inbreeding ( $w_3$ ). OCS1 and MS1 used a  $w_2$  of  $-10$ . A higher emphasis on coancestry was given on OCS2 and MS2 ( $w_2 = -20$ ). For OCS1 and OCS2, a  $w_3$  equal to  $-0.00001$  was used, corresponding to the application of OCS followed by minimum inbreeding mating, as previously explained. For MS1 and MS2, a  $w_3$  equal to  $-1$  was used, so in these two OF the selection and mating were performed simultaneously. All OF used the same weight for the expected merit of the future progeny ( $w_1 = 1$ ). In summary, the following weights were used for each application: OCS1 ( $w_1 = 1, w_2 = -10, w_3 = -0.00001$ ); OCS2 ( $w_1 = 1, w_2 = -20, w_3 = -0.00001$ ); MS1 ( $w_1 = 1, w_2 = -10, w_3 = -1$ ) and MS2 ( $w_1 = 1, w_2 = -20, w_3 = -1$ ). These weights were determined empirically based on results from previous studies (Carvalho et al., 2010a; Yoshida et al., 2017).

In addition, three other OF were applied for comparison purposes: truncation selection (TS) followed by random mating (TS1:  $w_1 = 1, w_2 = 0, w_3 = 0$ ); truncation selection followed by minimum inbreeding mating (TS2:  $w_1 = 1, w_2 = 0, w_3 = -0.00001$ ) and OCS followed by random mating (OCS3:  $w_1 = 1, w_2 = -10, w_3 = 0$ ). For each scenario, 20 replicates per generation (representing different populations) were simulated and their results were averaged for the comparisons. Results for all seven OF were compared for short- (generation 5) and long-term (generation 20) genetic gain and inbreeding provided by the optimization of each OF, as summarized in Supplementary Table 1.

### 3. Results

OCS and MS were applied using a differential evolution algorithm, under an objective function that accounted for genetic merit, coancestry among selection candidates and inbreeding of the future progeny. For OCS, the optimization process consisted of selection based on optimum contribution followed by minimum inbreeding mating (OCS1 and OCS2) or random mating (OCS3). Objective functions were tested with a lower (OCS1, OCS3 and MS1) or higher (OCS2 and MS2) emphasis on constraining coancestry. Truncation selection (TS) followed by random mating (TS1) or by minimum inbreeding mating (TS2) was also applied for comparison.

Fig. 1 presents the genetic response of the different strategies over generations. OCS1 displayed a genetic gain equivalent to MS1 and the

genetic gain of OCS2 was similar to MS2, in the short- and long-term. Therefore, the contrasts between OCS1 vs MS1 and OCS2 vs MS2 allow reasonable comparisons between both strategies in terms of controlling inbreeding under the same rate of genetic gain (discussed later). As expected, increased penalty on coancestry resulted in a reduction in genetic response. For instance, at G20, OCS2 expressed an average breeding value (7.45), 7.22% lower than OCS1 (8.03). Truncation selection strategies (TS1 and TS2) presented the highest genetic gain, which was about 10 to 12% superior to those presented by OCS1 and MS1 at G20. OCS followed by random mating (OCS3) presented similar genetic response than OCS followed by minimum inbreeding mating (OCS1) (Fig. 1).

The variance of true breeding values decreased in the first five generations, due to Bulmer (1981) effect, and kept almost constant in the next generations for the different strategies except for truncation selection (TS1 and TS2), which showed a continuing decrease of genetic variance along the generations (Fig. 2). At G20, the genetic variance was around 0.23 to 0.24 for the OCS and MS strategies, compared to 0.14 to 0.15 for the TS strategies.

Similar values of coancestry were observed between OCS1 and MS1 and between OCS2 and MS2, increasing up to 0.21 for OCS1 and MS1 and up to 0.16 for OCS2 and MS2 at G20 (Fig. 3). TS strategy resulted in a much higher level of coancestry than OCS or MS. At G20, coancestry of TS1 and TS2 were equal to 0.94 and 0.89, respectively. OCS1 and OCS3 presented similar coancestry trends.

The number of sires selected by generation varied among the strategies (Fig. 4). For TS1 and TS2, the number of sires selected was almost constant across generations (13). Minor variation occurred for TS1 and TS2 because in some replicates the sire ranked as 14th was also selected due to the stochastic nature of the DE algorithm. For OCS and MS, the number of sires selected increased overtime, reaching a plateau corresponding to the maximum possible value, i.e. 50 sires selected to be mated with 50 females. OCS1 and MS1 started using less sires (27) than OCS2 (37) and MS2 (38), but also ended up using 50 sires in the last simulated generation.

In the short-term, MS was more efficient in controlling inbreeding than OCS under the same penalty on coancestry (Fig. 5). At G4, for example, the average inbreeding of the different strategies was equal to 1.61% and 0.89% for OCS1 and MS1, and equal to 0.88% and 0.36% for OCS2 and MS2, respectively. However, in the long-term, MS and OCS presented similar inbreeding levels and rate of inbreeding under the same penalty on coancestry (Fig. 6). For instance, the average inbreeding of OCS1 and MS1 at G20 was equal to 8.78% and 8.49%, respectively. MS and OCS, which accounted for coancestry, were more

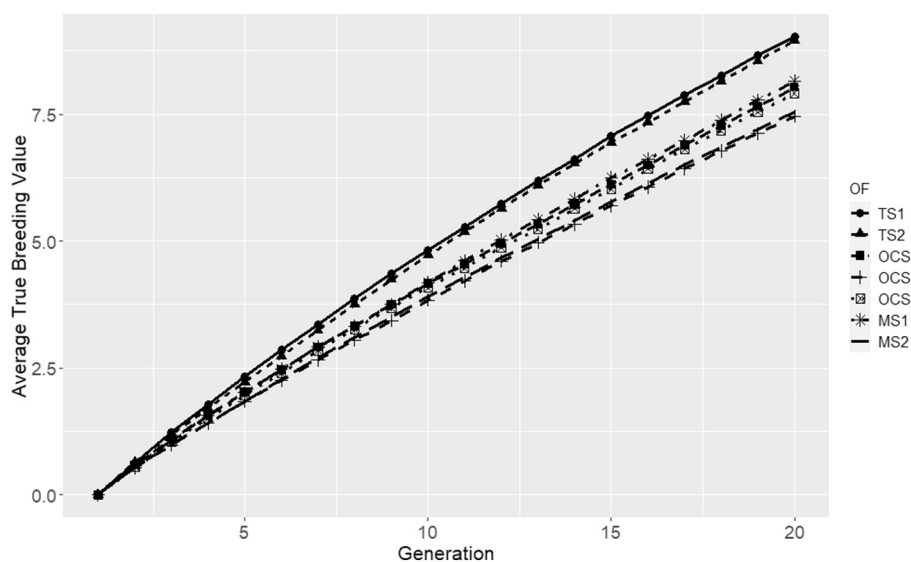


Fig. 1. Average true breeding value over 20 generations of selection considering different objective functions (OF).

TS1: truncation selection (TS) followed by random mating (RM); TS2: TS followed by minimum inbreeding mating (MIM); OCS1: optimum contribution selection (OCS) followed by MIM, with lower emphasis on coancestry; OCS2: OCS followed by MIM, with higher emphasis on coancestry; OCS3: OCS followed by RM, with lower emphasis on coancestry; MS1: mate selection (MS) with lower emphasis on coancestry; MS2: MS with higher emphasis on coancestry.

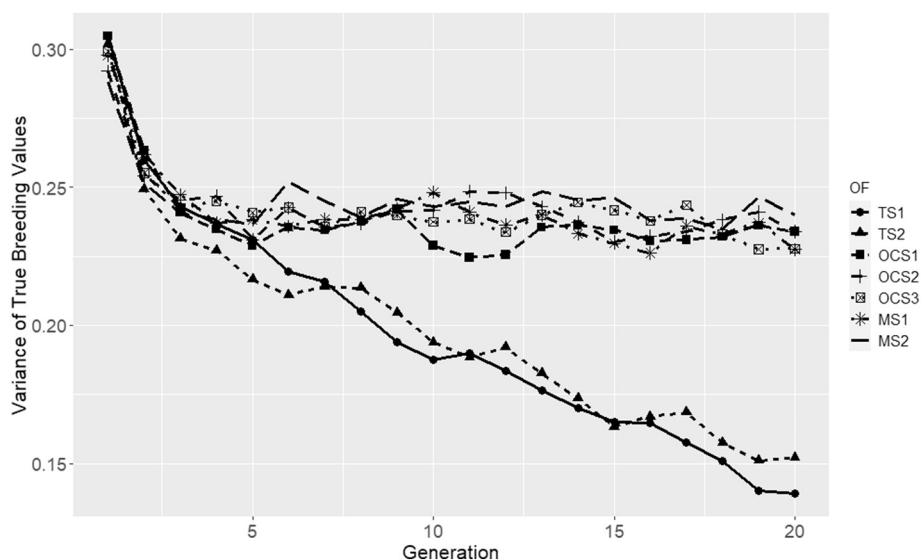


Fig. 2. Variance of true breeding value over 20 generations of selection considering different objective functions. The scenarios definition is present in Fig. 1.

efficient in controlling inbreeding compared to truncation selection followed by mating minimizing inbreeding (TS2; 41.06% at G20). There was even greater inbreeding for truncation selection followed by random mating (TS1; 44.37%). OCS3 presented higher rate of inbreeding in the short-term compared to the other OCS and MS strategies (Fig. 5). After G5, OCS3 presented a rate of inbreeding similar to OCS1 and MS1, besides presenting an inbreeding level slightly higher (Fig. 6).

#### 4. Discussion

Optimum contribution selection is usually compared with TS regarding their genetic response under the same rate of inbreeding (Meuwissen, 1997; Meuwissen and Sonesson, 1998). In our simulation, TS was not constrained to present the same rate of inbreeding than the other strategies. In contrast, TS was applied here to focus on maximizing genetic response of the next generation, constraining the maximum allowed number of mates per candidate sire, which was equal to four for all strategies. As a result, TS presented the highest genetic response due to the highest selection intensity among the tested strategies. TS would probably not have expressed the highest response

if inbreeding depression and/or deleterious recessive alleles were considered in the simulation process. It has been estimated that a 1% increase in inbreeding corresponds to a 0.137% reduction in trait mean (Leroy, 2014). In our simulated populations, this value would correspond to a mean reduction of up to 6% for TS ( $F > 40\%$ ) and 1% or less for the remaining strategies ( $F < 10\%$ ). Leroy (2014) also pointed out that the decrease in trait mean due to inbreeding depression is greater for production traits (reduction of 0.351%) than for other trait categories.

As reported in the literature (e.g. Woolliams et al., 2015), the strategy of performing minimum inbreeding mating after truncation selection (TS2) was not effective in keeping diversity and controlling inbreeding. The only effective way to control inbreeding, as shown by OCS and MS results, is by penalizing or constraining the coancestry among selected parents, which is in accordance with OCS theory (Meuwissen, 1997; Woolliams and Thompson, 1994). The penalties applied on coancestry in the present study, allowed OCS and MS to substantially reduce inbreeding when compared to TS (up to 85%), and the decrease in genetic gain was not so pronounced (up to 17%). Meuwissen and Sonesson (1998) observed that, at the same rate of

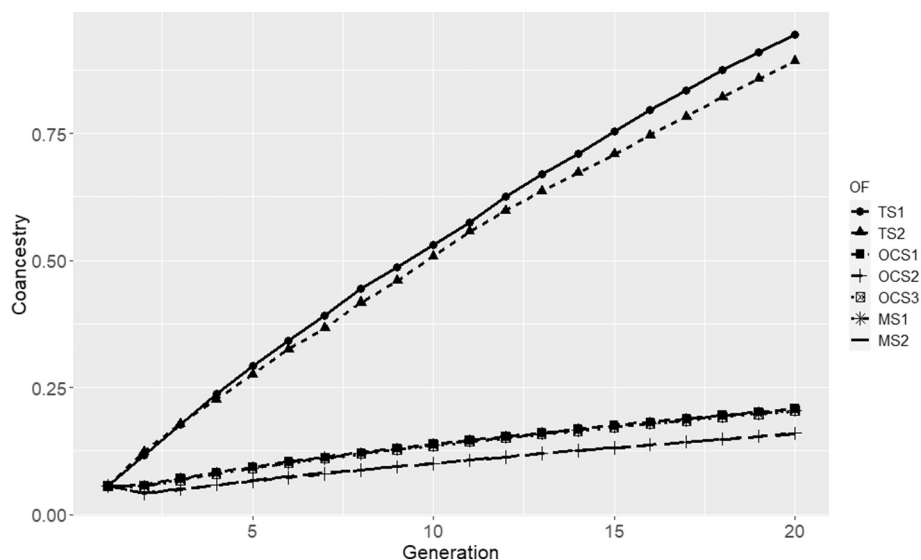


Fig. 3. Average coancestry over 20 generations of selection considering different objective functions. The scenarios definition is present in Fig. 1.

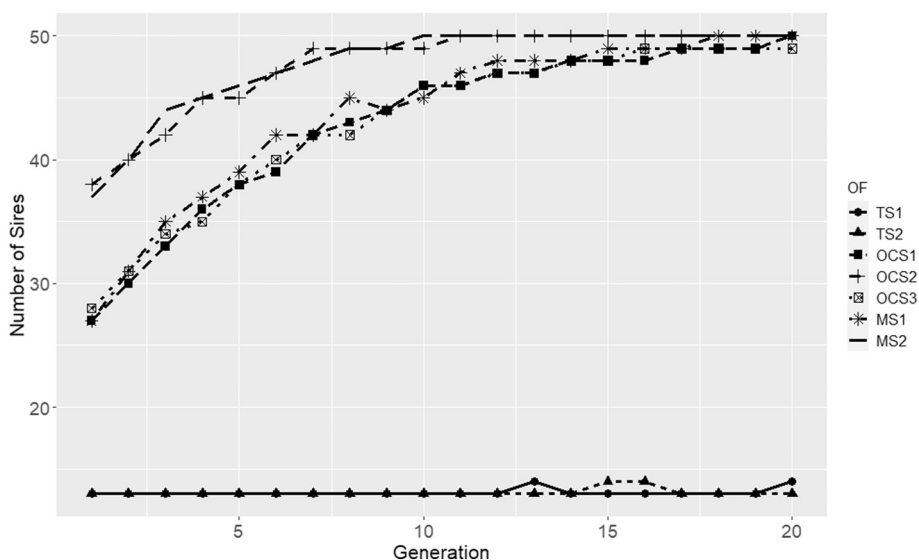


Fig. 4. Average number of sires selected over 20 generations of selection considering different objective functions. The scenarios definition is present in Fig. 1.

inbreeding, OCS attained up to 44% more genetic gain than TS. Our results are not directly comparable with theirs because, among other differences in the simulation process, we did not constrain TS to present the same rate of inbreeding than OCS, as previously discussed.

Sonesson and Meuwissen (2000) observed that OCS combined with non-random mating did not reduce the rate of inbreeding in comparison with OCS and random mating. However, non-random mating allowed higher selection intensity for OCS, resulting in increased genetic gain compared to random mating. In our simulation, OCS followed by minimum inbreeding mating (OCS1) resulted in lower level of inbreeding and similar genetic response than OCS combined with random mating (OCS3). Thus, depending on the implementation, OCS combined with non-random mating allows for increased genetic gain under the same rate of inbreeding (Sonesson and Meuwissen, 2000) or lower level of inbreeding under similar genetic gain (our results), compared to OCS with random mating. It is important to make a distinction between level of inbreeding at a specific time and rate of inbreeding over time. Compared to OCS1, OCS3 presented higher rate of inbreeding in the short-term and similar rate of inbreeding in the long-term. Therefore, avoiding the mating of relatives delayed the inbreeding, but the rate of

inbreeding in future generations were the same, showing that the effect of mating is generally much less important than that of selection on controlling inbreeding and genetic diversity (Meuwissen, 2009).

Accounting for selection and mating decisions simultaneously (MS), and not in two steps as in OCS, allowed for better control of inbreeding in the short-term, under the same response to selection. This result is in agreement with Yoshida et al. (2017), who also observed evidence that MS outperformed OCS in controlling inbreeding in the short-term, for a lowly-inbred Nile tilapia population. This is probably associated with the fact that in the initial generations, when most animals were unrelated, MS was able to identify candidate sires that would result in similar genetic gain and coancestry than OCS, but with a smaller inbreeding of the progeny. This, however, was not the case in the long-term, where MS and OCS presented similar genetic gain and inbreeding. Therefore, after a certain level of coancestry and inbreeding, it seems that MS and OCS would select the same candidates irrespective of considering inbreeding of the progeny in the selection process (MS) or as a second step in the mating strategy (OCS).

Giving more emphasis on controlling coancestry (OCS1 and MS1 vs OCS2 and MS2) resulted in a better control of long-term inbreeding,

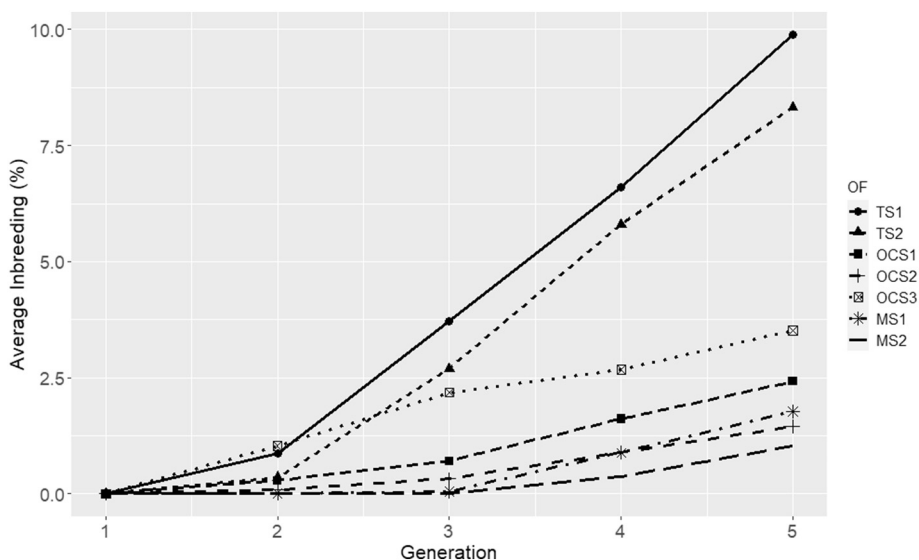


Fig. 5. Average inbreeding level over the first 5 generations of selection considering different objective functions. The scenarios definition is present in Fig. 1.

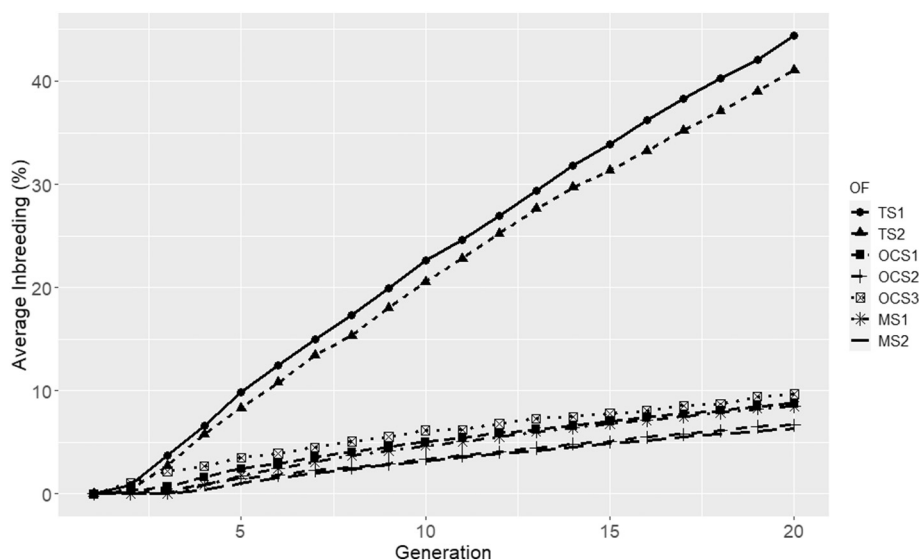


Fig. 6. Average inbreeding level over 20 generations of selection considering different objective functions. The scenarios definition is present in Fig. 1.

with a small reduction in response. Unfortunately, the optimal weights to be used for the different components of the OF cannot be analytically determined in the evolutionary algorithm implemented. They need to be determined empirically as stressed by Yoshida et al. (2017). To overcome this drawback, the authors recommend running the algorithm several times, varying the weights for the different components, explore the potential outcomes, and choose the set of weights resulting in a better balance among the different components, according to the goal of the breeding program. The advantage of using this strategy is that there is no need to determine a prior target value for the rate of inbreeding, which is usually determined empirically in most OCS applications (Woolliams et al., 2015).

A potential advantage of MS over OCS not investigated in the present study is related to its flexibility in incorporating different components to be concomitantly optimized in the objective function, together with genetic gain, coancestry and inbreeding, such as non-additive effects (Hayes et al., 2002; Hayes and Miller, 2000), connectedness among contemporary groups (Carvalho et al., 2010a), and genetic variability of the progeny (Yoshida et al., 2018b), among others (Kinghorn and Shepherd, 1999).

## 5. Conclusions

In the short-term and under similar genetic gain, MS was more efficient in controlling inbreeding than OCS followed by minimum inbreeding mating. However, in the long-term, MS and OCS presented similar results regarding the genetic gain and level and rate of inbreeding.

## Availability of data and material

Only simulated data was used in this study. The datasets and MS program used during the current study are available from the corresponding author upon reasonable request.

## Author's contributions

GM Y performed the simulations, MS analysis and wrote the initial version of the manuscript. JMY and SAQ contributed with study design and discussion. RC developed the MS program, designed the study, supervised work of GM Y and contributed to the analysis, discussion and writing. All authors read and approved the final manuscript.

## Declaration of Competing Interest

The authors declare that they have no competing interests.

## Acknowledgments

GM Y acknowledge Fundação de Amparo à Pesquisa do Estado de São Paulo (FAPESP processes numbers 2014/20626-4 and 2015/25232-7) for Doctoral fellowship. RC acknowledge Conselho Nacional de Desenvolvimento Científico e Tecnológico (CNPq, processes numbers 308636/2014-7 and 305435/2017-5) for fellowship.

## Appendix A. Supplementary data

Supplementary data to this article can be found online at <https://doi.org/10.1016/j.aquaculture.2020.735376>.

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