# Terminal Triangles Centroid Algorithms for Quality Delaunay Triangulation 

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#### Abstract

Two Lepp algorithms for quality Delaunay triangulation are discussed. Firstly a terminal triangles centroid Delaunay algorithm is studied. For each bad quality triangle $t$, the algorithm uses the longest edge propagating path $(\operatorname{Lepp}(\mathrm{t})$ ) to find a couple of Delaunay terminal triangles (with largest angles less than or equal to 120 degrees) sharing a common longest (terminal) edge. Then the centroid of the terminal quadrilateral is Delaunay inserted in the mesh. Insertion of the midpoints of some constrained edges are also performed to assure convergence close to the constrained edges. We prove algorithm termination and that a graded, optimal size, 30 degrees triangulation is obtained, for any planar straight line graph (PSLG) geometry with constrained angles greater than or equal to 30 degrees. We also prove that the size of the final triangulation is optimal and that this size is independent of the processing order of the bad triangles in the mesh. Next, by introducing the concept of non-improvable triangles (with constrained angle $<30$ degrees), we generalize the algorithm to deal with PSLG geometries with N small constrained angles. Thus given a triangle size parameter $\delta$ for non-improvable triangles, the generalized algorithm constructs a quality triangulation with non constrained angles $\geq 30$ degrees and at most N non-improvable triangles of size $\delta$ (longest edge $\leq \delta$ ). In practice the algorithms behave as predicted by the theory.


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## 1. Introduction

Algorithms based on the longest edge bisection of triangles were proposed and studied in [1,2] for adaptive and multigrid finite element methods. Lepp bisection algorithm [3,4] is an efficient reformulation of previous longest edge algorithm for triangulation refinement, that for each target triangle follows the longest edge propagating path (Lepp) to find a couple of terminal triangles sharing a common longest edge (terminal edge), which are then refined by longest edge bisection. Consequently, local refinement operations are used, and conforming triangulations (where adjacent triangles either share a common edge or a common vertex) are maintained throughout the whole refinement process. Due to the properties of the iterative longest edge bisection of triangles, refined triangulations that maintain the triangulation quality (bounded smallest angle) are obtained, while the proportion of quality triangles increases as the refinement proceeds. Based on the properties of terminal triangles and terminal edges it was also proved that optimal size triangulations are obtained [4].

[^0]A Lepp Delaunay algorithm for quality Delaunay triangulation, based on the Delaunay insertion of the midpoint of the terminal edge, was introduced by Rivara [3] and further studied by Bedregal and Rivara [5]. An algorithm based on computing the centroid $Q$ of the terminal triangles which is Delaunay inserted, was presented in [6] without proving termination, neither optimal size property. In this paper we study a tuned, order independent algorithm (where the size of the refined triangulation is almost equal independently of the triangle processing order), based on the Lepp centroid algorithm discussed in [6].

Alternative Delaunay refinement algorithms, based on selecting the circumcenter (or a point close to the circumcenter) of each skinny triangle, which is Delaunay inserted in the triangulation have been studied by Ruppert [7], Shewchuk [8], and by Erten an Üngor [9]. Lepp Delaunay algorithms and circumcenter based algorithms have analogous practical behavior, as shown in the empirical study of Ref. [6], where the Triangle software [8] (without later improvement criteria) was compared with Lepp Delaunay algorithms. It is worth noting however that Lepp based algorithms have the advantage of being order independent, in the sense that they construct triangulations of approximately the same size independently of the processing order of the bad quality triangles. Consequently they are simpler methods than circumcenter based algorithms, easy to implement and easy to parallelize. On the other hand, the implementation
of circumcenter algorithms is rather cumbersome, and requires processing triangles in bad-quality order. Section 6.3 of Ref. [10] discusses several recommendations to implement Ruppert's algorithm efficiently, which include maintaining a queue of skinny and oversized triangles throughout the refinement process.

Lepp algorithms. These are longest edge algorithms formulated in terms of the concepts of terminal edges, terminal triangles and the longest edge propagating path [3-6]. An edge $E$ is a terminal edge in triangulation $\tau$ if $E$ is the longest edge of every triangle that shares $E$. The triangles sharing $E$ are called terminal triangles (edge $A B$ in Fig. 1(a)). If $E$ is shared by two terminal triangles then $E$ is an interior edge; if $E$ is shared by a single terminal triangle then $E$ is a boundary edge.

For any triangle $t_{0}$ in $\tau$, the longest edge propagating path of $t_{0}$, Lepp $\left(t_{0}\right)$, is the ordered sequence of increasing triangles $\left\{t_{j}\right\}_{0}^{N+1}$ such that $t_{j}$ is the neighbor triangle on the longest edge of $t_{j-1}$ and where longest_edge $t_{j}>$ longest_edge $t_{j-1}$, for $j=1, \ldots, N$. The process ends by finding the terminal edge $E$ and a couple of associated terminal triangles $t_{N}, t_{N+1}$. In Fig. 1(a), Lepp $\left(t_{0}\right)=\left\{t_{0}\right.$, $\left.t_{1}, t_{2}, t_{3}\right\}$.

For each target triangle $t$, the generic Lepp based algorithms find an associated local largest edge shared by a couple of terminal triangles. Then a point is selected inside the terminal triangles (terminal edge midpoint or terminal triangles centroid) and inserted in the mesh. In the Lepp bisection algorithm, the midpoint $M$ of the terminal edge is inserted by longest edge bisection of the terminal triangles as shown in Fig. 1(b). The process is repeated until the target triangle $t$ is destroyed. The generic algorithm is as follows:

## Algorithm Generic Lepp-based algorithm

Input : triangulation $\tau$, set $S$ of triangles to be refined/improved Output : Refined triangulation $\tau^{\prime}$

```
    for each \(t\) in \(S\) do
        while \(t\) remains in \(\tau\) do
            Find \(\operatorname{Lepp}(t)\), terminal triangles \(t_{1}, t_{2}\) and terminal edge
        \(E\) ( \(t_{2}\) can be null)
        Select point \(P\) inside terminal triangles, insert \(P\) in the
            mesh and update \(S\)
        end while
    end for
```

In the Lepp centroid Delaunay algorithm of this paper, for each processing bad triangle $t$, if Lepp( $t$ ) finds a couple of non constrained Delaunay terminal triangles, the centroid Q of the quadrilateral formed by the terminal triangles is computed, and Delaunay inserted in the mesh. For constrained edges two additional operations are used. The algorithm is presented in Section 2 together with a sketch of the analysis performed over the most frequent operation, the Delaunay insertion of centroid Q.

This paper discusses a simple algorithm in 2-dimensions for the construction of quality triangulations suitable for complex practical applications such as those related with finite element methods, as well as a set of robust improvement operations that can be easily added to any meshing software to improve meshes. The following summarizes the contributions (new and improved results) of this paper.

- We prove that the algorithm produces $30^{\circ}$ quality triangulations for any planar straight line graph (PSLG) geometry with constrained angles greater than or equal to $30^{\circ}$ by using the improvement properties of the operations OP1, OP2, OP3 described in the next section, and the fact that the average Lepp size tends to be 2 . This is a strong new result with respect to previous algorithms. Note that the proof in Ruppert's algorithm requires constrained angles $\geq 90^{\circ}$, while the modified algorithm of Shewchuk requires constrained angles $\geq 60^{\circ}$.


Fig. 1. (a) $A B$ is a terminal edge shared by terminal triangles $\left\{t_{2}, t_{3}\right\}$ and $\operatorname{Lepp}\left(t_{0}\right)=\left\{t_{0}, t_{1}, t_{2}, t_{3}\right\}$; (b) First step of Lepp-bisection algorithm for refining $t_{0}$.

- The constrained Delaunay triangulation (CDT) of the PSLG data defines an intuitive edge distribution function, which identifies edge details and non-edge details in the PSLG geometry (smallest edges in the CDT). We prove that the algorithm constructs a graded quality triangulation around the geometry details. This also allows us to prove termination and optimal size property. Note that we use the edge distribution function instead of using the local feature size function introduced by Ruppert [7].
- To deal with constrained edges in the PSLG geometry, the algorithm does not require the edge encroachment test used in Ruppert's algorithm, but a simple test based on triangle constrained edges.
- We prove that the size of the output (quality) triangulation is independent of the processing order of the bad triangles in the mesh, which is not the case of circumcircle based algorithms.
- Due to the properties of Delaunay terminal triangles, the bad obtuse triangles with largest angle $>120^{\circ}$ cannot belong to couples of Delaunay terminal triangles, and are eliminated by edge swapping, assuming that an edge swapping Delaunay algorithm is used.
- The average Lepp size is small and tends to be 2 as the refinement proceeds. This result was proved for triangulations obtained by the Lepp bisection algorithm [5] and extends to the algorithms of this paper. This contributes to prove the optimal size property.
- Finally we generalize the tuned algorithm for PSLG geometries with non-improvable angles (constrained angles $<30$ degrees), an extension of the algorithm suitable for applications involving material changes.

This paper is organized as follows. In Section 2 we present the algorithm based on three simple mesh operations, as well as a sketch on the algorithm analysis based on studying the improvement properties of three intermediate mesh operations, not used in the implementation, but required in the analysis. In Section 3 we review results on the iterative longest edge bisection of triangles and on the properties of Lepp algorithms. In Section 4 we state improvement properties on the longest edge bisection of triangles with largest angles $\leq 120^{\circ}$ (the only triangles involved in the mesh operations). In Section 5 we discuss improvement properties of the operations performed over triangles with constrained edges. In Section 6 we present improvement results for the simple centroid insertion over Delaunay terminal triangles. In Section 7 we analyze the algorithm integrating the results of the previous sections. In Section 8 we present empirical results in agreement with the theory. In Section 9 we generalize the algorithm for geometries with constrained angles $<30^{\circ}$.


Fig. 2. Operation OP1 applied over non constrained terminal triangles $\left(t_{1}, t_{2}\right)$ in triangulation TT.


Fig. 3. Intermediate operations used in the analysis of Operation OP1. Operation IO1 performs longest edge bisections; Operation IO2 performs simple centroid insertion.

## 2. The algorithm and sketch of the analysis

The (tuned) Lepp Delaunay centroid algorithm uses the following three simple mesh operations:

OP1 Over a couple ( $t_{1}, t_{2}$ ) of non constrained Delaunay terminal triangles (see Fig. 2 TT ), the centroid Q of the quadrilateral formed by $\left(t_{1}, t_{2}\right)$ is computed and Delaunay inserted in the mesh as shown in Fig. 2 OP1.
OP2 Over a couple of Delaunay terminal triangles where one of the triangles is bad and has a constrained second longest edge $E$, the midpoint of $E$ is selected and constrained Delaunay inserted in the mesh.
OP3 For constrained terminal edge, the longest edge bisection of the terminal triangles (or triangle) is performed.

The operation OP2 was added to the algorithm discussed in Ref. [6], and contributes to prove the stronger results on the algorithm. A preliminary version of this paper was presented in the 27th International Meshing Roundtable [11].

### 2.1. The algorithm for geometries with constrained angles $\geq 30^{\circ}$

Assuming an input constrained Delaunay triangulation (CDT) of a PSLG data with constrained angles $\geq 30^{\circ}$; and angle tolerance $\theta_{\text {tol }} \leq 30^{\circ}$, the algorithm is as follows.
Algorithm Tuned Terminal_Triangles_Centroid_Delaunay _Algorithm
Input: CDT $\tau$ associated with PSLG data, angle tolerance $\theta_{\text {tol }}$ Output: Refined triangulation $\tau_{f}$ with angles $\geq \theta_{\text {tol }}$.

Find $S$ set of bad quality triangles
for each $t$ in $S$ (while $S \neq \varnothing$ ) do

```
while \(t\) remains unrefined do
        Use Lepp \((t)\) to find Delaunay terminal triangles \(t_{1}, t_{2}\) and
        terminal edge \(E\)
        if \(E\) is constrained (this includes \(t_{2}\) null) then
        Perform Constrained Delaunay insertion of midpoint of
        E
    else
        if there exists \(t\) ( \(t_{1}\) or \(t_{2}\) ) such that \(\alpha_{t}<\theta_{\text {tol }}\) and
                second longest edge \(L\) is constrained then
                Perform constrained Delaunay insertion of midpoint
                of \(L\)
        else
            Compute centroid Q of terminal triangles, and per-
            form constrained Delaunay insertion of Q
        end if
    end if
    Update \(S\)
    end while
end for
```


### 2.2. Sketch of the algorithm analysis

In the analysis we assume that the Delaunay insertion of the centroid Q is performed by using an edge swapping Delaunay function as described by de Berg et al. [12] in section 9.3, page 192.

Let us consider the most frequent operation OP1 in the algorithm. Then assume that by processing a bad quality triangle $t$ with smallest angle $\alpha_{0}<30^{\circ}$, the algorithm computes Lepp( t ) finding a couple of non constrained terminal triangle ( $t_{1}, t_{2}$ ) as shown in Fig. 2 TT, where $t_{1}$ is a bad triangle. Then operation OP1 applies and the centroid Q of the quadrilateral formed by the terminal triangles $\left(t_{1}, t_{2}\right)$ is computed and Delaunay inserted in the mesh as shown in Fig. 2 OP1, which improves the involved triangles.

To study the improvement properties of the operation OP1 we need to consider three intermediate operations, not performed by the algorithm, but required in the analysis.

IO1 The longest edge bisection of the triangles $\left(t_{1}, t_{2}\right)$, which introduces midpoint M and produces the triangulation of Fig. 3 IO1.
IO2 the simple insertion of centroid $Q$ obtained by joining $Q$ with the vertices of the quadrilateral AEBC Fig. 3 IO2, which indeed corresponds to the Laplacian smoothing over vertex M in triangulation of Fig. 3 IO1.
IO3 Delaunization of the triangulation obtained by operation IO2 by applying the necessary edge swapping operations to produce a full Delaunay triangulation. This completes the operation OP1.

Important Remark. Each triangle belonging to a couple of Delaunay terminal triangles has largest angle $\leq 120^{\circ}$. This implies that every bad triangle with largest angle $>120^{\circ}$ is eliminated by Delaunay swapping of its longest edge. In this sense, the Delaunay edge swapping operation plays an important role in the algorithm, by performing the implicit elimination of too obtuse bad triangles in the mesh.

The algorithm analysis is roughly as follows. The operation IO1 produces both a triangle better than the terminal triangle and a bad obtuse triangle. The next operation IO2 improves the new triangles, especially the obtuse ones, while the Delaunay operation IO3 further improves the mesh by producing more equilateral triangles and eventually by eliminating (by edge swapping) the too obtuse triangles (with angle $>120^{\circ}$ ).


Fig. 4. (a) Longest-edge bisection of triangle $t(A B C)(b)$ First longest edge bisections that define a quasiequilateral triangle $t(A B C)$.

## 3. Previous results

The iterative longest edge bisection of individual triangles was studied by Rosenberg and Stenger [13] and by Stynes [14,15]. This process produces a finite number of non-similar triangles with bounded smallest angle, while the proportion of good triangles (quasiequilateral triangles) increases as the refinement proceeds. The following definitions are in order.

Definition 1. Given a triangle $t(A B C)$ of vertices $A, B, C$, and edges $A B \geq B C \geq C A$, the longest-edge bisection of $t$ (or simply bisection of $t$ ) is performed by joining the midpoint $M$ of $A B$ with the opposite vertex $C$ (see Fig. 4(a)).

Definition 2. Triangle $t(A B C)$ of edges $A B \geq B C \geq C A$ is quasiequilateral if $A C \geq \max \{A B / 2, C M\}$ and $M C \geq B C / 2$ (see Fig. 4 (b)).

Note that for quasiequilateral triangles (see Fig. 4(b)) after the first median MC is introduced, the next longest edge bisections only produce medians parallel to the edges of the initial triangle $A B C$, which implies that at most, four similarly distinct triangles are produced. Furthermore the following results hold [13-15]:

A1. Given any triangle $t_{0}$ of smallest angle $\alpha_{0}$, the iterative longest edge bisection of $t_{0}$ and its descendants produces a finite set $S\left(t_{0}\right)$ of similarly distinct triangles. Furthermore each triangle $t$ in $\mathrm{S}\left(t_{0}\right)$ has smallest angle $\alpha_{t}$ such that $\alpha_{t} \geq \alpha_{0} / 2$.

A2. For any quasiequilateral triangle $t_{\text {qeq }}$, the triangle set $S\left(t_{q e q}\right)$ has at most, four similarly distinct triangles, all of which are also quasiequilateral.

A3. For any non quasiequilateral triangle $t_{0}$, consider the sequence of triangle sets $Q_{j}$ defined as follows: $Q_{0}=\left\{t_{0}\right\}$, and for $\mathrm{j} \geq 1, Q_{j}$ is obtained by longest edge bisection of the triangles of $Q_{j-1}$. Then the triangle sets $Q_{j}$ improve with $j$ as follows: both the percentage of quasiequilateral triangles and the area of $t_{0}$ covered by these triangles, monotonically increase as the iterative refinement proceeds.

Lepp bisection algorithm. As discussed in Section 1, the Lepp bisection algorithm only performs longest edge bisections of couples of terminal triangles sharing a common longest (terminal) edge.

The triangulations obtained are conforming and inherit properties A1, A2, A3 as follows: the iterative local/global use of the Lepp bisection algorithm (and previous longest edge algorithms) produces sequences of nested, refined and conforming triangulations $\left\{\tau_{j}\right\}$ such that B1, B2 hold:

B1. For any triangle $t_{0}$ in $\tau_{0}$, the refined triangles nested in $t_{0}$ belong to a finite set $S\left(t_{0}\right)$ of similarly distinct triangles, all of which have smallest angle $\alpha \geq \alpha_{0} / 2$, where $\alpha_{0}$ is the smallest angle of $t_{0}$.

B2. The refined triangulations $\left\{\tau_{j}\right\}$ improve with $j$ in the following senses: both the percentage of quasiequilateral triangles, and the area covered by these triangles, increase as the refinement proceeds.

Later Bedregal and Rivara [4] proved that there exists a close relationship between quasiequilateral triangles and terminal triangles (the proportion of terminal triangles increases as quasiequilateral triangles increases), which imply B3. Furthermore, bounds on the number of triangle partitions performed inside a triangle in a Lepp sequence, summarized in assertion B4, were stated by Bedregal and Rivara [4]. Finally assertions B3 and B4 together imply B5.

B3. The proportion of terminal triangles increases (approaching 1) as the refinement proceeds and the average length of Lepp $(t)$ tends to be 2 as the refinement proceeds.

B4. The number of longest edge bisections performed in the interior of a triangle $t$ to make it conforming in a refining Lepp sequence, is constant and less than 3 in most cases. This constant is bounded by $O\left(\log ^{2}(1 / \alpha)\right)$ for triangles with arbitrary smallest angle $\alpha$.

B5. Lepp bisection algorithm produces optimal size triangulations.

Lepp Delaunay algorithms. These allow the construction of quality Delaunay triangulations of planar straight line graph (PSLG) geometries. Starting from the bad quality Delaunay triangulation of the PSLG input data, for each bad quality triangle t , the Lepp( t ) is computed to find a couple of Delaunay terminal triangles over which a point is Delaunay inserted in the mesh. It is worth noting that Delaunay terminal triangles play a crucial role in Lepp Delaunay algorithms which have the properties summarized in the next theorems $[3,16,17]$.

Theorem 1. For any pair of Delaunay terminal triangles $t_{1}, t_{2}$ sharing a terminal edge $A B$ it holds:
(a) Largest angle $\left(t_{i}\right) \leq 2 \pi / 3$ for $i=1,2$
(b) At most one of the triangles $t_{1}, t_{2}$ is obtuse

Proof (Part (a) Sketch). Couples of Delaunay terminal triangles $A B C, A B D$ (see Fig. 5) are neighbor triangles that simultaneously satisfy that $A B$ is the common longest edge of the both triangles, and that triangles $A B C$ and $A B D$ are locally Delaunay, which implies that vertex $D$ is outside the circumcircle of triangle $A B C$. Both conditions together imply that vertex $D$ must belong to the shadowed region $\mathcal{R}$ limited by the circumcircle of triangle $A B C$ and the circles of vertices $A, B$ and radius $A B$. In the case that $\measuredangle A C B=120^{\circ}, \mathcal{R}$ reduces to one point $D^{\prime}$ (triangle $A D^{\prime} B$ is equilateral). Consequently for $\measuredangle A C B$ greater than $120^{\circ}, \mathcal{R}$ is empty and assertion (a) follows.

The Lepp Delaunay algorithms inherit the properties B3 and B5 as stated in the following theorem. For a proof see references [4,5]


Fig. 5. Delaunay terminal triangles $A B C, A B D$; vertex $D$ belongs to region $\Re$.


Fig. 6. Notation for longest edge bisection. Angles in longest edge bisection of triangle $A B C$ with $A B \geq B C \geq A C$.

Theorem 2. For the triangulations obtained by the Lepp Delaunay algorithms the following properties hold:
(a) The proportion of terminal triangles increases (approaching 1) as the refinement proceeds and the average length of Lepp( $t$ ) tends to be 2 as the refinement proceeds.
(b) Lepp Delaunay algorithms produce optimal size triangulations (of size by a constant equal to the size of the smallest quality triangulation)

Remark. Since the algorithms of this paper insert points in the interior of couples of Delaunay terminal triangles, only triangles with largest angle less than or equal to $120^{\circ}$ can become a terminal triangle throughout the algorithm processing. The following definition identifies the triangles that can become a terminal triangle throughout the algorithm processing.

Definition 3. We will say that $t$ is a PD terminal triangle (potentially a Delaunay terminal triangle) if the largestangle( $t$ ) $\leq$ $120^{\circ}$.

Corollary 1. Non-PD terminal triangles are eliminated by swapping its longest edge in a delaunization process.

At this point we need to emphasize the improvement property of the Delaunay edge swapping operation, stated by Sibson [18]. A proof can be found in Ref. [17].

Proposition 1. Given any couple $t_{1}, t_{2}$ of non Delaunay neighbor triangles, then the swapping of the common edge produces a couple of locally Delaunay triangles such that the six new angles are better (by pairs) than the six angles of $t_{1} . t_{2}$.

## 4. Angle bounds on the first bisections of triangles

Here we present revised results with respect to those of references [11]. We center the study on triangles with largest angle $\leq 120^{\circ}$, and follow the notation of references [16,19].

### 4.1. Triangles taxonomy

Let us consider the first longest edge bisection of a triangle $A B C$ where $A B \geq B C \geq A C$, which produces a better triangle $t_{B}$ and an obtuse triangle $t_{O B}$ (see Fig. 6). Considering this notation it is rather easy to prove the following lemma:

## Lemma 1.

(a) if $t$ is a right angled triangle then $\alpha_{1}=\alpha_{0}, \beta_{1}=\beta_{0}$, $A M=C M$
(b) if $t$ is an acute triangle then $\alpha_{1}<\alpha_{0}, \beta_{1}<\beta_{0}, A M<C M$; and
(c) if $t$ is an obtuse triangle then $\alpha_{1}>\alpha_{0}, \beta_{1}>\beta_{0}, A M>C M$.

These properties allow proving the assertions (b), (c), (d) of Lemma 2 [16]. The bound on $\alpha_{1}$ follows from the strong property A1 of Section 3.

Lemma 2. The following angle bounds hold [16].
(a) $\alpha_{1} \geq \alpha_{0} / 2, \alpha_{2} \geq 90^{\circ}, \beta_{2} \leq 90^{\circ}, \beta_{1} \geq \pi / 6, \beta_{1} \geq \alpha_{1}$
(b) $\beta_{2}=\alpha_{0}+\alpha_{1} \geq 3 \alpha_{0} / 2$
(c) if $t$ is obtuse, then $\alpha_{1}>\alpha_{0}$ and $\beta_{2} \geq 2 \alpha_{0}$
(d) if $t$ is acute, then $\alpha_{1}<\alpha_{0}$ and $t_{B}$ is acute

Next we introduce the taxonomy of Fig. 7, which is a variation of those discussed by Simpson and Rivara [16] and by Gutierrez et al. [19]. This is obtained by fixing the longest edge $A B$ of triangle $A B C$ considering $A B \geq B C \geq C A$, and studying which is the longest edge of triangle $A \bar{M} C$ and the longest edge of triangle CMN (see Fig. 6 ) according to the position of vertex $C$, which is situated in the region limited by lines AM, MX and arc AX in Fig. 7.

Note that the half circle of vertex $M$ and radius $A M$ separates obtuse and acute triangles. Arcs $A R$ and $M R$ respectively correspond to isosceles triangles with edges $A M=C M$ and edges $A C=A M$; while arc $Z W$ corresponds to the circle of center $\tilde{N}$ (where $A \tilde{N}=A B / 3$ ) and radius $A \tilde{N}$, corresponding to the triangles for which $C B=2 C M$.

The set of quasiequilateral triangles is the union of region $\mathcal{R}_{1}$ (acute triangles) and region $\mathcal{R}_{2}$ (obtuse triangles). By studying the boundaries of regions $\mathcal{R}_{1}$ and $\mathcal{R}_{2}$ it is easy to see that $\mathcal{R}_{1} \bigcup \mathcal{R}_{2}$ correspond to quasiequilateral triangles and that most of these triangles (vertex $C$ by above line $S W$ ) have the smallest angles $\geq 30^{\circ}$. Only for vertex $C$ in region SZW, the smallest angle $\alpha_{0}$ is lightly $<30^{\circ}$. The worst case corresponds to $C=Z$ where $\left.\operatorname{tg}\left(\alpha_{0}(Z)\right)=\sqrt{7} / 5>27.88^{\circ}\right)$. Note that most of the triangles of $\mathcal{R}_{3}$ also have the smallest angle $\geq 30^{\circ}$.

Finally arc $A W$ corresponds to points $C$ for which the largest angle is equal to $120^{\circ}$, defined by the circle of center $W^{\prime}$ and radius $W W^{\prime}$, where points $W, W^{\prime}$ are symmetric with respect to line $A B$.

These results are summarized in the parts (a), (b), (c) of Lemma 3. Part (d) was proved in $[16,19]$

## Lemma 3.

(a) Consider the taxonomy of Fig. 7. Then for quasiequilateral triangles in region TSWX, $\alpha_{0} \geq 30^{\circ}$;
(b) For quasiequilateral triangles in region SZW, $\alpha_{0}>27.88$.
(c) The non PD terminal triangles (with angle $>120^{\circ}$ ) have vertex $C$ in region AMW.
(d) Any triangle in region $R_{3}$ produces a quasiequilateral triangle $t_{B}$.


Fig. 7. Taxonomy on longest edge bisection of triangles $t(A B C)$ with $A B \geq B C$ $\geq C A$.

### 4.2. Characterization of triangles $t_{B}, t_{O B}$

Here we study the triangles $t_{B}, t_{O B}$ obtained by longest edge bisection of triangle $t$ with angles $\leq 120^{\circ}$. Remember that the angles $\alpha_{0}, \alpha_{1}$ are obtained by longest edge bisection of $t(A B C)$ as shown in Fig. 6. In addition we call $\alpha_{0}\left(t_{B}\right), \alpha_{0}\left(t_{O B}\right)$ to the smallest angles of $t_{B}, t_{O B}$

Lemma 4. Given a triangle $t$, then:
(a) If $t$ is an acute triangle with $\alpha_{0} \leq 30^{\circ}$, then $\alpha_{1} \geq 0.79 \alpha_{0}$, $\beta_{2} \geq 1.79 \alpha_{0}$ and $\alpha_{0}\left(t_{B}\right) \geq 1.79 \alpha_{0}$. Furthermore $\alpha_{0}$ approaches $\alpha_{1}$ as $\alpha_{0}$ decreases.
(b) If $t$ is an obtuse triangle with largest angle $\leq 120^{\circ}$ and smallest angle $\alpha_{0} \leq 30$, then $\beta_{0}>30^{\circ}, \beta_{1}>90^{\circ}-\alpha_{0}>60^{\circ}, \beta_{2}=2 \alpha_{0}$ and $\alpha_{0}\left(t_{B}\right) \geq \operatorname{Min}\left\{30,2 \alpha_{0}\right\}$.
(c) If $\alpha_{0} \geq 30^{\circ}$, then $\alpha_{0}\left(t_{B}\right) \geq 30^{\circ}$ and $t_{B}$ is quasiequilateral.
(d) If $t$ is quasiequilateral with $\alpha_{0} \geq 30^{\circ}$, then $\alpha_{0}\left(t_{B}\right) \geq 30^{\circ}$ and $\alpha_{0}\left(t_{O B}\right)>27.88^{\circ}$.
(e) If $\alpha_{0}>16.8^{\circ}$, then $\alpha_{0}\left(t_{B}\right) \geq 30^{\circ}$.

Proof. The proof of assertion (a) follows by studying the case of the acute triangles of region UAS in Fig. 7, where the worst case corresponds to point $U$ for which $\alpha_{1} \approx 23.79^{\circ}$. For more details see Ref. [16,17]. Assertion (b) follows from Lemma 2. Parts (c), (d), follow from Lemma 3. Assertion (e) follows from part (a) of this lemma.

The following Corollary and Lemma summarizes improvement results for the longest edge bisection of PD-terminal triangles (angles $\leq 120^{\circ}$ ), which are the only triangles involved in the operations OP1, OP2 applied over couples of Delaunay terminal triangles in the algorithm. The non PD terminal triangles correspond to the obtuse triangles of region WAM in Fig. 7, with largest angle $>120^{\circ}$.

Corollary 2. Given a PD-Terminal triangle $t$, then
(a) $t_{B}$ is a PD-terminal triangle
(b) If $\alpha_{0} \leq 30^{\circ}$, the $t_{B}$ is such that $\alpha_{0}\left(t_{B}\right) \geq \operatorname{Min}\left\{30^{\circ}, B \alpha\left(t_{0}\right)\right\}$, where either $B=1.79$ if $t$ is acute, or $B=2$ if $t$ is obtuse
(c) If $t$ is quasi equilateral then $t_{B}, t_{O B}$ are quasiequilateral
(d) For triangles with $\alpha \geq 30^{\circ}$ (vertex $C$ by above edge UB in Fig. 8), $t_{B}$ is quasiequilateral

In Lemma 5 we further characterize $t_{O B}$ triangles associated to PD-terminal triangles.

Lemma 5. Given any PD-terminal triangle $t$, then


Fig. 8. For constrained second longest edge $C B$ of a bad quality terminal triangle, the midpoint $M^{\prime}$ of $C B$ is constrained Delaunay inserted in the mesh instead of M.
(a) If $t$ is acute and $\alpha_{0} \leq 30^{\circ}$, then $t_{O B}$ is a non-PD terminal triangle.
(b) If $t$ is obtuse and $\alpha_{0}>22^{\circ}$, then $t_{O B}$ can be a PD terminal triangle. If $\alpha<22^{\circ}$ the $t_{O B}$ is a non-PD terminal triangle.

Proof. Part (a) follows from the fact that for acute triangles $\alpha_{1}<\alpha_{0}$, which in turn implies that $\beta_{2}=\alpha_{1}+\alpha_{2}<60^{\circ}$ and consequently $t_{O B}$ is a non-PD terminal triangle. Part (b) follows from the fact that for obtuse triangles, $\alpha_{1}>\alpha_{0}$. In [17] it was proved that largest angle equal to $120^{\circ}$ and $\alpha_{1}+\alpha_{0}=60^{\circ}$ implies that $\alpha_{0}>22^{\circ}$. Thus, only for some triangles with $\alpha_{0}>22^{\circ}$ it can hold $\alpha_{1}+\alpha_{0}>60^{\circ}$ and $t_{O B}$ can be a PD terminal triangle.

Remark. The longest edge bisection of a triangle close to the equilateral one, introduces two quasiequilateral triangles $t_{B}$ and $t_{O B}$, such that $\alpha_{0}\left(t_{B}\right) \geq 30^{\circ}$ and where $t_{O B}$ can have a smallest angle $27.88 \leq \alpha_{1} \leq 30^{\circ}$.

## 5. Operations over triangles with constrained edges

### 5.1. Triangles with constrained second longest edge

Here we study the operation OP2. For bad quality terminal triangle $A B C$, where $A B \geq B C \geq A C$ with a constrained second longest edge $C B$, the constrained Delaunay insertion of the midpoint $M^{\prime}$ of CB in Fig. 8 is performed,

For PD terminal triangles the following properties hold:
Theorem 3. Let $t(A B C)$ be any PD terminal triangle (largest angle $\leq 120^{\circ}$ ) with smallest angle $<30^{\circ}$, and second longest edge $C B$ of midpoint $M^{\prime}$ (Fig. 8). Then the bisection of $t$ by the edge CB produces a non-PD terminal triangle $A M^{\prime} B$.

Proof. Firstly consider largest angle $120^{\circ} \leq \gamma \leq 90^{\circ}$. Then $\gamma$ is also the largest angle of triangle $C A M^{\prime}$ which implies that $A M^{\prime}>C M^{\prime}=M^{\prime} B$. This in turn implies that $\delta<\alpha<30^{\circ}$ and $\gamma^{\prime}>120^{\circ}$.

Next consider an isosceles acute triangle with edges $\mathrm{AB}=\mathrm{CB}$ and smallest angle $\alpha$. In this case $\gamma=\left(180^{\circ}-\alpha\right) / 2$ which is also the largest angle of triangle $C A M^{\prime}$ and the result also follows. Finally for any acute triangle with $\alpha<30^{\circ}$, its largest angle $\gamma>(180-\alpha) / 2$ and using a reasoning analogous to the previous ones, the result follows.

Corollary 3. The operation OP2 always performs swapping of the longest edge $A B$ to delaunize the mesh (see Fig. 9 ). This improves the mesh by destroying the bad (non-PD) triangle $A M^{\prime} B$ by Delaunay swapping of edge $A B$.

It is worth noting that the insertion of the midpoint of a constrained second longest edge CB avoids the insertion of points unnecessarily close to the constrained edges. Thus for very long


Fig. 9. Operation OP2 (Delaunay insertion of midpoint M') performs swapping of edge $A B$.
polygons (such as a for long quadrilaterals), the algorithm repeatedly introduces a midpoint of either a terminal edge or of a constrained second longest edge, as shown in Fig. 10.

Note that the previous Lepp Delaunay midpoint algorithm requires an analogous operation to guarantee convergence [3]. The previous Lepp Delaunay centroid algorithm of references [6] does not use this operation, but introduces more points than the tuned algorithm close to constrained edges.

### 5.2. Triangles with constrained smallest angle

The following Lemma assures that for triangle $t$ with $30^{\circ}$ constrained angle the algorithm produces a finite number of quality triangles in the interior of $t$ when triangle $t$ is reached throughout an interior Lepp.

Lemma 6. Let $t$ be any triangle with $30^{\circ}$ constrained angle. Then (a) If $t$ is obtuse, the tuned algorithm produces quality triangles in the interior of $t$; (b) If $t$ is acute the tuned algorithm inserts three points in the constrained edges, as shown in Fig. 11, to produce quality triangles in the interior of $t$, excepting triangle $E P_{3} D$, which is improved using the simple centroid insertion operation inside Delaunay terminal triangle of edge ED, if this is a good triangle.

Proof (a). Note that, according to Lemma 1(a), the longest edge bisection of a $30^{\circ}$ right angled triangle produces a good triangle with $\alpha_{1}=\alpha_{0}=30^{\circ}$ (see Fig. 6). Thus the refinement propagation will introduce one midpoint over the constrained longest edge and eventually one midpoint over the constrained second longest edge (if the propagation arrives by this edge). If $t$ is obtuse then


(a)

(b)

Fig. 11. Acute isosceles triangle with $30^{\circ}$ constrained smallest angle (edges EF, DF are constrained).
according to part (c) of Lemma 1, $\alpha_{1}>\alpha_{0}=30^{\circ}$, and analogously to the right triangle case, the result follows.
(b) Consider the acute isosceles triangle DEF of Fig. 11 with constrained smallest angle $30^{\circ}$ and longest edges $\mathrm{DF}, \mathrm{EF}$ of length equal to 1. If triangle DEF becomes terminal, a vertex $P_{1}$ is constrained Delaunay inserted over constrained longest edge EF (or DF ) producing triangles $D E P_{1}$ and $D P_{1} F$. Note that $\mathrm{DE}=2$ sin $15^{\circ} \approx 0.5176$. Next, using the cosine theorem we find that $D P_{1} \approx$ 0.6196 and (smallest angle) $\angle F D P_{1} \approx 23.79^{\circ}$. Then by processing triangle $D P_{1} F$, the algorithm will perform constrained Delaunay insertion of point $P_{2}$ over constrained longest edge DF, which introduces new bad triangle $D P_{1} P_{2}$ whose processing will find terminal triangles $D P_{1} P_{2}, D E P_{1}$. Since triangle $D P_{1} P_{2}$ has constrained second longest edge $D P_{2}$, the point $P_{3}$ midpoint of $D P_{2}$ will be Delaunay inserted producing the triangles of Fig. 11(b). Using

Fig. 10. For long quadrilateral both the insertion over a constrained second longest edge (operation OP2) and over a constrained longest edge (operation OP3) are repeatedly used.


Fig. 12. Centroid refinement of terminal triangles $A B C, A D B$.
repeatedly the cosine theorem to compute edges and angles we find that triangles $P_{3} E P_{1}$ and $P_{2} P_{3} P_{1}$ are good triangles of smallest angles $46.89^{\circ}$ and 36.7 approximately, while triangle $D E P_{3}$ is a bad triangle with smallest angle $\approx 28.1^{\circ}$, longest edge $D E$ and non constrained second longest edge $E P_{3}$. Consequently this will be improved by using the standard centroid insertion operation where Q will be inside the neighbor Delaunay terminal triangle if this is good.

## 6. Improvement properties of the simple centroid insertion

Here we study the intermediate operation IO2, corresponding to the simple insertion of the centroid Q over a couple of Delaunay terminal triangles as shown in Fig. 12. This is performed by joining $Q$ with the four vertices, instead of performing longest edge bisections. This operation corresponds to a Laplacian smoothing of the terminal edge midpoint $M$ (inserted by longest edge bisection of the terminal triangles) which improves the triangles obtained by longest edge bisection. It is well known that the Laplacian smoothing works well for convex geometries [20,21], and couples of terminal triangles always define a convex quadrilateral. The following theorem states further improvement results for couples of Delaunay terminal triangles.

Theorem 4. Let us consider any couple of Delaunay terminal triangles $\left(t_{1}, t_{2}\right)$ where $t_{1}(A B C)$ is bad and worst than the triangle $t_{2}(A D B)$ as shown in Fig. 13. Then, considering the coordinate system of center $A$ and $x$-axis over edge $A B$, with length of $A B$ equal to 1 , it holds that:
(a) The centroid $Q$ of $\left(t_{1}, t_{2}\right)$ is situated inside the better triangle $t_{2}$ and $y_{Q}<0$. Furthermore $-0.217<y_{Q}<0$
(b) For any triangle $t_{1}$, it holds that $0.25+x_{C} / 4<x_{Q}<$ $0.375+x_{D} / 4<0.625$
(c) If $t_{1}$ is obtuse then $x_{Q}<0.375+x_{I} / 4$, where I is the right intersection point of the circumcircle of $t_{1}(A B C)$ and the arc of circle of center $A$ and radius $A B$, as shown in Fig. 5

Proof. The first part of assertion (a) comes from Theorem 1. The lower bound on $y_{K}$ comes from the case of terminal triangles of angles $\left(30^{\circ}, 30^{\circ}, 120^{\circ}\right)$ and $\left(60^{\circ}, 60^{\circ}, 60^{\circ}\right)$.

Assertion (b) comes from computing $x_{Q}$ using the coordinate system described in the body of this theorem. Thus, $x_{Q}=0.25+$ $\left(x_{C}+x_{D}\right) / 4$. Since triangle $t_{1}$ has largest angle $\leq 120^{\circ}$, then $x_{C}<1 / 2$, and the first part of the upper bound of assertion (b) follows. Since $x_{D}<1$, the 0.625 bound follows. The lower bound is quite direct.

Next we prove assertion (c). If t is obtuse, then $x_{D}<x_{I}$, where I is the right intersection point of the circles of Fig. 5, and assertion (c) follows.


Fig. 13. Delaunay terminal triangles $t_{1}(A B C), t_{2}(B A D)$. Centroid $Q$ is inside rectangle EFGH.


Fig. 14. Operation $O P 1$ over two bad skinny Delaunay terminal triangles with opposite and almost equal smallest angles $\alpha_{0}, \alpha_{0}^{\prime}$.

## Corollary 4.

(a) For $Q$ inside polygon MEFM', the simple insertion of $Q$ (operation IO2) improves the angles $\alpha_{0}, \alpha_{1}$.
(b) For $Q$ inside polygon MM'GH, the simple insertion of $Q$ (operation IO2) improves the angle $\alpha_{0}$.

Note that another improvement case occurs when the Delaunay terminal triangles correspond to two acute bad quality triangles with opposite and almost equal smallest angles as shown in Fig. 14. Here the centroid Q (close to the terminal edge) is inserted by using operation IO2 producing two better acute triangles CAQ and QDB and two very obtuse triangles (largest angle $>120^{\circ}$ ) QAD and CQB , which are eliminated by swapping of their respective longest edges.

## 7. Analysis of the tuned terminal triangles centroid Delaunay algorithm of Section 2.1

Consider a general PSLG (planar straight line graph) geometry, defined by a set of points, edges and eventually polygonal objects defining exterior boundaries and interior holes. Any PSLG geometry has edge details and non-edge details. Edge details are small edges in the PSLG data, while non edge details are defined by two close isolated interior points, an isolated point close to an input edge, two edges with close points, constrained angles either over the boundaries or interior to the geometry, and vertices over these angles. For an illustration see Fig. 15(a).

Note that the constrained Delaunay triangulation (CDT) of the input PSLG data intuitively defines an edge distribution function to which an optimal size good quality triangulation should be adapted. More specifically this identifies edge details and


Fig. 15. (a) PSLG geometry; (b) constrained Delaunay triangulation identifies edge details and non edge details.
non-edge details by means of skinny triangles with associated (constrained or non constrained) small edges, very obtuse triangles with largest angled vertex close to an edge data, and triangles with constrained smallest angle. Fig. 15(b) shows the constrained Delaunay triangulation of the example of Fig. 15(a). We will prove that the algorithm of Section 2.1 produces a graded quality mesh with smaller good quality triangles around the PSLG geometry details.

Theorem 5. Consider any PSLG geometry with constrained angles $\geq 30^{\circ}$ and the input constrained Delaunay triangulation $\tau_{0}$ associated with the PSLG data. Then for angle tolerance $\theta_{\text {tol }}=30^{\circ}$,
(a) The algorithm finishes with a graded $30^{\circ}$ constrained Delaunay triangulation.
(b) The final triangulation is size optimal.

Proof. Given $\theta_{\text {tol }}=30^{\circ}$, consider the bad triangles with angles less than $30^{\circ}$. To prove part (a), we will study five cases of triangle processing:
Case 1. Non PD terminal triangles. Each bad quality triangle $t$ (with largest angle $>120^{\circ}$ either with one or two bad angles) is a non PD terminal triangle which cannot become Delaunay terminal. Then according to Corollary 1, this is eliminated by swapping its longest edge, either by processing $t$ or by processing a Lepp-neighbor bad quality triangle. This operation produces locally more equilateral triangles.
Case 2. Operation OP1 over bad PD terminal triangles. Consider a couple of non constrained Delaunay terminal triangles. Let $t(A B C)$ with $A B \geq B C \geq A C$ be the worst triangle in the couple with $\alpha_{0}<30^{\circ}$. Here we will consider the three intermediate operations IO1, IO2, IO3 to perform the operation OP1.

According to part(b) of Corollary 2, the longest edge bisection of $t$ would introduce the midpoint $M$ of $A B$, a better triangle $t_{B}(A C M)$ with $\alpha_{0}\left(t_{B}\right) \geq 1.79 \alpha_{0}$, and a bad obtuse triangle $t_{O B}$. Next, the simple centroid insertion of $Q$ (operation IO2) corresponds to the Laplacian smoothing of point $M$, which according to Theorem 4 and Corollary 4, improves the worst angles of $t_{O B}$ (introduced by the longest edge bisection) and avoids the repetition of a triangle similar to triangle $A B C$.

Finally the operation IO3 is performed, which delaunize the current triangulation. If triangle $C Q B$ is a non PD terminal triangle, then triangle CQB is eliminated (and improved) by swapping edge $C B$, either when $Q$ is Delaunay inserted (if there exists a vertex inside the (big) circumcircle of triangle $C Q B$ ), or by later processing $C B Q$, or by processing a bad quality neighbor triangle. If triangle $C Q B$ is a PD terminal triangle and still bad, then by processing triangle $C Q B$ this can become a terminal triangle and


Fig. 16. Triangle $A B C$ with $\alpha_{0}<30^{\circ}$. Better triangle $A C Q$ and $C Q B$ are obtained with respect to those obtained by longest edge bisection.


Fig. 17. Points $Q_{i}$ are introduced until triangle $C A Q_{n}$ is good.
the centroid $\tilde{Q}$ of $C Q B$ and its neighbor triangle is inserted, which improves the angles (see Fig. 16).
Repetitive use of operation OP1. According to part (e) of Lemma 4, for $\alpha_{0}<16.8^{\circ}$, triangle CAQ can still be bad. Then for small $\alpha_{0}$, a finite sequence of points $Q_{i}$ need to be inserted in the mesh until a good triangle $C A Q_{n}$ is obtained (see Fig. 17). The process finishes without refining edge $A C$ ( $A C$ is a local smallest edge), unless a close smaller edge induces neighbor refinement. See the termination analysis for more details.
Case 3. Terminal triangles with constrained edges. For Delaunay terminal triangles with the constrained terminal edge, the constrained Delaunay insertion of the terminal edge midpoint is performed and the improvement process continues. For bad triangles with constrained second edge $E$, the simple constrained Delaunay insertion of the midpoint of $E$ is performed, which according to Corollary 3 improves the triangles close to constrained edges in the PSLG geometry.
Case 4. Couples of good Delaunay terminal triangles. For couples of good quality Delaunay terminal triangles with smallest angles $\geq 30^{\circ}$, the centroid $Q$ of the terminal quadrilateral is inserted, which produces four quasiequilateral triangles better than those obtained by longest edge bisection. This is equivalent to a Laplacian smoothing of the terminal edge midpoint introduced by the longest edge bisection of the terminal triangles. This operation improves eventual angles lightly less than $30^{\circ}$ that could have been introduced by the longest edge bisection.
Case 5. Triangles with $30^{\circ}$ constrained angles. Here, according to Lemma 6, good quality triangles are obtained inside $t$ by inserting a small number of points over the constrained edges.
Termination. The proof on termination is based on the fact that for skinny triangles and according to part (b) of Corollary 2, a sequence of $Q_{i}$ points are added to the mesh such that the new smallest angles increase at least by a factor of (1.79) ${ }^{i}$ until a good triangle is obtained. Thus the algorithm stops when every triangle of local smallest edge in $\tau_{0}$ becomes good (smallest angle $\geq 30^{\circ}$ ), and every remaining intermediate bad quality triangle $t$ is processed or eliminated by edge swapping; and every intermediate almost good terminal triangle is improved by centroid insertion. This produces a good quality triangulation graded around the PSLG geometry details. Note that the smallest edge $A C$ is never refined, unless there exists a smaller bad quality triangle $t^{*}$ such that Lepp $\left(t^{*}\right)$ contains triangle $A Q_{n} C$ (see Fig. 18).
Optimal size property. This follows from the termination reasoning together with the fact that the average Lepp size tends to be 2 as the refinement proceeds (part a) of Theorem 2).

Table 1
Algorithms comparison, Key test case, $\theta_{\text {tol }}=33^{\circ}$.

| Triangle processing | Del centroid algorithm |  | Ruppert's algorithm [8] |  |
| :--- | :--- | :--- | :--- | :---: |
|  | Without order | Without order | Ordering triangles |  |
| Final Mesh size | 229 | 450 | 249 |  |

Table 2
Mesh sizes for Delaunay centroid algorithm as a function of $\theta_{\text {tol }}$.

|  | Superior <br> lake | Neuss <br> geometry | Square | Chesapeake <br> bay | Long <br> rectangle | Key <br> geometry |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | size $\left(\tau_{0}\right)$ | $\operatorname{size}\left(\tau_{0}\right)$ | $\operatorname{size}\left(\tau_{0}\right)$ | $\operatorname{size}\left(\tau_{0}\right)$ | $\operatorname{size}\left(\tau_{0}\right)$ | $\operatorname{size}\left(\tau_{0}\right)$ |
|  | 528 | 3070 | 9 | 14,262 | 2 | 54 |
| $\theta_{\text {tol }}$ | $\operatorname{size}\left(\tau_{0}\right)$ | $\operatorname{size}\left(\tau_{0}\right)$ | $\operatorname{size}\left(\tau_{0}\right)$ | $\operatorname{size}\left(\tau_{0}\right)$ | $\operatorname{size}\left(\tau_{0}\right)$ | $\operatorname{size}\left(\tau_{0}\right)$ |
| 30 | 1835 | 8338 | 54 | 36,803 | 19 | 170 |
| 33 | 2273 | 9939 | 65 | 45,883 | 22 | 229 |
| 34 | 2512 | 11,054 | 70 | 52,027 | 25 | 262 |
| 35 | 3017 | 12,742 | 81 | 63,138 | 27 | 349 |

Table 3
Percentage of triangles added with respect to current version of Triangle ${ }^{\text {d }}$.

| $\theta_{\text {tol }}$ | Lake <br> superior | Neuss <br> geometry | Square | Chesapeake <br> Bay | Long <br> rectangle | Key <br> geometry |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 30 | 0.44 | 13.18 | 24.07 | 4.82 | -15.79 | 22.94 |
| 33 | -528 | 1201 | 16.92 | 2.41 | 0.00 | 10.92 |
| 34 | -5.29 | -2.70 | 20.00 | 3.61 | -68.00 | -8.78 |
| 35 | $-\infty$ | $-\infty$ | 24.69 | $-\infty$ | -207.41 | 5.44 |

${ }^{\mathrm{a}}$ Triangle processes skinny and oversized triangles in order and uses a boundary preprocess step.


Fig. 18. Neighbor triangle $t^{*}(A C F)$ induces refinement of triangle $A Q_{n} C$ to obtain a graded refined triangulation around edge $F A$.

Theorem 6. The algorithm is order independent, in the sense that the mesh size is approximately the same by processing the bad triangles in arbitrary order.

Proof. It is easy to see that the set of terminal edges in the triangulation induces a mesh partition so that every triangle in the partition reaches the same terminal edge. Thus the processing of several bad quality triangles in each partition (independently of their quality) find the same couple of terminal triangles.

## 8. Empirical study for geometries with constrained angles $\geq$ $30^{\circ}$

In Table 1 we compare our algorithm with results reported by Shewchuk [8] on Ruppert's algorithm (without the off-center preprocess of Üngor). Next we present results on the behavior of the Delaunay centroid algorithm for the six geometries of Fig. 19. Table 2 includes final mesh sizes for $\theta_{\text {tol }}=30^{\circ}, 33^{\circ}, 34^{\circ}, 35^{\circ}$ obtained with our algorithm. See the final triangulations for $\theta_{\text {tol }}=$ $30^{\circ}$ for these examples in Fig. 19. Table 3 compares the number of triangles obtained with our software, with respect to those obtained with the current version of Triangle [22] which processes skinny and oversized triangles in order, and includes a boundary preprocess technique due to Üngor [9] to minimize the size of the final triangulation. A negative number means our
software introduces less triangles than Triangle, while the $-\infty$ symbol means that Triangle does not converge.

It should be noted that: (i) our results are not far from those obtained by the current optimized version of Triangle; (ii) our software works properly until $\theta_{\text {tol }}=35^{\circ}$ for all the test cases, while Triangle fails for $50 \%$ of the test cases ( $-\infty$ symbol) for $\theta_{\text {tol }}=35^{\circ}$; iii) Note that for the key test case and $\theta_{\text {tol }}=$ $33^{\circ}$, our algorithm produces a final triangulation with 229 triangles against 450 triangles obtained with pure Ruppert algorithm (first-come first split bad quality triangle) and 249 triangles by always processing the worst existing triangle, as reported by Shewchuk [8].

Furthermore, for all the test cases, the average Lepp size is less than 3 from the beginning and quickly becomes less than 2.5 , as the refinement proceeds. The algorithm is an easy to implement, order independent, robust method, suitable for use in adaptive finite element methods where good quality meshes are needed to assure convergence. With an adequate triangle data structure that keeps information on neighbor triangles, the refinement is of cost $O(N)$ where $N$ is the number of points inserted.

## 9. Algorithm for PSLG geometries with constrained angles < $30^{\circ}$

In this section we consider a PSLG geometry with N constrained angles $<30^{\circ}$, which implies that the associated CDT will have N non-improvable triangles with constrained angle < $30^{\circ}$. However if we introduce and edge size parameter $\delta$, each non-improvable triangle $t$ can be refined until obtaining a nonimprovable triangle of size $\delta$ (longest edge $<\delta$ ) and a set of quality triangles in the interior of t . The algorithm is as follows:
Algorithm Algorithm_For_Geometries_With_Small_Constrained _Angles
Input: CDT $\tau$ associated with PSLG data, angles tolerance $\theta_{\text {tol }}$, and finite number N of constrained angles $<30^{\circ}$
Output: Refined triangulation $\tau_{f}$ with non constrained angles $\geq$ $\theta_{\text {tol }}$, and $\mathrm{N} \delta$-size small constrained triangles.


Fig. 19. Quality meshes for $\theta_{\text {tol }}=30^{\circ}$ (a) lake Superior shape; (b) Neuss shape; (c) Square with skinny triangles; (d) Chesapeake B bay shape; (e) Long rectangle; (f) Key shape.

Find $S$ set of bad quality triangles and set $\tilde{S}$ of non-improvable triangles (constrained angle $<\theta_{\text {tol }}$ )
Initialize $W$ set of processing triangles with set $S$ and triangles of $\tilde{S}$ with longest edge $>\delta$
for each $t$ in $W$ (while $W \neq \varnothing$ ) do
while $t$ remains unrefined do
Use Lepp $(t)$ to find Delaunay terminal triangles $t_{1}, t_{2}$ and terminal edge $E$
if $E$ is constrained (this includes $t_{2}$ null) then
Perform Constrained Delaunay insertion of midpoint of E
else
if there exists $t$ ( $t_{1}$ or $t_{2}$ ) such that $\alpha_{t}<\theta_{\text {tol }}$ and second longest edge $L$ is constrained then
Perform constrained Delaunay insertion of midpoint of $L$
else
Compute centroid Q of terminal triangles, and perform constrained Delaunay insertion of Q
end if
end if
Update $S, \tilde{S}$
Update W eliminating refined triangles and adding new triangles with non constrained angle $<\theta_{\text {tol }}$; and adding new non-improvable triangles with longest edge $>\delta$ end while
end for

Theorem 7. Given a parameter $\delta$, for each non-improvable triangle $t$, the algorithm produces a smaller non-improvable triangle of longest edge $<\delta$, and a set of quality triangles in the interior of $t$.

Proof. The algorithm works until inserting points P, Q to obtain a triangle of size $\delta$, (see Fig. 20) by processing triangles in the quadrilateral CAQP by using the edge constrained operations.


Fig. 20. For small angle $A B C$ with constrained edges $A B, C B$, the algorithm finishes with a triangle PQB of size $\delta$ and quality triangles in region AQPC.

The use of the algorithm for interior small constrained angles is illustrated in Figs. 21, 22, 23, for sets of (shadowed) small constrained angles.

## 10. Conclusions

We have discussed a simple, easy to implement and robust Lepp algorithm for the construction of quality Delaunay triangulations. This uses three simple mesh operations over couples of Delaunay triangles sharing a common longest (terminal) edge. These are Delaunay insertion of either the centroid Q, or the midpoint of a constrained second edge, and longest edge bisection of the triangles when the terminal edge is constrained.

For any input PSLG geometry with constrained angles $\geq 30^{\circ}$, the algorithm produces an optimal size triangulation (of size by a factor equal to the smallest possible one) with angles $\geq 30^{\circ}$, and where the mesh size is independent of the triangle processing order. The last property makes the algorithm very appropriate for parallel implementation.

We also discussed an algorithm for geometries including constrained angles $<30^{\circ}$. Obviously these angles cannot be improved, but are isolated when refinement around them is needed. This is important for geometries with complex material changes such a those required for semiconductor applications.


Fig. 21. Rectangle with interior (small) shadowed constrained angles of $10^{\circ}, 15^{\circ}, 20^{\circ}$. (a) Initial constrained Delaunay triangulation. Triangulations (b), (c) correspond to different $\delta$ values.


Fig. 22. Rectangle with interior (small) shadowed constrained angles of $7^{\circ}, 12^{\circ}, 9^{\circ}, 6^{\circ}, 9^{\circ}, 8^{\circ}$. (a) Initial constrained Delaunay triangulation. Triangulations (b), (c) correspond to different $\delta$ values.

It is worth noting that we have been able to develop algorithms that produce almost Delaunay triangulations, without using explicit Delaunay point insertion operations, but simpler
mesh operations based on those described in this paper. We have developed research in this direction, which will be published elsewhere.


Fig. 23. (a) Initial triangulation with 32 constrained angles of $11.25^{\circ}$ sharing the same vertex. Triangulations (b), (c), (d) correspond to different $\delta$ values.

Finally, these ideas can be generalized to 3-dimensions. In a recent paper by Balboa, Rodriguez and Rivara [23], an improvement method for tetrahedral meshes was proposed. This uses a simple centroid insertion operation that generalizes the IO2 operation of this paper, combined with a 'swapping of a terminal edge' operation, a mesh improvement operation that follows the ideas of Freitag and Oliver Gooch [24] but applied to the 3-dimensional terminal edge context.

## Declaration of competing interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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