

# Contents

<b>CHAPTER 1 INTRODUCTION .....</b>	<b>1</b>
1.1 SPATIAL DECISION SUPPORT SYSTEMS .....	2
1.2 PROBLEM TO ADDRESS .....	4
1.3 RESEARCH OBJECTIVES .....	5
1.4 STRUCTURE OF THE THESIS DOCUMENT .....	6
<b>CHAPTER 2 RELATED DOMAINS REVIEW .....</b>	<b>8</b>
2.1 SPATIAL OBJECT REPRESENTATION.....	8
2.2 SPATIAL DECISION SUPPORT SYSTEMS .....	10
2.2.1 <i>Decision-making models</i> .....	10
2.2.2 <i>Spatial decision support systems</i> .....	12
2.3 THE DESIGN PROBLEM OF SDSS .....	14
<b>CHAPTER 3 GEOGRAPHICAL DATA REPRESENTATION.....</b>	<b>16</b>
3.1 GIS DATABASES.....	16
3.1.1 <i>Vector data model</i> .....	17
3.1.2 <i>Raster data model</i> .....	18
3.1.3 <i>Comparison between vector and raster data models</i> .....	19
3.1.4 <i>Coordinate systems and Open Geospatial standards</i> .....	19
3.2 GEOGRAPHICAL DATABASES OPERATIONS.....	20
3.3 SIMPLE FEATURE ACCESS .....	22
3.4 SPATIAL INDEXING .....	24
3.5 DISCUSSION .....	26
<b>CHAPTER 4 DEMPSTER-SHAFER THEORY AND BELIEF FUNCTIONS ....</b>	<b>27</b>
4.1 FORMAL DESCRIPTION .....	29
4.2 BELIEF FUNCTIONS AND COMBINATION RULES .....	30
4.3 DISCOUNT AND COMBINE METHOD .....	31
4.4 YAGER MODIFIED DEMPSTER RULE .....	32
<b>CHAPTER 5 ADAPTING DEMPSTER-SHAFER THEORY TO SPATIAL CONTEXTS      33</b>	
5.1 MASS IN SPACE .....	35
5.2 MASS FUNCTION BY INTERVAL .....	37

5.3	MASS FUNCTION ALONG TIME .....	38
5.4	BELIEF AND PLAUSIBILITY DEFINITION BY SPACE, INTERVAL, AND TIME.....	41
5.5	DISCUSSION .....	42
<b>CHAPTER 6 SDSS SCENARIO GENERATION MODEL .....</b>		<b>44</b>
6.1	SUITABLE OBJECTS .....	44
6.2	DATA OBJECTS.....	44
6.3	GEOOBJECT .....	45
6.4	GEOOBJECTS MAP AND SUITABILITY MAP GENERATION .....	46
6.5	THE ALGORITHM.....	47
6.6	EVALUATION EXAMPLE .....	49
6.7	DISCUSSION .....	52
<b>CHAPTER 7 SCENARIO GENERATION LANGUAGE.....</b>		<b>53</b>
7.1	GRAMMAR .....	55
7.2	ANALYSIS DEFINITION .....	55
7.2.1	<i>Hypothesis definitions</i> .....	55
7.2.2	<i>Model constraints</i> .....	56
7.2.3	<i>Saving</i> .....	57
7.2.4	<i>Operator syntax</i> .....	57
7.3	SGL EXAMPLES .....	58
7.3.1	<i>Example 1: People possible concentration points</i> .....	58
7.3.2	<i>Example 2: Burglary risk</i> .....	59
7.3.3	<i>Example 3: Burglary risk in a street</i> .....	59
7.3.4	<i>Example 4: Path evaluation and saving</i> .....	59
7.4	DISCUSSION .....	60
<b>CHAPTER 8 URBAN CRIME PREDICTION AND POLICE PATROLLING OPTIMIZATION .....</b>		<b>61</b>
8.1	DEMPSTER-SHAFER RISK TERRAIN MODELING .....	63
8.2	FORECASTING EXPERIMENTS .....	68
8.2.1	<i>Medium scale scenario</i> .....	68
8.2.2	<i>Medium scale scenario</i> .....	69
8.2.3	<i>Large scale scenario</i> .....	71
8.3	DISCUSSION .....	74

<b>CHAPTER 9 TRANSPORTATION NETWORK PLANNING EXAMPLE.....</b>	<b>75</b>
9.1    TRANSPORTATION MODELING .....	76
9.2    DETERMINING AN OD ROUTE .....	77
9.3    BELIEF ROUTES IN REAL WORLD .....	80
9.4    AN APPLICATION FOR DEVELOPING BELIEF ROUTES .....	86
9.4.1    Discussion .....	87
<b>CHAPTER 10    MULTIPLE STAKEHOLDERS, SCENARIO COMPARISON AND COMBINATION.....</b>	<b>89</b>
10.1    MERGE AND COMPARE OPERATORS.....	91
10.1.1    Sum operator.....	92
10.1.2    Average operator .....	92
10.1.3    Subtraction operator.....	93
10.2    ORDERED WEIGHT AVERAGE (OWA) OPERATOR.....	93
10.2.1    OWA-DESC.....	93
10.2.2    OWA-ASC .....	94
10.2.3    Weighted OWA operator.....	94
10.2.4    Induced OWA operator .....	95
10.3    OPERATORS APPLIED TO THE TRANSPORTATION NETWORK PROBLEM.....	95
10.4    TOOL DESIGN .....	95
10.5    DISCUSSION.....	101
<b>CHAPTER 11    CONCLUSIONS AND FUTURE WORK.....</b>	<b>103</b>
11.1    SUMMARY AND CONCLUSIONS OF THE CONDUCTED RESEARCH .....	103
11.2    FUTURE WORK.....	107
11.2.1    Automatic SGL statements generation from recurrent characteristics or patterns.....	107
11.2.2    Non-spatial belief relationships.....	107
11.2.3    Integration with RDF and GEO-RDF.....	107
<b>BIBLIOGRAPHY .....</b>	<b>109</b>
<b>APPENDIX A .....</b>	<b>120</b>